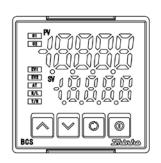
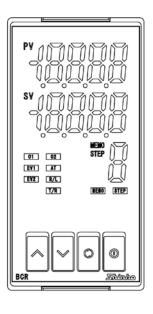
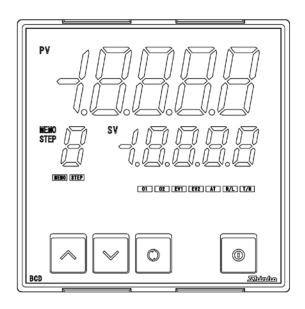
BCx2 INSTRUCTION MANUAL







Shinko

Preface

Thank you for purchasing our digital indicating controller BCx2 (BCS2, BCR2, BCD2). This manual contains instructions for the mounting, functions, operations and notes when operating the BCx2. To prevent accidents arising from the misuse of this controller, please ensure the operator receives this manual.

Abbreviations used in this manual

Abbreviation	Term
PV	Process variable
SV	Desired value
MV	Manipulated variable
DV	Deviation
OUT1	Control output OUT1
OUT2	Control output OUT2
AT	Auto-tuning

Characters used in this manual

Indication	7		1	Ų	m	¥	5	5	7	8	9	Ţ	F
Number, °C/°F	-1	0	1	2	3	4	5	6	7	8	9	$^{\circ}$	°F
Indication	R	Ь	C	ď	Ε	F	E.	Н	}	Ţ	Ŀ	Ļ)(
Alphabet	Α	В	С	D	Е	F	G	Н	I	J	K	L	М
Indication	\cap	0	P	9	_	7	;~	Ц	R	Ü	ì	7) 1 (
Alphabet	Ν	0	Р	Q	R	S	Т	U	V	W	Χ	Υ	Z

Notes

- This instrument should be used in accordance with the specifications described in the manual. If it is not used according to the specifications, it may malfunction or cause a fire.
- Be sure to follow the warnings, cautions and notices. If they are not observed, serious injury or malfunction may occur.
- The contents of this instruction manual are subject to change without notice.
- Care has been taken to ensure that the contents of this instruction manual are correct, but if there are any doubts, mistakes or questions, please inform our sales department.
- Measures must be taken to ensure that the operator cannot touch power terminals or other high voltage sections.
- Any unauthorized transfer or copying of this document, in part or in whole, is prohibited.
- Shinko Technos Co., Ltd. is not liable for any damage or secondary damage(s) incurred as a result of using this product, including any indirect damage.

Safety Precautions (Be sure to read these precautions before using our products.)

The safety precautions are classified into categories: "Warning" and "Caution". Depending on circumstances, procedures indicated by \triangle Caution may result in serious consequences, so be sure to follow the directions for usage.



Procedures which may lead to dangerous conditions and cause death or serious injury, if not carried out properly.



Procedures which may lead to dangerous conditions and cause superficial to medium injury or physical damage or may degrade or damage the product, if not carried out properly.



- To prevent an electrical shock or fire, only Shinko or other qualified service personnel may handle the inner assembly.
- To prevent an electrical shock, fire or damage to the instrument, parts replacement may only be undertaken by Shinko or other qualified service personnel.



- To ensure safe and correct use, thoroughly read and understand this manual before using this instrument.
- This instrument is intended to be used for industrial machinery, machine tools and measuring equipment. Verify correct usage after purpose-of-use consultation with our agency or main office. (Never use this instrument for medical purposes with which human lives are involved.)
- External protection devices such as protective equipment against excessive temperature rise, etc. must be installed, as malfunction of this product could result in serious damage to the system or injury to personnel. Proper periodic maintenance is also required.
- This instrument must be used under the conditions and environment described in this manual. Shinko Technos
 Co., Ltd. does not accept liability for any injury, loss of life or damage occurring due to the instrument being used
 under conditions not otherwise stated in this manual.

Caution with respect to Export Trade Control Ordinance

To avoid this instrument from being used as a component in, or as being utilized in the manufacture of weapons of mass destruction (i.e. military applications, military equipment, etc.), please investigate the end users and the final use of this instrument. In the case of resale, ensure that this instrument is not illegally exported.

1. Installation Precautions

⚠ Caution

This instrument is intended to be used under the following environmental conditions (IEC61010-1): Overvoltage category I, Pollution degree 2

Ensure the mounting location corresponds to the following conditions:

- A minimum of dust, and an absence of corrosive gases
- No flammable, explosive gases
- · No mechanical vibrations or shocks
- No exposure to direct sunlight, an ambient temperature of -10 to 55[°]C (14 to 131°F) that does not change rapidly, and no icing
- An ambient non-condensing humidity of 35 to 85%RH
- No large capacity electromagnetic switches or cables through which large current is flowing
- No water, oil or chemicals or where the vapors of these substances can come into direct contact with the unit
- Take note that the ambient temperature of this unit not the ambient temperature of the control panel must not exceed 55°C (131°F) if mounted through the face of a control panel, otherwise the life of electronic components (especially electrolytic capacitors) may be shortened.

Note • Avoid setting this instrument directly on or near flammable material even though the case of this instrument is made of flame-resistant resin.

2. Wiring Precautions

\bigwedge

Caution

- Do not leave wire remnants in the instrument, as they could cause a fire or malfunction.
- Use the solderless terminal with an insulation sleeve in which the M3 screw fits when wiring the instrument.
- The terminal block of this instrument is designed to be wired from the left side. The lead wire must be inserted from the left side of the terminal, and fastened with the terminal screw.
- Tighten the terminal screw using the specified torque. If excessive force is applied to the screw when tightening, the terminal screw or case may be damaged.
- Do not pull or bend the lead wire on the terminal side when wiring or after wiring, as it could cause malfunction.
- When using a terminal cover for the BCS2, pass terminal wires numbered 7 to 12 into the holes of the terminal cover.
- This instrument does not have a built-in power switch, circuit breaker and fuse. It is necessary to install a-power switch, circuit breaker and fuse near the controller. (Recommended fuse: Time-lag fuse, rated voltage 250 V AC, rated current 2 A)
- For a 24 V AC/DC power source, do not confuse polarity when using direct current (DC).
- Do not apply a commercial power source to the sensor which is connected to the input terminal nor allow the power source to come into contact with the sensor.
- Use a thermocouple and compensating lead wire according to the sensor input specifications of this controller
- Use the 3-wire RTD according to the sensor input specifications of this controller.
- For DC voltage input, (+) side input terminal number of 0 to 5 V DC, 1 to 5 V DC, 0 to 10 V DC differs from that of 0 to 1 V DC.

Model	Terminal Number
BCS2	9: (+) side of 0 to 5 V DC, 1 to 5 V DC, 0 to 10 V DC
	①: (+) side of 0 to 1 V DC
BCR2, BCD2	②: (+) side of 0 to 5 V DC, 1 to 5 V DC, 0 to 10 V DC
	②: (+) side of 0 to 1 V DC

- When using a relay contact output type, externally use a relay according to the capacity of the load to protect the built-in relay contact.
- When wiring, keep input wires (thermocouple, RTD, etc.) away from controller AC power sources or load wires.

3. Operation and Maintenance Precautions



Caution

- It is recommended that AT be performed on the trial run.
- Do not touch live terminals. This may cause electrical shock or problems in operation.
- Turn the power supply to the instrument OFF when retightening the terminal or cleaning.
 Working on or touching the terminal with the power switched ON may result in severe injury or death due to electrical shock.
- Use a soft, dry cloth when cleaning the instrument.

 (Alcohol based substances may tarnish or deface the unit.)
- As the display section is vulnerable, do not strike or scratch it with a hard object or put pressure on it.

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1. Model

1.1 Model

	B C□2										
	BCS2						48 x 48 x 68	mm (W x H x D) (Depth of control panel interior: 60)			
Size	BCR2						48 x 96 x 68	mm (W x H x D) (Depth of control panel interior: 60)			
	BCD2						96 x 96 x 68	96 x 96 x 68 mm (W x H x D) (Depth of control panel interior: 60)			
Control		R					Relay contac	tt: 1a			
Control OUT1	output	S					Non-contact	voltage (for SSR drive) 12 V DC±15%			
0011		Α					Direct curren	t: 4 to 20 mA DC			
Power s	supply		0				100 to 240 V	AC (Standard)			
voltage			1				24 V AC/DC	24 V AC/DC			
Input				0			Multi-range (*1)			
					0			No Option 1 needed.			
					1		EV2	Event output EV2 (*3)			
					2		DS	Heating/Cooling control output OUT2, Non-contact voltage			
					3		DA	Heating/Cooling control output OUT2, Direct current			
Onting	1 (*0)				4		P24	Insulated power output			
Option (Change			ا مما		5		EV2+DR(*4)	Event output EV2 (*3) + Heating/Cooling control			
(Choose	e only one	e opi	ion.)					output OUT2, Relay contact			
					6		EV2+DS(*4)	Event output EV2 (*3) + Heating/Cooling control			
								output OUT2, Non-contact voltage			
					7		EV2+DA(*4)	Event output EV2 (*3) + Heating/Cooling control			
								output OUT2, Direct current			
						0		No Option 2 needed.			
						1	C5W (20A)	Event input (2 points) (*5) + Serial communication +			
								Heater burnout alarm (20A) (*6)			
						2	C5W (100A)	Event input (2 points) (*5) + Serial communication +			
								Heater burnout alarm (100A) (*6)			
						3	EIW (20A)	Event input (2 points) +			
	2 41-1							Heater burnout alarm (20A) (*6)			
Option 2						4	EIW (100A)	Event input (2 points) +			
(Choose	e only one	e opt	ion.)					Heater burnout alarm (100A) (*6)			
			5	EIT	Event input (2 points) (*7)+						
							External setting input + Transmission output				
					6	C5	Serial communication				
					7	W (20A) Heater burnout alarm (20 A) (*6)					
					8	W (100A) Heater burnout alarm (100 A) (*6)					
						9	El Event input (2 points)				

- (*1) Thermocouple, RTD, Direct current and DC voltage can be selected by keypad.
- (*2) Only one option can be selected from Option 1 and Option 2 respectively.
- (*3) Event output EV1 is standard.

The following outputs can be selected in [Event output EV1/EV2 allocation] by keypad:

Alarm output (12 alarm types and No alarm action), Heater burnout alarm output, Loop break alarm output, Time signal output, Output during AT, Pattern end output, Output by communication command, Heating/Cooling control output OUT2 (for EV2 option only).

For Event output EV1/EV2, Heater burnout alarm output and Output by communication command are available when C5W, EIW, C5 or W option is ordered.

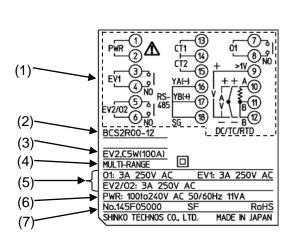
- (*4) When EV2+D□ option and EIT option are added simultaneously, Transmission output terminals become EV2 output terminals, so Transmission output is disabled. For the BCS2, EV2+D□ cannot be selected.
- (*5) For the BCS2, Event input (2 points) is not available.
- (*6) For direct current output type, Heater burnout alarm does not work.
- (*7) For the BCS2, 1 point of Event input is available.

1.2 How to Read the Model Label

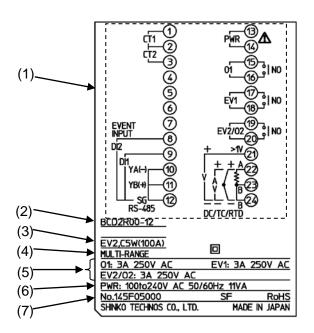
The model label is attached to the right side of the case.

BCS2 (e.g.) BCS2R00-12

BCR2, BCD2 (e.g.) BCD2R00-12



(Fig. 1.2-1)



(Fig. 1.2-2)

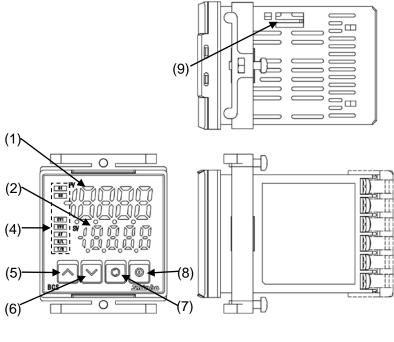
No.	Description	Example
(1)	Terminal arrangement	BCS2R00-12, BCD2R00-12 (*1)
(2)	Model	BCS2R00-12, BCD2R00-12
(3)	Option	EV2 (Event output EV2)
		C5W(100A) [Serial communication + Heater burnout
		alarm (100 A)] (*2)
(4)	Input	MULTI-RANGE (Multi-range input)
(5)	Control output, Event output	O1: 3 A 250 V AC (Control output OUT1)
		EV1: 3 A 250 V AC (Event output EV1)
		EV2: 3 A 250 V AC (Event output EV2)
(6)	Power supply voltage,	100 to 240 V AC 50/60 Hz,
	Power consumption	11 VA
(7)	Serial number	No. 145F05000

^(*1) Terminal arrangement diagram differs depending on the model.

^(*2) For Heater burnout alarm output (C5W, EIW, W options), CT rated current is entered in bracket ().

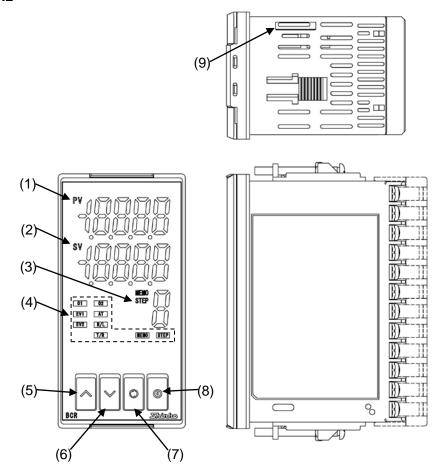
2. Name and Functions of Sections

BCS2

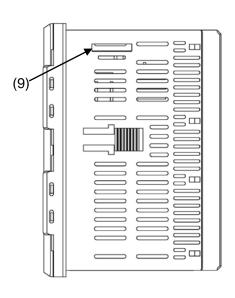


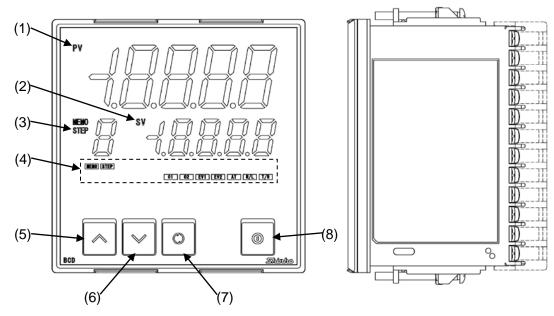
(Fig. 2-1)

BCR2



(Fig. 2-2)





(Fig. 2-3)

Display

No.	Name		Description				
(1)	PV Display	Indicates PV.	Indicates PV.				
		Indicates setting	g characters in each setting mode.				
(2)	SV Display	Indicates SV.					
		Indicates set da	ta in each setting mode.				
		In Monitor mode	e, indicated contents differ depending on the model as				
		follows.					
		Model	Model Indicated Contents				
		BCS2	BCS2 Indicates MV, Remaining time (Program control), Step				
		number (Program control) or Set value memory number					
			(Fixed value control).				
		BCR2, BCD2 Indicates MV or Remaining time (Program control).					
(3)	MEMO/STEP	Indicates Set value memory number (Fixed value control) or Step number					
	Display	(Program contro	ol). (For BCR2, BCD2)				

Action Indicators

No.	Name	Description
(4)	O1 (Green)	Lit when control output OUT1 is ON.
		For direct current output type, flashes corresponding to the MV in 125 ms
		cycles.
	O2 (Yellow)	Lit when control output OUT2 (EV2, DS, DA, EV2+D□ options) is ON.
		For direct current output type (DA option), flashes corresponding to the MV
		in 125 ms cycles.
	EV1 (Red)	Lit when Event output EV1 is ON.
	EV2 (Red)	Lit when Event output EV2 (EV2, EV2+D□ options) is ON.
		Unlit if \$\sum_B 19\$ (Heating/Cooling control relay contact output) is selected in
		[Event output EV2 allocation].
	AT (Yellow)	Flashes while AT, 'AT on startup' or Auto-reset is performing.
	R/L (Yellow)	Lit during Remote action, selected in [Remote/Local] (EIT option).
	T/R (Yellow)	Lit during Serial communication (C5W, C5 options) TX (transmitting) output.
	MEMO	Lit when Set value memory number (Fixed value control) is indicated.
	(Yellow)	(For BCR2, BCD2)
	STEP (Green)	Lit when a step number (Program control) is indicated. (For BCR2, BCD2)

Key

No.	Name		Description			
(5)	UP key	Increases the numeric value.				
		By pressing this key for 1 secor	nd during Program control, the performing			
		step is interrupted, proceeding t	o the beginning of the next step. (Advance			
		function)				
(6)	DOWN key	Decreases the numeric value.				
(7)	MODE key	Switches a setting mode, and registers the set data.				
		By pressing this key for 3 seconds during RUN mode, the unit enters				
		Monitor mode.				
(8)	OUT/OFF key	By pressing the @ key for approx. 1 second, one of the following items				
		selected in [OUT/OFF key function] is activated.				
		OUT/OFF Key Function	Description			
		Control output OFF function	Turns control output ON or OFF.			
		Auto/Manual control	Switches the Auto/Manual control.			
		Program control	Starts/Stops the Program control.			

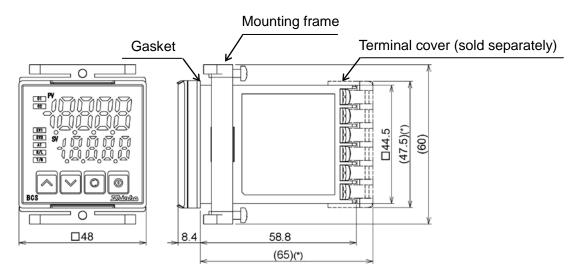
Console Connector

No.	Name	Description
(9)	Console	By connecting the tool cable (CMD-001, sold separately), the following
	connector	operations can be conducted from an external computer using the Console software SWC-BCx01M.
		Reading and setting of SV, PID and various set values
		Reading of PV and action status
		Function change

3. Mounting to the Control Panel

3.1 External Dimensions (Scale: mm)

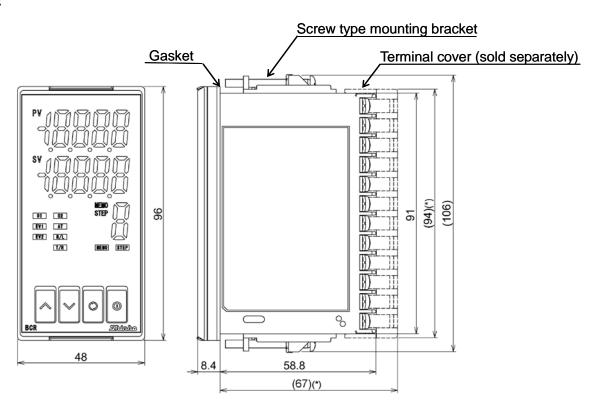
BCS2



(*) When the terminal cover is used.

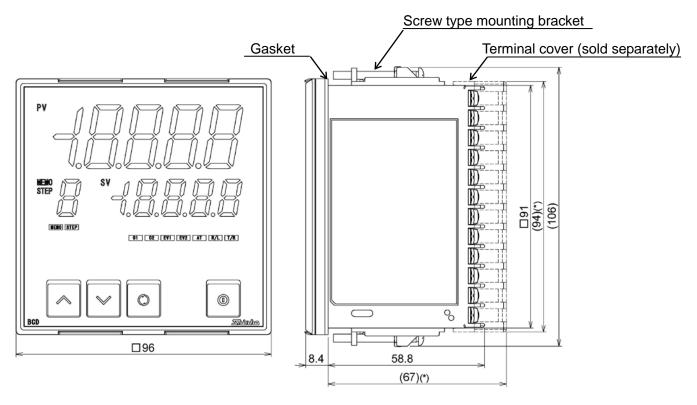
(Fig. 3.1-1)

BCR2



(*) When the terminal cover is used.

(Fig. 3.1-2)



(*) When terminal covers are used.

(Fig. 3.1-3)

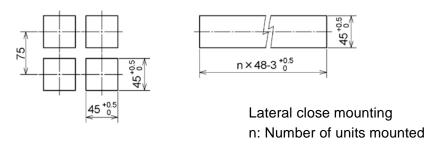
3.2 Panel Cutout (Scale: mm)



Caution

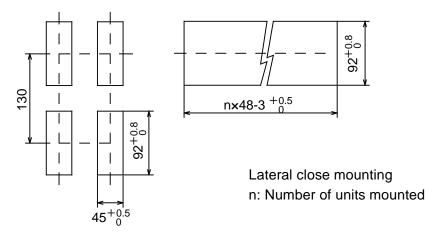
If lateral close mounting is used for the controller, IP66 specification (Drip-proof/Dust-proof) may be compromised, and all warranties will be invalidated.

BCS2



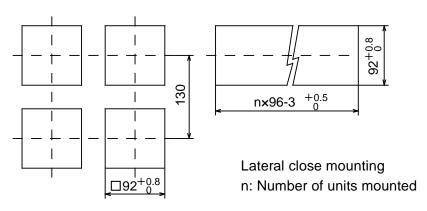
(Fig. 3.2-1)

BCR2



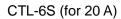
(Fig. 3.2-2)

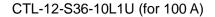
BCD2

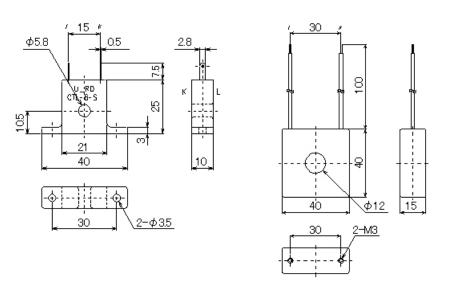


(Fig. 3.2-3)

3.3 CT (Current Transformer) External Dimensions (Scale: mm)







(Fig. 3.3-1)



Caution

As the mounting frame of the BCS2 is made of resin, do not use excessive force while tightening screws, or the mounting frame could be damaged.

Tighten screws with one rotation upon the screw tips touching the panel.

The torque is 0.05 to 0.06 N·m.

For the BCR2, BCD2, the torque should be 0.1 Nom.

3.4.1 How to Mount the Unit

BCS2

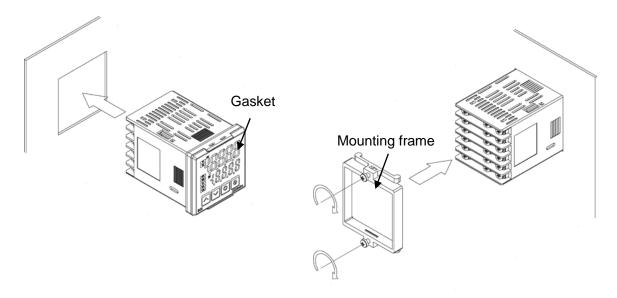
Mount the controller vertically to the flat, rigid panel to ensure it adheres to the Drip-proof/Dust-proof specification (IP66).

If the lateral close mounting is used for the controller, IP66 specification (Drip-proof/Dust-proof) may be compromised, and all warranties will be invalidated.

Mountable panel thickness: 1 to 5 mm

- (1) Insert the controller from the front side of the control panel. (Fig. 3.4.1-1)

 If the Drip-proof/Dust-proof specification (IP66) is not necessary, the gasket may be removed (please keep in mind the warranty is void if gasket is removed).
- (2) Insert the mounting frame until it comes into contact with the panel, and fasten with screws. Tighten screws with one rotation upon the screw tips touching the panel. (Fig. 3.4.1-2) The torque is 0.05 to 0.06 N•m.



(Fig. 3.4.1-1) (Fig. 3.4.1-2)

BCR2, BCD2

Mount the controller vertically to the flat, rigid panel to ensure it adheres to the Drip-proof/Dust-proof specification (IP66).

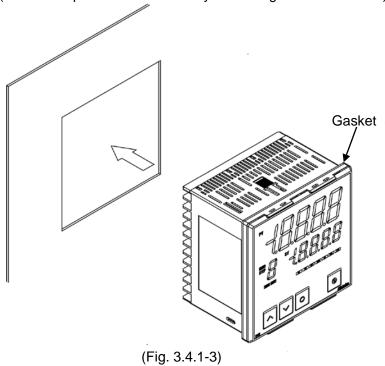
If the lateral close mounting is used for the controller, IP66 specification (Drip-proof/Dust-proof) may be compromised, and all warranties will be invalidated.

Mountable panel thickness: 1 to 7 mm

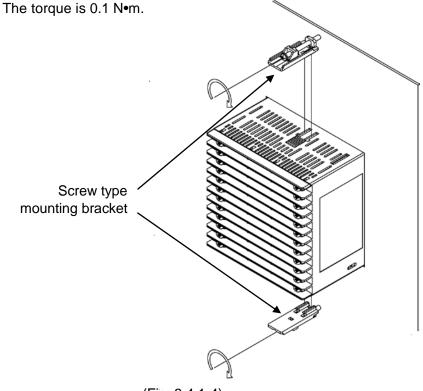
(1) Insert the controller from the front side of the control panel. (Fig. 3.4.1-3)

If the Drip-proof/Dust-proof specification (IP66) is not necessary, the gasket may be removed.

(Please keep in mind the warranty is void if gasket is removed).



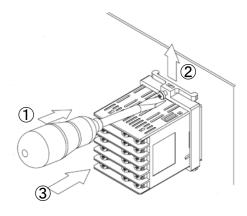
(2) Attach the mounting brackets by the holes at the top and bottom of the case, and secure the controller in place with the screws.



3.4.2 How to Remove the Mounting Frame and Unit

BCS2 (Fig. 3.4.2-1)

- (1) Turn the power to the unit OFF, and disconnect all wires before removing the mounting frame.
- (2) Insert a flat blade screwdriver between the mounting frame and unit (1).
- (3) Slowly push the frame upward using the screwdriver ($^{\textcircled{2}}$), while pushing the unit toward the panel ($^{\textcircled{3}}$).
- (4) Repeat step (2) and slowly push the frame downward using the screwdriver for the other side. The frame can be removed little by little by repeating these steps.



(Fig. 3.4.2-1)

BCR2, BCD2

- (1) Turn the power to the unit OFF, and disconnect all wires before removing the unit.
- (2) Loosen the screws of the mounting brackets, and remove the mounting brackets.
- (3) Pull the unit out from the front of the control panel.

4. Wiring



Warning

Turn the power supply to the instrument off before wiring or checking.

Working on or touching the terminal with the power switched on may result in severe injury or death due to electrical shock.



Caution

- Do not leave wire remnants in the instrument, as they could cause a fire or malfunction.
- Use the solderless terminal with an insulation sleeve in which the M3 screw fits when wiring the instrument.
- The terminal block of this instrument is designed to be wired from the left side. The lead wire must be inserted from the left side of the terminal, and fastened with the terminal screw.
- Tighten the terminal screw using the specified torque. If excessive force is applied to the screw when tightening, the terminal screw or case may be damaged.
- Do not pull or bend the lead wire on the terminal side when wiring or after wiring, as it could cause malfunction.
- When using a terminal cover for the BCS2, pass terminal wires numbered 7 to 12 into the holes of the terminal cover.
- This instrument does not have a built-in power switch, circuit breaker and fuse. It is necessary to install a-power switch, circuit breaker and fuse near the controller. (Recommended fuse: Time-lag fuse, rated voltage 250 V AC, rated current 2 A)
- For a 24 V AC/DC power source, do not confuse polarity when using direct current (DC).
- Do not apply a commercial power source to the sensor which is connected to the input terminal nor allow the power source to come into contact with the sensor.
- Use a thermocouple and compensating lead wire according to the sensor input specifications of this controller.
- Use the 3-wire RTD according to the sensor input specifications of this controller.
- For DC voltage input, (+) side input terminal number of 0 to 5 V DC, 1 to 5 V DC, 0 to 10 V DC differs from that of 0 to 1 V DC.

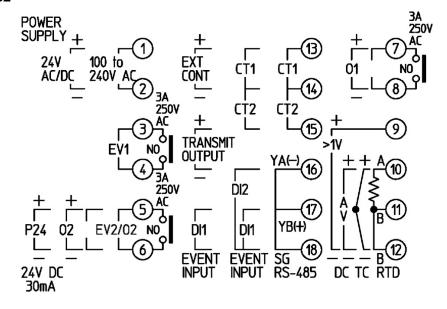
Model	Terminal Number					
BCS2	9: (+) side of 0 to 5 V DC, 1 to 5 V DC, 0 to 10 V DC					
	10: (+) side of 0 to 1 V DC					
BCR2, BCD2	②: (+) side of 0 to 5 V DC, 1 to 5 V DC, 0 to 10 V DC					
	②: (+) side of 0 to 1 V DC					

- When using a relay contact output type, externally use a relay according to the capacity of the load to protect the built-in relay contact.
- When wiring, keep input wires (thermocouple, RTD, etc.) away from AC sources or load wires.

4.1 Terminal Arrangement

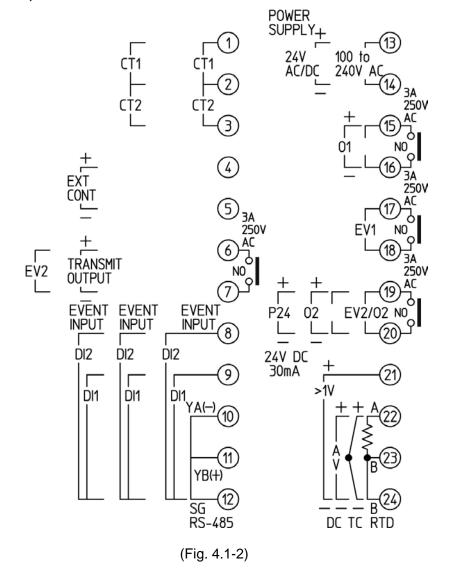
Terminal arrangement of the BCS2, BCR2, BCD2 differs depending on the options as follows.

BCS2



(Fig. 4.1-1)

BCR2, BCD2

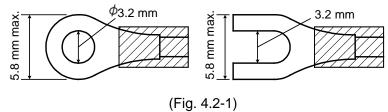


Terminal	Description		
POWER SUPPLY	100 to 240 V AC or 24 V AC/DC		
	For a 24 V AC/DC power source, do not confuse polarity when using		
	direct current (DC).		
EV1	Event output E\	/1	
EV2	Event output E\	/2 (EV2, EV2+D□ options)	
O2	Control output C	DUT2 (EV2, DS, DA, EV2+D□ options)	
P24	24 V DC insulat	ed power output (P24 option)	
O1	Control output C	DUT1	
RTD	RTD input		
TC	Thermocouple i	nput	
DC	Direct current, [DC voltage inputs	
	_	e input, (+) side input terminal number of 0 to 5 V DC, 1 to	
	5 V DC, 0 to 1	0 V DC differs from that of 0 to 1 V DC.	
	Model	Terminal Number	
	BCS2	9: + side of 0 to 5 V DC, 1 to 5 V DC, 0 to 10 V DC	
		10: + side of 0 to 1 V DC	
	BCR2, BCD2	②: + side of 0 to 5 V DC, 1 to 5 V DC, 0 to 10 V DC	
		②: + side of 0 to 1 V DC	
0.74	CT in rout 4 (OFW FIV W		
CT1	CT input 1 (C5W, EIW, W options)		
CT2	CT input 2 (C5W,		
RS-485	Serial communication RS-485 (C5W, C5 options)		
EVENT INPUT	Event input DI1 (BCS2: EIW, EIT, EI options,		
	BCR2/BCD2: C5W, EIW, EIT, EI options)		
	Event input DI2 (BCS2: EIW, EI options,		
EVT CONT	BCR2/BCD2: C5W, EIW, EIT, EI options)		
EXT CONT	External setting input (EIT option)		
TRANSMIT OUTPUT	Transmission output (EIT option) or Event output EV2 (EV2+D□ option)		
	BCR2, BCD2: If EV2+D□ option and EIT option are added simultaneously,		
	Transmission output terminals become EV2 output terminals, so Transmission output will be disabled.		
	output will be als	Sapieu.	

4.2 Lead Wire Solderless Terminal

Use a solderless terminal with an insulation sleeve in which an M3 screw fits as shown below. The torque should be 0.63~N \cdot m.

Solderless	Manufacturer	Model	Tightening
Terminal	Wallulacturei	Wiodei	Torque
Y-type	Nichifu Terminal Industries Co., Ltd.	TMEV1.25Y-3	
т-цуре	Japan Solderless Terminal MFG Co., Ltd.	VD1.25-B3A	O CO Nors
Ding type	Nichifu Terminal Industries Co., Ltd.	TMEV1.25-3	0.63 N•m
Ring-type	Japan Solderless Terminal MFG Co., Ltd.	V1.25-3	

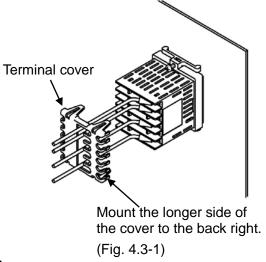


4.3 Terminal Cover

BCS2

When using a terminal cover (sold separately), make sure the longer side is on the back right side of the case

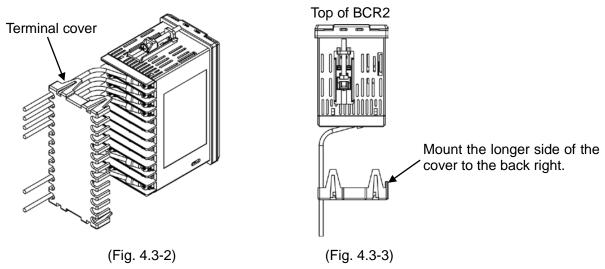
Pass the wires from terminals 7 to 12 into the holes of the terminal cover.



BCR2

When using a terminal cover (sold separately), make sure the longer side is on the back right side of the case.

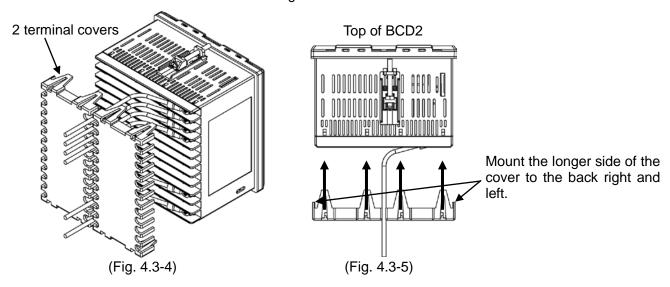
Pass the wires from terminals 13 to 24 through the left side of the terminal cover.



BCD2

When using terminal covers (sold separately), make sure the longer side is on the back right and left sides of the case.

Pass the wires from terminals 13 to 24 through between covers.



4.4 Wiring

For the terminal arrangement, refer to Section '4.1 Terminal Arrangement' (p.19).

4.4.1 Power Supply

Power supply voltage is 100 to 240 V AC or 24 V AC/DC.

For a 24 V AC/DC power source, ensure polarity is correct when using direct current (DC).

BCS2	BCR2, BCD2
PWR 2	PWR 13

4.4.2 Control Output OUT1, OUT2

When EV2, DS, DA or EV2+D□ option is ordered, control output OUT2 is available.

Specifications of Control output OUT1, OUT2 are shown below.

Relay contact	1a	
	Control capacity: 3 A 250 V AC (resistive load),	
	1 A 250 V AC (inductive load $\cos\phi$ =0.4)	
	Electrical life: 100,000 cycles	
	Minimum applicable load: 10 mA 5 V DC	
Non-contact voltage	12 V DC±15%	
(for SSR drive)	Max. 40 mA (short circuit protected)	
Direct current	4 to 20 mA DC	
	Load resistance: Max. 550 Ω	

BCS2		BCF	22, BCD2
Relay contact	Non-contact voltage, Direct current	Relay contact	Non-contact voltage, Direct current
EV2/02 5 0 NO	± 5 02 6	01 NO	01
01 8 NO	†	EV2/02/20 NO	02

Number of Shinko SSR units when connected in parallel (for Non-contact voltage output):

SA-400 series: 5 unitsSA-500 series: 2 units

4.4.3 Input

Each input wiring is shown below.

For DC voltage input, (+) side input terminal number of 0 to 5 V DC, 1 to 5 V DC, 0 to 10 V DC differs from that of 0 to 1 V DC.

BCS2			
Thermocouple	RTD	Direct current, DC voltage (0 to 1 V)	DC voltage (0 to 5 V, 1 to 5 V, 0 to 10 V)
+(10) (11) (12) TC	4(1) (1) (2) RTD	+ L 4 > J DC	+ (9) (10) (10) (10) (10) (10) (10) (10) (10

BCR2, BCD2			
Thermocouple	RTD	Direct current, DC voltage (0 to 1 V)	DC voltage (0 to 5 V, 1 to 5 V, 0 to 10 V)
7 F	A 22 W 23 B 23 RTD	R IF <>기+ (항) (항)	+ (1) (2) (3) (4) (4) (5) (6) (7) (7) (7) (7) (7) (7) (7) (7) (7) (7

4.4.4 Event Output 1, Event Output 2

Event output EV1 is a standard feature.

If EV2 or EV2+D□ option is ordered, Event output EV2 is available.

Specifications of Event output 1 and Event output 2 are shown below.

Relay contact	1a
	Control capacity: 3 A 250 V AC (resistive load)
	1 A 250 V AC (inductive load $\cos\phi$ =0.4)
	Electrical life: 100,000 cycles
	Minimum applicable load: 10 mA 5 V DC

BCS2	BCF	R2, BCD2
EV1 3 6	EV1 18 NO	
	For EV2 option	For EV2+D□ option
EV2/02 6 NO	EV2/02 19 NO	EV2 6 NO

4.4.5 Insulated Power Output

If P24 option is ordered, the Insulated power output is available.

Specifications of Insulated power output are shown below.

Output voltage	24±3 V DC (at load current 30 mA DC)
Ripple voltage	Within 200 mV DC (at load current 30 mA DC)
Max load current	30 mA DC

BCS2	BCR2, BCD2
P24 6	P24 20

4.4.6 CT Input

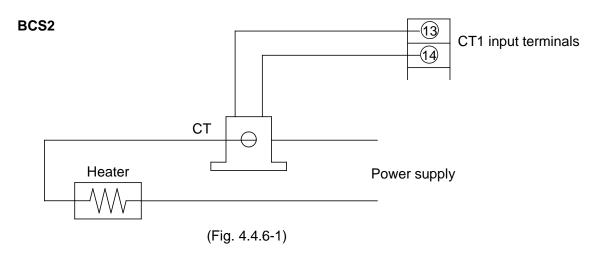
CT input is available when Heater burnout alarm (C5W, EIW, W options) is ordered.

Cannot be used for detecting heater current under phase control.

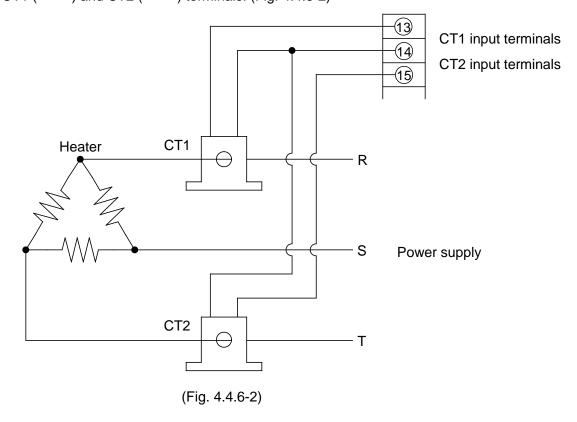
BCS2	BCR2, BCD2
CT1 (14)	CT1 2
CT2 (15)	CT2 3

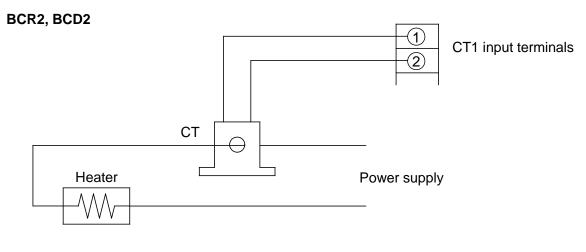
Use the CT (current transformer) provided, and pass one lead wire of the heater circuit into the hole of the CT. (Fig. 4.4.6-1)

When wiring, keep the CT wire away from AC sources or load wires to avoid the external interference.



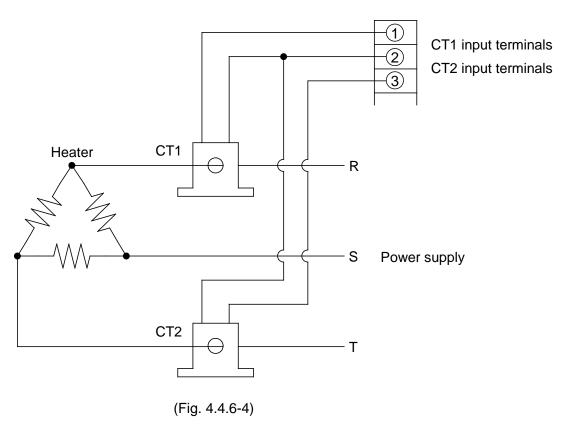
If using 3-phase, pass any 2 lead wires of R, S, T into the CT, and connect them to CT1 ($^{\textcircled{3}-\textcircled{4}}$) and CT2 ($^{\textcircled{4}-\textcircled{5}}$) terminals. (Fig. 4.4.6-2)





(Fig. 4.4.6-3)

When using 3-phase, pass any 2 lead wires of R, S, T into the CT, and connect them to CT1 $(^{\textcircled{1}-\textcircled{2}})$ and CT2 $(^{\textcircled{2}-\textcircled{3}})$ terminals. (Fig. 4.4.6-4)



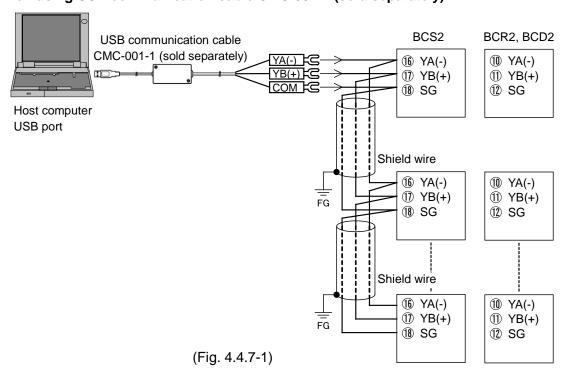
4.4.7 Serial Communication

If the C5W or C5 option is ordered, Serial communication is available.

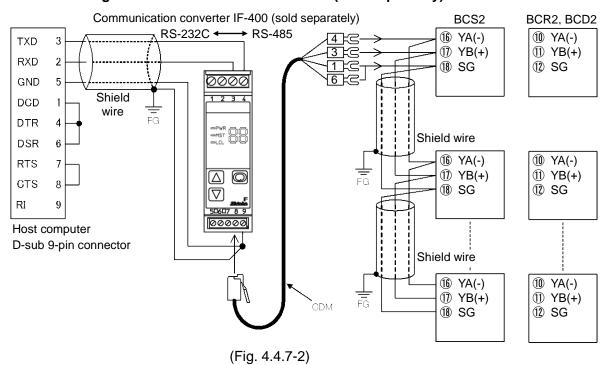
BCS2	BCR2, BCD2
YA(-) (6)	YA(-) (1)
YB(+) (7)	YB(+) (1)
485 (8)	SG (12)
SG (8)	RS-485

(1) Serial Communication

• When using USB communication cable CMC-001-1 (sold separately)



• When using communication converter IF-400 (sold separately)



(2) Set value digital transmission

By connecting to Shinko programmable controllers [PC-900 or PCD-33A with the SVTC (Set value digital transmission) option], digital SV via the SVTC command can be received from programmable controllers.

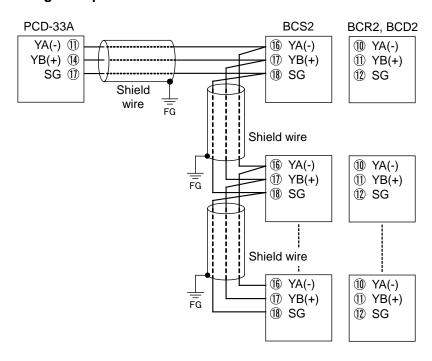
Wiring

For the PC-900, connect YA (-) to YA (-), YB (+) to YB (+), COM (PC-900) to SG (BCx2) terminal respectively.

For the PCD-33A, connect YA (-) to YA (-), YB (+) to YB (+), SG to SG terminal respectively. Up to 31 units of the BCS2 or BCR2 or BCD2 can be connected.

The following shows a connection example of PCD-33A and BCS2, BCR2, BCD2. (Fig. 4.4.7-3)

Wiring example of PCD-33A and BCx2



(Fig. 4.4.7-3)

Shield wire

Connect only one end of the shield to the FG terminal to avoid a ground loop. If both ends of the shield wire are connected to the FG terminal, the circuit will be closed, resulting in a ground loop. This may cause noise. Be sure to ground the FG terminal.

Recommended cable: OTSC-VB 2PX0.5SQ (made by Onamba Co., Ltd.) or equivalent (Use a twisted pair cable.)

4.4.8 Event Input

Event Input DI1 is available for the BCS2 with Event input (EIW, EIT, EI options).

Event Input DI1 is available for the BCR2, BCD2 with Serial communication (C5W option) or Event input (EIW, EIT, EI options).

Event Input DI2 is available for the BCS2 with Event input (EIW, EI options).

Event Input DI2 is available for the BCR2, BCD2 with Serial communication (C5W option) or Event input (EIW, EIT, EI options).

Specifications of Event input are shown below.

Circuit current when closed	Approx. 16 mA
-----------------------------	---------------

BCS2		BCR2, BCD2
EIW (20A), EIW (100A), EI	EIW (100A), EIT	
DI2 (17) DI1 (18) EVENT (NPUT	DI1 (18) EVENT INPUT	DI2

4.4.9 External Setting Input

If the EIT option is ordered, External setting input is available.

Specifications of External setting input are shown below.

Setting signal	Direct current 4 to 20 mA DC
Allowable input	50 mA DC max.
Input impedance	50 Ω max.
Input sampling period	125 ms

BCS2	BCR2, BCD2
EXT ± (3) CONT (4)	EXT CONT 5

4.4.10 Transmission Output

If the EIT option is ordered, Transmission output is available.

For the BCR2, BCD2, if EV2+D□ option and EIT option are added simultaneously,

Transmission output terminals become EV2 output terminals, so Transmission output will be disabled.

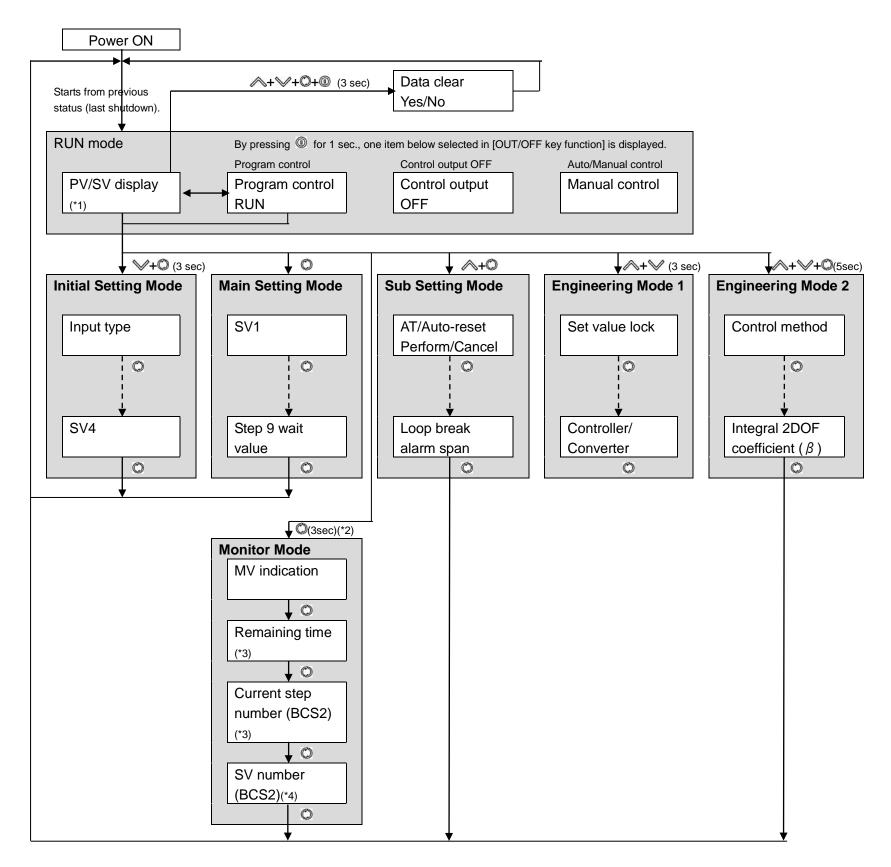
Specifications of Transmission output are shown below.

Resolution	12000	
Output	4 to 20 mA DC	
_	Load resistance: Max 550 Ω	
Output accuracy	Within ±0.3% of Transmission output span	

BCS2	BCR2, BCD2
TRANSMIT 15 OUTPUT	TRANSMIT +6 OUTPUT -7

5. Outline of Key Operation and Each Mode

5.1 key Operation



[Each Mode and Setting Item]

- (*1) If 'Program control' is selected in [OUT/OFF key function], the unit will enter Standby mode (program control waiting).
- (*2) The unit cannot proceed to Monitor mode if it is in Standby of program control.
- (*3) Available only when 'Program control' is selected in [OUT/OFF key function].
- (*4) Not available if 'Program control' is selected in [OUT/OFF key function].

[Key Operation]

- ∧+V+O+O (3 sec): Press and hold the ∧, ∨, O, O keys (in that order) together for approx. 3 sec.
- √+□ (3 sec): Press and hold the

 √, □ keys (in that order) together for approx. 3 sec.
- \wedge + \mathbb{O} : Press and hold the \wedge , \mathbb{O} keys (in that order) together.
- ♦ +
 (3 sec): Press and hold the
 ♠,
 ♦ keys (in that order) together for approx. 3 sec.
- ♥ ②: If the ③ key is pressed, the unit will proceed to the next setting item, illustrated by an arrow.

 By pressing the ⑤ key, the mode goes back to the previous mode.
- ↓ ○: Press the key until the desired setting mode appears.

- ullet Use the $width {\sim}$ or $width {\sim}$ key for settings or selections, and register them by pressing the $width {\sim}$ key.
- If the \square key is pressed for approx. 3 seconds at each item, the unit will revert to the RUN mode.
- If the key is pressed for approx. 3 seconds at each item, the following will be performed depending on the selection in [OUT/OFF key function]. If 'Control output OFF function' is selected in [OUT/OFF key function], the unit will enter Control output OFF status.
 - If 'Auto/Manual control' is selected in [OUT/OFF key function], the unit will enter Manual control status.
 - If 'Program control' is selected in [OUT/OFF key function], the unit will enter 'Program control RUN' or Standby mode.

5.2 Modes

Mode	Description		
RUN mode	When power is turned ON, the unit enters RUN mode.		
	The PV Display indicates PV, and the SV Display indicates SV. Control starts from previous status (last shutdown). By pressing the key for approx. 1 sec, one of the following functions is		
	activated depending on the selection in [OUT/OFF key function].		
	OUT/OFF Ke		Description
	Control output OF	-	Turns the control output ON or OFF.
	Auto/Manual contr		Switches the Auto/Manual control.
	Program control	OI .	Starts/Stops the Program control.
Monitor mode	<u> </u>	key for approx 3	sec in RUN mode, the unit enters Monitor
Worldor mode	' '		, and the SV Display indicates MV.
		• •	ne following is indicated.
	Indicated contents	•	•
	Model	differ depending	Indicated Contents
	BCS2	Indicatos MV/ B	Remaining time (Program control), Step
	BC32	· ·	am control) or Set value memory number
		(Fixed value co	•
	PCD2 PCD2	,	•
Initial patting made	BCR2, BCD2		r Remaining time (Program control).
Initial setting mode	' '	• ,	that order) together for approx. 3 sec in RUN
	mode, the unit ente	•	ode.
	The following items		nit Event cutout EV4/EV2 /EV2 EV2 D
	1	•	nit, Event output EV1/EV2 (EV2, EV2+D
Main actting made			/DI2 allocation (*), SV1, etc.
Main setting mode	SV can be set.	key iii Kon iiioc	le, the unit enters Main setting mode.
		l' is solosted in [C	OUT/OFF key function], SV, Time and Wait
	value for Steps 1 t		7017011 key function], 3V, Time and Wait
	· ·		ected in [Event input DI1/DI2 allocation] (*)
	SV1 to SV4 can be		ected in [Event input DI1/DI2 allocation] (*),
Sub setting mode			that order) together in RUN mode, the unit
Oub setting mode	enters Sub setting	, ,	rtiat order) together in reord mode, the drift
	The following items		
			se action, Event output EV1/EV2 (EV2,
	EV2+D□ option		50 dotton, 2001t odtput 2 1/2 v 2 (2 v 2,
Engineering mode 1	·	•	n that order) together for approx. 3 sec in
Linging mode i	RUN mode, the uni	• `	, -
	The following items	•	ing mode 1.
			12 allocation (*), Event output EV1/EV2
		•	n, Sensor correction, PV filter time constant,
	<u> </u>		unction, Controller/Converter, etc.
Engineering mode 2	-		n that order) together for approx. 5 sec in
g : ::g ::eac 1	RUN mode, the uni	- · · ·	
	The following items	_	
			n 2DOF coefficient ($lpha$), Integral 2DOF
	coefficient (β)	,	· (· // · · · · · · · · · · · · · · · ·

^(*) Event input DI1 allocation: BCS2 with EIW, EIT, EI options, BCR2/BCD2 with C5W, EIW, EIT, EI options Event input DI2 allocation: BCS2 with EIW, EI options, BCR2/BCD2 with C5W, EIW, EIT, EI options

5.3 Basic Operation after Power-ON

After the unit is mounted to the control panel and wiring is completed, operate the unit following the procedures below.

(1) Turn the power supply to the unit ON

After the power is turned ON, the PV Display indicates the input type, and the SV Display indicates the Input range high limit value (for thermocouple, RTD inputs) or Scaling high limit value (for DC voltage, current inputs) for approximately 3 seconds. (Table 5.3-1)

During this time, all outputs and the indicators are in OFF status. [0 mA DC for the direct current output type, and 0 mA DC for Transmission output (EIT option)]

Control will then start, indicating the PV on the PV Display and SV on the SV Display. While the control output OFF function is working, the PV Display indicates [aFF...]. Indication differs depending on the selection in [Indication when control output OFF].

(Table 5.3-1)

Concer land		С	°F	
Sensor Input	PV Display	SV Display	PV Display	SV Display
K	EIL	1370	EIIF	2498
	E□ .E	4000	E□ .F	752.0
J	J	1000	J	1832
R	- L	1760	r F	3200
S	5 I	1760	5 F	3200
В	ЬШЕ	1820	ЬШЕ	3308
E	$\mathcal{E} \square \mathcal{L}$	800	EIIF	1472
Т	Γ□ .Ε	4000	Γ□ .F	752.0
N	$\neg \Box \mathcal{L}$	1300	∩∏F	2372
PL-II	PL20	1390	PL 2F	2534
C(W/Re5-26)	σ	23 15	c F	4 199
Pt100	PF .E	8500	PC .F	156 <i>2.</i> 0
JPt100	JPF.E	5000	JPCF	932.0
Pt100	PT	850	PTUF	1562
JPt100	JPFE	□5 <i>00</i>	JPFF	_932
4 to 20 mA DC	420R			
0 to 20 mA DC	020R			
0 to 1 V DC	O IB	Scaling high	limit value	
0 to 5 V DC	0058		minit value	
1 to 5 V DC	/□58			
0 to 10 V DC	0 108			

When power is turned ON, and any errors are found, the following error codes are indicated on the PV Display.

To cancel the error code, press the \bigcirc key.

Error Code	Error Contents	
E-01	Non-volatile IC memory is defective.	
E-02	Data writing (in non-volatile IC memory) error when power failure occurs.	

(2) Enter each value.

Refer to Sections '6. Initial Setting' (p.37) to '8. Operation and Settings of Standard Functions' (p.80):

Enter each value: Input type, Control method, Direct/Reverse action, SV, PID constants, Event output EV1 allocation, etc.

(3) Turn the load circuit power ON

Control starts, so as to reach, and then maintain the control target at the SV.

Error codes during operation

If errors occur during operation, error codes below are indicated on the PV Display.

Error Code	Error Contents
Er05 (*)	PV has exceeded Input range high limit value (scaling high limit value for DC
C C U D (^)	voltage, current inputs).
E-05 (*)	PV has dropped below Input range low limit value (scaling low limit value for DC
	voltage, current inputs).
E-07 (*)	Input burnout, or PV has exceeded the Indication range and Control range.
Er 10	Hardware malfunction

^(*) Indicated when Enabled is selected in [Error indication Enabled/Disabled].

Indication Range and Control Range

Input Type	Indication Range and Control Range
Thermocouple	[Input range low limit – 50°C (100°F)] to [Input range high limit + 50°C (100°F)]
RTD	[Input range low limit – Input span x 1%] to [Input range high limit + 50°C (100°F)]
DC voltage,	[Scaling low limit – Scaling span x 1%] to
Direct current	[Scaling high limit + Scaling span x 10%]

• Input error (Overscale, Underscale)

If input errors (overscale, underscale) occur, the following will be performed depending on the selection in [Error indication Enabled/Disabled].

If Disabled is selected in [Error indication Enabled/Disabled]:

Overscale occurs if PV has exceeded Input range high limit value (Scaling high limit value for DC voltage, current inputs). The PV Display indicates PV.

Underscale occurs if PV has dropped below Input range low limit value (Scaling low limit value for DC voltage, current inputs). The PV Display indicates PV.

For manual control, the preset MV is output.

If Enabled is selected in [Error indication Enabled/Disabled]:

Overscale occurs if PV has exceeded Input range high limit value (Scaling high limit value for DC voltage, current inputs). The PV Display indicates PV and error code $\mathcal{E} r \mathcal{Q} \mathcal{G}$ alternately.

Underscale occurs if PV has dropped below Input range low limit value (Scaling low limit value for DC voltage, current inputs). The PV Display indicates PV and error code $\mathcal{E} r \mathcal{Q} \mathcal{E}$ alternately.

For manual control, the preset MV is output.

Burnout

If burnout occurs, the following will be performed depending on the selection in [Error indication Enabled/Disabled].

If Disabled is selected in [Error indication Enabled/Disabled]:

If PV has exceeded Indication range and Control range, the PV Display flashes [_ _ _].

If PV has dropped below Indication range and Control range, the PV Display flashes [_ _ _ _].

If thermocouple or RTD input is burnt out, or if DC voltage (0 to 1 V DC) input is disconnected, the PV Display flashes [_____].

If DC voltage or current input is disconnected:

For 4 to 20 mA DC, 1 to 5 V DC inputs, the PV Display flashes [_ _ _ _].

For 0 to 20 mA DC, 0 to 5 V DC and 0 to 10 V DC inputs, the PV Display indicates the value corresponding with 0 mA DC or 0 V DC input.

OUT1 and OUT2 are turned OFF (OUT1 low limit value for direct current output, and OUT2 low limit value for DA, EV2+DA).

For manual control, the preset MV is output.

If Alarm, Heater burnout alarm or Loop break alarm is selected in [Event output EV1/EV2 allocation], Event output will be turned ON under the alarm active conditions.

Burnout is enabled even in standby (program control waiting) mode in Program control.

[Output status when input errors occur] can be used only for controllers using direct current and voltage inputs, and direct current output.

Output status differs depending on selection in [Output status when input errors occur].

Output status when input errors occur	Contents, Indication	Output Status			
		OUT1		OUT2	
		Direct	Reverse	Direct	Reverse
		(Cooling) action	(Heating) action	(Cooling) action	(Heating) action
۵∩Ⅲ	[] is flashing.	ON (20mA) or OUT1 high limit value (*)	OFF (4mA) or OUT1 low limit value	OFF or OUT2 low limit value	ON or OUT2 high limit value (*)
oFF.		OFF (4mA) or OUT1 low limit value			OFF or OUT2 low limit value
on	[] is flashing.	OFF (4mA) or OUT1 low limit value	ON (20mA) or OUT1 high limit value (*)	ON or OUT2 high limit value (*)	OFF or OUT2 low limit value
oFF			OFF (4mA) or OUT1 low limit value	OFF or OUT2 low limit value	

^(*) Outputs a value between OFF (4mA) and ON (20mA) or between OUT1 (or OUT2) low limit value and OUT1 (or OUT2) high limit value, depending on deviation.

If Enabled is selected in [Error indication Enabled/Disabled]:

If PV has exceeded Indication range and Control range, the PV Display indicates $\begin{bmatrix} \overline{} & \overline{} \end{bmatrix}$ and $\begin{bmatrix} E r \overline{} & \overline{} \end{bmatrix}$ alternately.

If PV has dropped below Indication range and Control range, the PV Display indicates [---] and $[E \cap G]$ alternately.

If thermocouple or RTD input is burnt out, or if DC voltage (0 to 1 V DC) input is disconnected, the PV Display indicates [$\overline{}$] and [$\overline{}$ $\overline{}$ $\overline{}$] alternately.

If DC voltage or current input is disconnected:

For 4 to 20 mA DC, 1 to 5 V DC inputs, the PV Display indicates [---] and $[E \cap G]$ alternately.

For 0 to 20 mA DC, 0 to 5 V DC and 0 to 10 V DC inputs, the PV Display indicates the value corresponding with 0 mA DC or 0 V DC input.

OUT1 and OUT2 are turned OFF (OUT1 low limit value for direct current output, and OUT2 low limit value for DA, EV2+DA).

For manual control, the preset MV is output.

If Alarm, Heater burnout alarm or Loop break alarm is selected in [Event output EV1/EV2 allocation], Event output will be turned ON under the alarm active conditions.

Burnout is enabled even in standby (program control waiting) mode in Program control

[Output status when input errors occur] can be used only for controllers using direct current and voltage inputs, and direct current output.

Output status differs depending on selection in [Output status when input errors occur].

Output status when input errors occur	Contents, Indication	Output Status				
		OUT1		OUT2		
		Direct	Reverse	Direct	Reverse	
		(Cooling) action	(Heating) action	(Cooling) action	(Heating) action	
on	[] and [E r []] are indicated alternatedly.	ON (20mA) or OUT1 high limit value (*)	OFF (4mA) or OUT1 low limit value	OFF or OUT2 low limit value	ON or OUT2 high limit value (*)	
oFF		OFF (4mA) or OUT1 low limit value			OFF or OUT2 low limit value	
on	[and] and [and] are indicated alternatedly.	OFF (4mA) or OUT1 low limit value	ON (20mA) or OUT1 high limit value (*)	ON or OUT2 high limit value (*)	OFF or OUT2 low limit value	
oFF.			OFF (4mA) or OUT1 low limit value	OFF or OUT2 low limit value		

^(*) Outputs a value between OFF (4mA) and ON (20mA) or between OUT1 (or OUT2) low limit value and OUT1 (or OUT2) high limit value, depending on deviation.

6. Initial Setting

Setup (setting the Input type, Event output allocation, SV, etc.) should be done before using this controller, according to the user's conditions.

Perform setup in Initial setting mode.

Setting items in Initial setting mode are shown in (Table 6.1).

If the user's specification is the same as the factory default value of this instrument, or if user's instrument has already been installed in a system, initial settings are not necessary. Proceed to Section '7. Settings' (p.53).

(Table 6.1)

Setting Items in Initial Setting Mode	Factory Default
Input type	K -200 to 1370℃
Scaling high limit	1370℃
Scaling low limit	-200°C
Decimal point place	No decimal point
Event output EV1 allocation	No event
EV1 alarm value 0 Enabled/Disabled	Disabled
EV1 alarm value	0℃
EV1 high limit alarm value	0℃
EV1 alarm hysteresis	1.0℃
EV1 alarm delay time	0 sec
EV1 alarm Energized/De-energized	Energized
Event output EV2 allocation (EV2 option)	No event
EV2 alarm value 0 Enabled/Disabled (EV2, EV2+D□ options)	Disabled
EV2 alarm value (EV2, EV2+D□ options)	0℃
EV2 high limit alarm value (EV2, EV2+D□ options)	0℃
EV2 alarm hysteresis (EV2, EV2+D□ options)	1.0℃
EV2 alarm delay time (EV2, EV2+D□ options)	0 sec
EV2 alarm Energized/De-energized (EV2, EV2+D□ options)	Energized
Heater burnout alarm 1 value (C5W, EIW, W options)	0.0 A
Heater burnout alarm 2 value (C5W, EIW, W options)	0.0 A
Loop break alarm time	0 minutes
Loop break alarm span	0℃
Event input DI1 allocation	No event
(BCS2: EIW, EIT, EI options, BCR2/BCD2: C5W, EIW, EIT, EI options)	
Event input DI2 allocation	No event
(BCS2: EIW, EI options, BCR2/BCD2: C5W, EIW, EIT, EI options)	
External setting input high limit (EIT option)	1370℃
External setting input low limit (EIT option)	-200°C
Transmission output type (EIT option)	PV transmission
Transmission output high limit (EIT option)	1370℃
Transmission output low limit (EIT option)	-200°C
SV1	0℃
SV2 (BCS2: EIW, EIT, EI options, BCR2/BCD2: C5W, EIW, EIT, EI options)	0℃
SV3 (BCS2: EIW, EI option, BCR2/BCD2: C5W, EIW, EIT, EI options)	0℃
SV4 (BCS2: EIW, EI option, BCR2/BCD2: C5W, EIW, EIT, EI options)	0℃

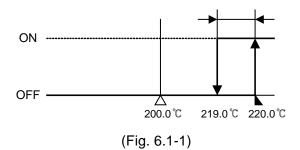
6.1 Example of Initial Setting

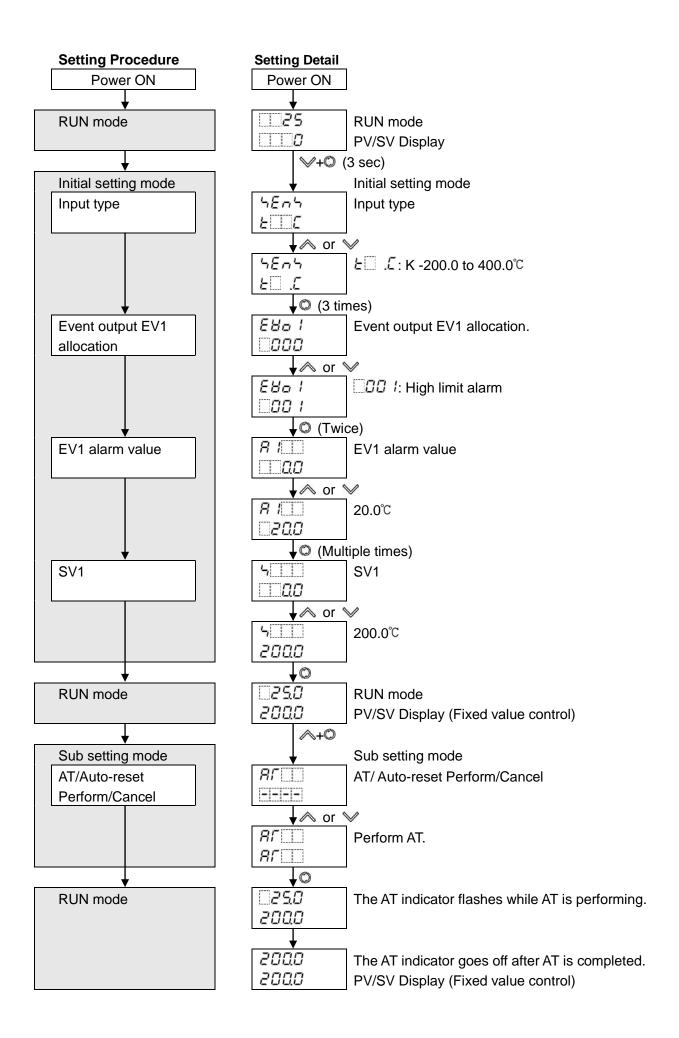
(e.g.) BCS2R00-00

Initial Setting Items	Example
Input type	K -200.0 to 400.0℃
Event output EV1 allocation	High limit alarm
EV1 alarm value	20.0℃ (Deviation setting from SV)
SV	200.0℃ (Fixed value control)

PID control is performed. PID constants are calculated by performing AT.

Alarm action





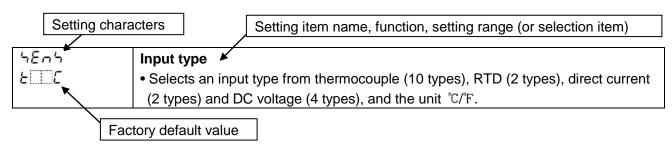
6.2 Initial Setting Mode

To enter Initial setting mode, press and hold the \vee and \bigcirc keys (in that order) for 3 seconds in RUN mode. To set (or select) each setting item, use the \wedge or \vee key.

To register each setting item, press the © key.

Explanation of setting item:

- Upper left: PV Display: Indicates setting characters.
- Lower left: SV Display: Indicates factory default value.
- Right side: Indicates the setting item, explanation of its function, and setting range (or selection item).



Characters, Factory Default	Setting Item, Function, Setting Range			
5€05 €□□€	(2 type • When connect with the when Change	elects an input type from thermocouple (10 types), RTD (2 types), direct current types) and DC voltage (4 type), and the unit °C/°F. Then changing the input from DC voltage to other inputs, remove the sensor onnected to this controller first, then change the input. If the input is changed the the sensor connected, the input circuit may break. Then changing an input type, refer to Section "8.10 Items to be Initialized by hanging Settings" (p.98).		
	ELLE	K -200 to 1370°C	EIF	K -328 to 2498°F
	E .C	K -200.0 to 400.0℃	E□ .F	K -328.0 to 752.0°F
	J	J -200 to 1000℃	J∭F	J -328 to 1832°F
	- II E	R 0 to 1760°C	r F	R 32 to 3200°F
	5 E	S 0 to 1760°C	4 F	S 32 to 3200°F
	ьШС	B 0 to 1820℃	Ь∭Е	B 32 to 3308°F
	ΕΠΕ	E -200 to 800°C	E	E -328 to 1472°F
	T .E	T -200.0 to 400.0℃	Γ□ .F	T -328.0 to 752.0°F
	$\neg \Box \mathcal{L}$	N -200 to 1300°C	n F	N -328 to 2372°F
	PL2C	PL-Ⅱ 0 to 1390°C	PL2F	PL-Ⅱ 32 to 2534°F
	σ	C(W/Re5-26) 0 to 2315°C	c F	C(W/Re5-26) 32 to 4199°F
	PF .E	Pt100 -200.0 to 850.0°C	PT F	Pt100 -328.0 to1562.0°F
	JPT.E	JPt100 -200.0 to 500.0°C	JPTF	JPt100 -328.0 to 932.0°F
	PT	Pt100 -200 to 850°C	PF	Pt100 -328 to 1562°F
	JPFE	JPt100 -200 to 500℃	JPFF	JPt100 -328 to 932°F
	420A	4 to 20 mA DC -2000 to 10000	<u> </u>	
	020R	0 to 20 mA DC -2000 to 10000	<u> </u>	
	B⊟ IR	0 to 1 V DC -2000 to 10000	<u> </u>	
	0058	0 to 5 V DC -2000 to 10000		
	/□58	1 to 5 V DC -2000 to 10000		
_	0 108	0 to 10 V DC -2000 to 10000		
\5\LH 1370	Scaling high limit • Sets scaling high limit value.			
	Setting range: Scaling low limit value to Input range high limit value			
	DC voltage, current inputs: -2000 to 10000 (*1)			

 $^{(^{\}star}1)$ The placement of the decimal point follows the selection.

Characters, Factory Default	Setting Item, Function, Setting Range			
4566	Scaling low limit			
-200	Sets scaling low limit value.			
	Setting range: Input range low limit value to Scaling high limit value DC voltage, current inputs: -2000 to 10000 (*1)			
d₽□□		point place		
\Box \Box \Box \Box		Selects decimal point place.		
	Selectio			
		No decimal point		
		1 digit after decimal point		
	<u> </u>	2 digits after decimal point		
	0000	3 digits after decimal point		
		nly for DC voltage and current inputs		
E80 !		tput EV1 allocation		
□000		Event output EV1 from the Event Outp		
		nanging Event output EV1, refer to Sec	ction "8.10 Items to be Initialized by	
	Selectio	g Settings" (p.98).		
		itput Allocation Table		
		No event		
	000	Alarm output, High limit alarm		
	002	Alarm output, I light limit alarm		
	003	Alarm output, High/Low limits alarm		
	007	Alarm output, High/Low limits alarm		
		independent alarm		
	005	Alarm output, High/Low limit range alarm		
	006	Alarm output, High/Low limit range independent alarm		
	007	Alarm output, Process high alarm		
	008	Alarm output, Process low alarm		
	009	Alarm output, High limit with standby alarm		
	□ <i>0 10</i>	Alarm output, Low limit with standby alarm		
		Alarm output, High/Low limits with standby alarm		
	□0 12	Alarm output, High/Low limits with standby independent alarm		
	□ <i>0 13</i>	Heater burnout alarm output		
	□ <i>0</i> /4	Loop break alarm output		
	□ <i>0 1</i> 5	Time signal output	Turns OFF or ON during Program control, by setting OFF and ON time within the step set in [Step number].	
	□0 I5	Output during AT	Turns ON during AT.	
	□ <i>0</i> 17	Pattern end output	Turns ON when Program control ends, and remains ON until turned	
	□ <i>0 18</i>	Output by communication command	OFF by pressing the ® key. Turns OFF or ON by communication command 00E4H during Serial communication. B0 EV1 output 0: OFF 1: ON B1 EV2 output 0: OFF	
(#4) The color according (#4)		nt follows the selection.	1: ON	

^(*1)The placement of the decimal point follows the selection.

Characters,	Setting Item, Function, Setting Range			
Factory Default	EV1 alarm value 0 Enabled/Disabled			
	When EV1 alarm value is 0 (zero), alarm action can be Enabled or Disabled.			
// <i>D</i> ii:	Selection item:			
	Disabled			
	リモー Disabled リモー Enabled			
		High limit clarm) to 1705 (Alarm output High/Low limit range		
	Available when \$\overline{\mathcal{GG}}\$! (Alarm output, High limit alarm) to \$\overline{\mathcal{GG}}\$\$ (Alarm output, High/Low limit range independent alarm), \$\overline{\mathcal{GG}}\$\$ (Alarm output, High limit with standby alarm) to \$\overline{\mathcal{G}}\$\$ (Alarm output,			
	High/Low limits with standby independent alarm) are selected in [Event output EV1 allocation].			
B (EV1 alarm value	ent dann) are selected in [Event output Evil allocation].		
	• Sets EV1 alarm value.			
		'1 low limit alarm value in the following cases:		
		/Low limits independent alarm), \(\sum_005 \) (Alarm		
	_	independent alarm), or $\Box D \vdash C = C$ (Alarm output,		
		independent alarm) is selected in [Event output EV1		
	allocation].	,		
	Setting range:			
	High limit alarm	-(Input span) to Input span °C (°F) (*1) (*2)		
	Low limit alarm	-(Input span) to Input span °C (°F) (*1) (*2)		
	High/Low limits alarm	0 to Input span °C (°F) (*1) (*2)		
	High/Low limits independent	0 to Input span °C (°F) (*1) (*2)		
	alarm	, , , , , ,		
	High/Low limit range alarm	0 to Input span °C (°F) (*1) (*2)		
	High/Low limit range	0 to Input span °C (°F) (*1) (*2)		
	independent alarm			
	Process high alarm Input range low limit to Input range high limit (*1) (*3			
	Process low alarm	Input range low limit to Input range high limit (*1) (*3)		
	High limit with standby alarm	-(Input span) to Input span °C (°F) (*1) (*2)		
	Low limit with standby alarm	-(Input span) to Input span °C (°F) (*1) (*2)		
	High/Low limits with standby	0 to Input span °C (°F) (*1) (*2)		
	alarm			
	High/Low limits with standby	0 to Input span °C (°F) (*1) (*2)		
	independent alarm			
	Available when any alarm from \$\square GG \tag{6}\$	(Alarm output, High limit alarm) to 🖂 🞜 (Alarm output, High/Low		
	limits with standby independent alarm) is selected in [Event output EV1 allocation].			
A IH	EV1 high limit alarm value			
	Sets EV1 high limit alarm value.			
	This value is available only for the following.			
	,	/Low limits independent alarm), 🗆 🗆 🙃 (Alarm		
		independent alarm), or $\Box \Box \Box \Box \Box \Box \Box$ (Alarm output,		
	,	independent alarm) is selected in [Event output EV1		
	allocation].	, - ,,,,		
	Setting range: Same as those decimal point follows the selection.	e of EV1 alarm value		

^(*1) The placement of the decimal point follows the selection.

 $^(^*2)$ For DC voltage, current inputs, the input span is the same as the scaling span.

 $^{(^*3) \ \}text{For DC voltage, current inputs, input range low (or high) limit value is the same as scaling low (or high) limit value.}$

Characters,	Setting Item, Function, Setting Range		
Factory Default	EV1 alarm hysteresis		
	Sets EV1 alarm hysteresis.		
	• Setting range: 0.1 to 1000.0°C (°F),		
	DC voltage, current inputs: 1 to 10000 (*1)		
	Available when any alarm from \$\overline{\text{CG}}\$! (Alarm output, High limit alarm) to \$\overline{\text{C}}\$!? (Alarm output, High/Low		
8 183	limits with standby independent alarm) is selected in [Event output EV1 allocation].		
	EV1 alarm delay time		
<i>u</i>	 Sets EV1 alarm action delay time. When setting time has elapsed after the input enters the alarm output range, the 		
	alarm is activated.		
	Setting range: 0 to 10000 seconds		
	Available when any alarm from \$\Big G \big \text{ (Alarm output, High limit alarm) to \$\Big G \big \text{?} (Alarm output, High/Low		
	limits with standby independent alarm) is selected in [Event output EV1 allocation].		
RILA	EV1 alarm Energized/De-energized		
noñL	Selects Energized/De-energized status for EV1 alarm.		
	(Refer to 'EV1/EV2 Energized/De-energized' on p.50.)		
	Selection item:		
	noñL Energized		
	r E 出っ De-energized		
	Available when any alarm from 🗆 🕫 l (Alarm output, High limit alarm) to 🗀 l l l (Alarm output, High/Low		
	limits with standby independent alarm) is selected in [Event output EV1 allocation].		
14 14	TS1 output step number		
IIII 1	• Sets the step number at which Time signal output TS1 will be turned OFF or ON		
	during Program control.		
	(Refer to 'Time Signal Output' on p.52.)		
	Setting range: 1 to 9		
	Available only when 🗆 15 (Time signal output) is selected in [Event output EV1 allocation].		
rs if	TS1 OFF time		
00.00	Sets Time signal output TS1 OFF time.		
	(Refer to 'Time Signal Output' on p.52.)		
	• Setting range: 00:00 to 99:59 (*2)		
	Available only when 🗆 15 (Time signal output) is selected in [Event output EV1 allocation].		
[5 lo	TS1 ON time		
00.00	Sets Time signal output TS1 ON time.		
	(Refer to 'Time Signal Output' on p.52.)		
	• Setting range: 00:00 to 99:59 (*2)		
	Available only when \$\sum G !5\$ (Time signal output) is selected in [Event output EV1 allocation].		
	and desirable point follows the collection		

^(*1)The placement of the decimal point follows the selection.

^(*2) Time unit follows the selection in [Step time unit].

Characters, Factory Default	Setting Item, Function, Setting Range			
2800 000	 Event output EV2 allocation Selects Event output EV2 from the Event Output Allocation Table below. When changing Event output EV2, refer to Section "8.10 Items to be Initialized by Changing Settings" (p.98). Selection item: 			
		Event Output Allocation Table DDD No event		
		No event		
	00 i	Alarm output, High limit alarm		
	002	Alarm output, Low limit alarm		
	003	Alarm output, High/Low limits alarm		
	<u> </u>	Alarm output, High/Low limits independent alarm		
	005	Alarm output, High/Low limit range alarm		
	005	Alarm output, High/Low limit range independent alarm		
	007	Alarm output, Process high alarm		
	008	Alarm output, Process low alarm		
	009	Alarm output, High limit with standby alarm		
	□ <i>0 10</i>	Alarm output, Low limit with standby alarm		
		Alarm output, High/Low limits with standby alarm		
	□0 IZ	Alarm output, High/Low limits with standby independent alarm		
	□ <i>0 13</i>	Heater burnout alarm output		
	0 14	Loop break alarm output		
		Time signal output	Turns OFF or ON during Program control, by setting OFF and ON times within the step set in [Step number].	
	0 16	Output during AT	Turns ON during AT.	
	□ <i>0</i> 17	Pattern end output	Turns ON when Program control ends, and remains ON until turned OFF by pressing the ® key.	
	□ <i>0 18</i>	Output by communication command	Turns OFF or ON by communication command 00E4H during Serial communication. B0 EV1 output 0: OFF 1: ON B1 EV2 output 0: OFF 1: ON	
	0 19	Heating/Cooling control	Works as Control output OUT2	
	ii	relay contact output	(Heating/Cooling control).	
	Available or	nly when Event output EV2 (EV2, EV2+D□ options		
RZ ER		n value 0 Enabled/Disabled		
no	When E Selection	V2 alarm value is 0 (zero), alarm actior n item:	n can be Enabled or Disabled.	
	no	Disabled		
	4E 5	Enabled		
	Available wl	by when Event output EV2 (EV2, EV2+D \Box options then $\Box GGI$ (Alarm output, High limit alarm) to $\Box GI$ t talarm), $\Box GGI$ (Alarm output, High limit with star	005 (Alarm output, High/Low limit range ndby alarm) to □0 12 (Alarm output,	
(*1) Not available if Heat		nits with standby independent alarm) are selected ntrol (EV2+D option) is ordered.	in [Event output EV2 allocation].	

Characters, Factory Default	Setting	Item, Function, Setting Range	
R2	EV2 alarm value		
	Sets EV2 alarm value.		
	EV2 alarm value matches EV2 low limit alarm value in the following cases:		
	□□□□ (Alarm output, High/Low limits independent alarm), □□□□ (Alarm output,		
	-	ndent alarm), or $\Box \mathcal{D} \not\vdash \mathcal{C}$ (Alarm output, High/Low limits	
		arm) is selected in [Event output EV2 allocation].	
	Setting range:		
	High limit alarm	-(Input span) to Input span °C (°F) (*1) (*2)	
	Low limit alarm	-(Input span) to Input span °C (°F) (*1) (*2)	
	High/Low limits alarm	0 to Input span °C (°F) (*1) (*2)	
	High/Low limits independent	0 to Input span °C (°F) (*1) (*2)	
	alarm		
	High/Low limit range alarm	0 to Input span °C (°F) (*1) (*2)	
	High/Low limit range	0 to Input span °C (°F) (*1) (*2)	
	independent alarm		
	Process high alarm	Input range low limit to Input range high limit (*1) (*3)	
	Process low alarm	Input range low limit to Input range high limit (*1) (*3)	
	High limit with standby alarm	-(Input span) to Input span °C (°F) (*1) (*2)	
	Low limit with standby alarm	-(Input span) to Input span °C (°F) (*1) (*2)	
	High/Low limits with standby	0 to Input span °C (°F) (*1) (*2)	
	High/Low limits with standby	0 to Input span °C (°F) (*1) (*2)	
	independent alarm		
	Available only when Event output EV2 (EV2, EV2+D options) is ordered. Available when any alarm from \$\Bar{Q} \Bar{Q}\$ (Alarm output, High limit alarm) to \$\Bar{Q} \Bar{Q}\$ (Alarm output, High/Low		
	limits with standby independent alarm) is selected in [Event output EV2 allocation].		
R2H	EV2 high limit alarm value	, , ,	
	Sets EV2 high limit alarm val	ue.	
	This value is available only for the following:		
	□□□□ (Alarm output, High/Low limits independent alarm), □□□□ (Alarm output,		
	High/Low limit range independent alarm), or $\Box \mathcal{I}$ (Alarm output, High/Low limits		
	•	arm) is selected in [Event output EV2 allocation].	
	Setting range: Same as those	e of EV2 alarm value	
	Available only when Event output EV2	(EV2, EV2+D□ options) is ordered.	
BSHA	EV2 alarm hysteresis		
□□ tO	• Sets EV2 alarm hysteresis.		
	• Setting range: 0.1 to 1000.0°		
	DC voltage, current inputs: 1		
	Available only when Event output EV2 (EV2, EV2+D options) is ordered. Available when any alarm from 00 ! (Alarm output, High limit alarm) to 0 !? (Alarm output, High/Low		
	limits with standby independent alarm) is selected in [Event output EV2 allocation].		
8592	EV2 alarm delay time		
	Sets EV2 alarm action delay		
		ed after the input enters the alarm output range, the	
	alarm is activated.	and de	
	Setting range: 0 to 10000 set Available only when Event output EV2		
		(EV2, EV2+DL) opinions) is ordered. (Alarm output, High limit alarm) to \(\bigcirc \mathcal{G} \) \(\bigcirc \text{ (Alarm output, High/Low } \)	
	•	is selected in [Event output EV2 allocation].	

- $(^{\star}1)$ The placement of the decimal point follows the selection.
- (*2) For DC voltage, current inputs, the input span is the same as the scaling span.
- (*3) For DC voltage, current inputs, input range low (or high) limit value is the same as scaling low (or high) limit value.

Setting Item, Function, Setting Range EV2 alarm Energized/De-energized • Selects Energized/De-energized status for EV2 alarm. (Refer to 'EV1/EV2 Energized/De-energized' on p.50.) • Selection item:				
Selects Energized/De-energized status for EV2 alarm. (Refer to 'EV1/EV2 Energized/De-energized' on p.50.) Selection item: Dank Energized				
(Refer to 'EV1/EV2 Energized/De-energized' on p.50.) • Selection item: park Energized				
Selection item: Decil Energized				
nonL Energized				
ァモビュ De-energized				
Available only when Event output EV2 (EV2, EV2+D□ options) is ordered.				
Available when any alarm from $\square GG \mid$ (Alarm output, High limit alarm) to $\square G \mid \mathcal{E}$ (Alarm output,	High/Low			
limits with standby independent alarm) is selected in [Event output EV2 allocation].				
「トラー TS2 output step number				
• Sets the step number at which Time signal output TS2 will be turned OFF	or ON			
during Program control.				
(Refer to 'Time Signal Output' on p.52.)				
Setting range: 1 to 9				
Available only when 🗔 /5 (Time signal output) is selected in [Event output EV2 allocation].				
「トラード TS2 OFF time				
• Sets Time signal output TS2 OFF time.	Sets Time signal output TS2 OFF time.			
(Refer to 'Time Signal Output' on p.52.)	(Refer to 'Time Signal Output' on p.52.)			
• Setting range: 00:00 to 99:59 (*1)	• Setting range: 00:00 to 99:59 (*1)			
Available only when 🗔 /5 (Time signal output) is selected in [Event output EV2 allocation].				
「〜 Z a TS2 ON time				
• Sets Time signal output TS2 ON time.	Sets Time signal output TS2 ON time.			
(Refer to 'Time Signal Output' on p.52.)	(Refer to 'Time Signal Output' on p.52.)			
• Setting range: 00:00 to 99:59 (*1)				
Available only when 🖫 /5 (Time signal output) is selected in [Event output EV2 allocation].				
Heater burnout alarm 1 value				
• Sets the heater current value for Heater burnout alarm 1.				
H / and CT1 current Characters H / and CT1 current value are alternately indicated on the P\	/			
value are alternately Display.	Display.			
indicated on the PV When OUT1 is ON, the CT1 current value is updated.	When OUT1 is ON, the CT1 current value is updated.			
Display. When OUT1 is OFF, the unit memorizes the previous value when OUT1 w	When OUT1 is OFF, the unit memorizes the previous value when OUT1 was ON.			
Upon returning to set limits, the alarm will stop.				
Setting range:				
20 A: 0.0 to 20.0 A				
100 A: 0.0 to 100.0 A				
Setting to 0.0 disables the alarm.				
Not available for the direct current output type.				
Available when Heater burnout alarm (C5W, EIW, W options) is ordered.				

^(*1) Time unit follows the selection in [Step time unit].

Characters,	Setting Item, Function, Setting Range				
Factory Default				Jotting Kang	
H2		ırnout alarm 2 value			
	Sets the heater current value for Heater burnout alarm 2.				
H₽ and CT2	Available only when using 3-phase.				
current value are	Characters H≥ and CT2 current value are alternately indicated on the PV				
alternately	Display.				
indicated on the	When OUT1 is ON, the CT2 current value is updated.				
PV Display.	When OUT1 is OFF, the unit memorizes the previous value when OUT1 was ON.				
1 -7	Upon ret	urning to set limits, th	ne alarm will sto	p.	
	Setting r	ange:			
	20 A: 0.0 to 20.0 A				
	100 A: 0.	0 to 100.0 A			
	Setting to	0.0 disables the ala	rm.		
	Not availabl	e for the direct current outp	ut type.		
	Available or	lly when Heater burnout ala	rm (C5W, EIW, W op	otions) is ordered.	
LP_F	Loop brea	ak alarm time			
$\Box\Box\Box$		time to assess the Lo	•	າ.	
	Refer to	'Loop Break Alarm' o	n p.50.		
	Setting r	ange: 0 to 200 minute	es		
	Setting to	o 0 (zero) disables the	e alarm.		
LP_H	Loop brea	ak alarm span			
		temperature to asses	•	ak alarm.	
		'Loop Break Alarm' o	•		
	_	ange: 0 to 150℃ (℉)		°C (°F)	
		DC voltage, current inputs: 0 to 1500 (*1)			
	Setting to 0 (zero) disables the alarm.				
ERI I	Event input DI1 allocation				
□ <i>000</i>		Event input DI1 from	•	cation Table.	
	•	'Event Input' on p.51	.)		
	Selection				
	Event Inp	Event Input Allocation Table			
		Event input function	Input ON (Closed)	Input OFF (Open)	Remarks
		No event	(Glosca)	(Open)	
	00 /	Set value memory			
	002	Control ON/OFF	Control OFF	Control ON	Control output OFF
		Control Civion	Control Of 1	Control Oly	function
	003	Direct/Reverse	Direct	Reverse	Always effective
		action	action	action	, liways checlive
	004	Preset output 1	Preset	Usual	If sensor is burnt out,
		ON/OFF	output	control	the unit maintains
		OIN/OI I	σαιραι	CONTROL	control with the
					preset MV.
	005	Preset output 2	Preset	Usual	The unit maintains
		ON/OFF		control	control with the
		ON/OFF	output	COLLIGI	
	005	Auto/Manuel	Monuel	Automatia	preset MV.
		Auto/Manual	Manual	Automatic	Effective when
		control	control	control	Auto/Manual control
					is selected in [OUT/
(*1) The placement of t	ha daaimal nais	t follows the selection.	1	1	OFF key function].

 $^{(^{\}star}1)$ The placement of the decimal point follows the selection.

Characters, Factory Default	Setting Item, Function, Setting Range				
E81 1		Event input function	Input ON (Closed)	Input OFF (Open)	Remarks
	□ <i>001</i>	Remote/Local	Remote	Local	Effective when External setting input (EIT option) is ordered.
	008	Program control RUN/STOP	RUN	STOP	Level action when power is turned on
	□009	Program control Holding/Not holding	Holding	Not holding	Level action when power is turned on
	O 10	Program control	Advance	Usual	
		Advance function	function	control	
		Integral action	Integral	Usual	Control continues
		Holding	action	integral	with the integral
			Holding	action	value being held.
		available only when Event ir CD2, available when Serial			input (EIW, EIT, EI options) is
E8: 5	Event inp	ut DI2 allocation			
□ <i>000</i>	Selects I	Event input DI2 from	Event Input Allo	ocation Table.	
	(Refer to 'Event Input' on p.51)				
	 Selection 	n item:			
	Same as those of Event input DI1 allocation For BCS2, available only when Event input (EIW, EI option) is ordered. For BCR2/BCD2, available when Serial communication (C5W option) or Event input (EIW, EIT, EI options) is ordered.				
- CLH	External setting input high limit				
1370	Sets External setting input high limit value.				
	This value corresponds to 20 mA in direct current input.				
		Setting range: External setting input low limit to Input range high limit (*1)			
	Available only when External setting input (EIT option) is ordered.				
- TLL	External	setting input low lin	nit		
-200	• Sets Ex	ternal setting input lo	ow limit value.		
	This valu	e corresponds to 4 n	nA in direct curr	ent input.	
	Setting range: Input range low limit to External setting input high limit (*1)				
	Available only when External setting input (EIT option) is ordered.				
5-05	Transmission output type				
P8	Selects transmission output type.				
	When changing transmission output type, refer to Section "8.10 Items to be				
	Initialized by Changing Settings" (p.98).				
	Selection	n item:			
	PB	PV transmission			
	<i>५8</i> □□	SV transmission			
	Ā8⊞	MV transmission			
	<i>d8</i> □□	DV transmission			
	Available on	ly when Transmission outp	ut (EIT option) is ord	lered.	
(*1) The placement of the	ne decimal point follows the selection.				

^(*1) The placement of the decimal point follows the selection.

Characters,	Setting Item, Function, Setting Range		
Factory Default	Transmission sytuate high limit		
1370	Transmission output high limit		
ים ים	Sets the Transmission output high limit value. This is a set of the set		
	<u>-</u>	s to 20 mA in direct current output.	
	Setting range:		
	PV, SV transmission	Transmission output low limit to Input range high limit value	
	NA) / (DC voltage, current inputs: -2000 to 10000	
	MV transmission	Transmission output low limit to 105.0%	
	DV transmission	Transmission output low limit to Scaling span (*1)	
<i>r</i> , ,	•	ission output (EIT option) is ordered.	
	Transmission output		
-200		n output low limit value.	
	•	s to 4 mA in direct current output.	
	Selection item:		
	PV, SV transmission	Input range low limit to Transmission output high limit value	
		DC voltage, current inputs: -2000 to 10000	
	MV transmission	-5.0% to Transmission output high limit value	
	DV transmission	-Scaling span to Transmission output high limit value (*1)	
		ission output (EIT option) is ordered.	
<u> </u>	SV1		
	• Sets SV1.		
	Setting range: Scaling low limit to Scaling high limit (*1)		
, =,(;	Available when Control output OFF function or Auto/Manual control is selected in [OUT/OFF key function].		
<i>52</i> □□	SV2		
	• Sets SV2.		
	Setting range: Scaling low limit to Scaling high limit (*1)		
	Available for the following:		
	 When Control output OFF function or Auto/Manual control is selected in [OUT/OFF key function]. For BCS2, Event input (EIW, EIT, El options) is ordered. 		
	• For BCR2/BCD2, Serial communication (C5W option) or Event input (EIW, EIT, EI options) is ordered.		
. =	,	memory) is selected in [Event input DI1/DI2 allocation].	
\ \frac{1}{2} \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \	SV3		
	• Sets SV3.		
	Setting range: Scalin	g low limit to Scaling high limit (*1)	
	Available for the following:		
	When Control output OFF For BCS2, Event input (E)	function or Auto/Manual control is selected in [OUT/OFF key function].	
		ommunication (C5W option) or Event input (EIW, EIT, EI options) is ordered.	
	When Of Set value memory) is selected in [Event input DI1/DI2 allocation].		
54	SV4		
	• Sets SV4.		
	Setting range: Scalin	g low limit to Scaling high limit (*1)	
	Available for the following:		
		function or Auto/Manual control is selected in [OUT/OFF key function].	
	For BCS2, Event input (EFor BCR2/BCD2, Serial c	ommunication (C5W option) or Event input (EIW, EIT, EI options) is ordered.	
		memory) is selected in [Event input DI1/DI2 allocation].	

^(*1) The placement of the decimal point follows the selection.

[EV1/EV2 Energized/De-energized]

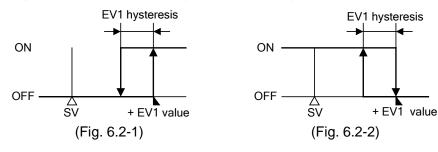
When rank (Energized) is selected, Event output 1 or 2 is conductive (ON) while the EV1/EV2 indicator is lit.

Event output 1 or 2 is not conductive (OFF) while the EV1/EV2 indicator is not lit.

When $r \not\in \exists '$ (De-energized) is selected, Event output 1 or 2 is not conductive (OFF) while the EV1/EV2 indicator is lit.

Event output 1 or 2 is conductive (ON) while the EV1/EV2 indicator is not lit.

High limit alarm (when Energized is set) High limit alarm (when De-energized is set)



EV1 value and EV1 hysteresis represent EV1 alarm value and EV1 alarm hysteresis respectively. For EV2, read "EV2" for "EV1".

[Loop Break Alarm]

When the control action is Reverse (Heating) control:

- If the PV does not **reach** the Loop break alarm span setting within the time allotted to assess the Loop break alarm (after the MV has reached 100% or the OUT high limit value), the alarm will be activated.
- Likewise, if the PV does not **drop to** the Loop break alarm span setting within the time allotted to assess the Loop break alarm (after the MV has reached 0% or the OUT low limit value), the alarm will be activated.

When the control action is Direct (Cooling) control:

- If the PV does not **drop to** the Loop break alarm span setting within the time allotted to assess the Loop break alarm (after the MV has reached 100% or the OUT high limit value), the alarm will be activated.
- Likewise, if the PV does not **reach** the Loop break alarm span setting within the time allotted to assess the Loop break alarm (after the MV has reached 0% or the OUT low limit value), the alarm will be activated.
- If Serial communication (C5W, C5 options) is added, status can be read by reading Status flag 1.

[Event Input]

If \(\sum \textsup \subset \) (Set value memory) is selected, the set value memory number will be as follows.

When only Event input DI1 is selected.

Set value memory number	SV1	SV2
DI1	Open	Closed

When only Event input DI2 is selected.

Set value memory number	SV1	SV2
DI2	Open	Closed

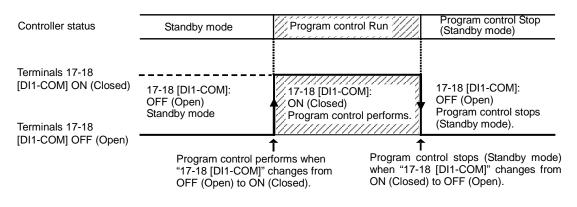
When both Event input DI1, DI2 are selected.

Set value memory number	SV1	SV2	SV3	SV4
DI1	Open	Closed	Open	Closed
DI2	Open	Open	Closed	Closed

- Preset value of \$\overline{\pi} \overline{\pi} \overline{\pi}\$ (Preset output 1 ON/OFF) and \$\overline{\pi} \overline{\pi} \overline{\pi}\$ (Preset output 2 ON/OFF) can be set in [OUT1/OUT2 MV preset value (p.77)] in Engineering mode 1.
- If \$\BBGS\$ (Preset output 2 ON/OFF) is selected in [Event input DI1 allocation], and \$\BBGS\$ (Auto/Manual control) is selected in Event input DI2 allocation, and if DI1-COM and DI2-COM terminals are turned ON (Closed) simultaneously, then Preset output 2 will be given priority, and control starts with the MV set in [OUT1/OUT2 MV preset value (p.77)] in Engineering mode 1. In this case, control will be switched to manual control, and MV cannot be changed via keypad.
- Signal edge action from OFF to ON / ON to OFF is engaged.

 If \$\sum_{\overline{\pi}} \overline{\pi}\$ (Program control RUN/STOP) is selected in [Event input DI1 allocation], the following action will be performed.

However, only when power is turned ON, Level action is engaged - which follows the input status [ON (Closed) or OFF (Open)] of Event input DI1.



(Fig. 6.2-3)

- OR calculation [if any one is ON (closed), the function activates] begins if the same functions except ☐☐☐ / (Set value memory) have been selected in [Event input DI1/DI2 allocation].

 If any terminals DI1-COM or DI2-COM is ON (closed), the function activates.
- If any function except \(\bigcup \frac{10}{10} \) (Program control Advance function) is selected in [Event input DI1/DI2 allocation], Level action is engaged when power is turned ON which follows the input status [ON (Closed) or OFF (Open)] of Event input DI1/DI2.

[Time Signal Output]

Time signal output activates during Time signal output ON time within each step (number). Time signal output ON time follows Time signal output OFF time after the program control starts.

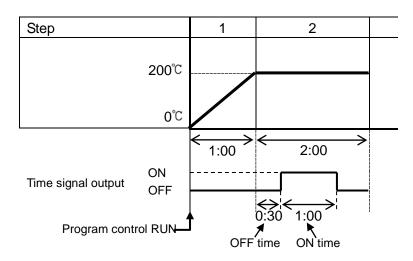
The following program pattern shows that the temperature rises to 200°C for 1 hour, and stays at 200°C for 2 hours after Program control starts.

Step	1	2
Step SV	200℃	200℃
Step time	1:00	2:00

Time signal output (Fig. 6.2-4) is shown when set as follows.

• TS1/TS2 output step number: 2

TS1/TS2 OFF time: 0:30TS1/TS2 ON time: 1:00



(Fig. 6.2-4)

Time signal output is effective within the step set in [TS1/TS2 output step number]. For example, if TS1/TS2 ON time is set to "2:00" at the above, Time signal output is turned OFF at the moment when Step 2 is completed.

7. Settings

In this section, Main setting mode, Sub setting mode, Engineering mode 1 and Engineering mode 2 will be explained.

7.1 Main Setting Mode

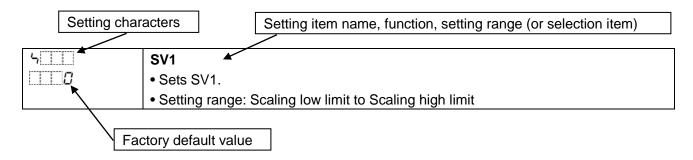
To enter Main setting mode, press the O key in RUN mode.

Use the \wedge or \vee key for settings (or selections).

To register the set data, use the Q key.

Explanation of setting items:

- Upper left: PV Display: Indicates setting characters.
- Lower left: SV Display: Indicates factory default value.
- Right side: Indicates the setting item, explanation of its function and setting range (or selection item).



Depending on the selection in [OUT/OFF key function], corresponding item is indicated.

When 'Control output OFF function' or 'Auto/Manual control' is selected in [OUT/OFF key function]:

Characters, Factory Default	Setting Item, Function, Setting Range
4	SV1
	• Sets SV1.
	Corresponds to [SV1] in Initial setting mode.
	Setting range:
	Scaling low limit to Scaling high limit (*1)
52 00	SV2 (*2)
\Box \Box \Box \Box	• Sets SV2.
	Corresponds to [SV2] in Initial setting mode.
	Setting range:
	Scaling low limit to Scaling high limit (*1)
<i>53</i> □□	SV3 (*2)
\square \square \square	• Sets SV3.
	Corresponds to [SV3] in Initial setting mode.
	Setting range:
	Scaling low limit to Scaling high limit (*1)
44 T	SV4 (*2)
\square \square \square	• Sets SV4.
	Corresponds to [SV4] in Initial setting mode.
	Setting range:
	Scaling low limit to Scaling high limit (*1)

^(*1) The placement of the decimal point follows the selection.

Available for the following:

- For BCS2, when Event input (EIW, EI option) is ordered
- For BCR2/BCD2, when Serial communication (C5W option) or Event input (EIW, EIT, EI option) is ordered.
- When \$\Bigcap GG \forall \text{ (Set value memory) is selected in [Event input DI1/DI2 allocation]}

When 'Program control' is selected in [OUT/OFF key function]:

Characters, Factory Default	Setting Item, Function, Setting Range
5	Step 1 SV
	Sets Step 1 SV.
	Setting range:
	Scaling low limit to Scaling high limit (*1)
Γ□_ <i>1</i>	Step 1 time
0000	Sets Step 1 time.
	Setting range:
	======, or 00:00 to 99:59
	If is set, Step 1 time will be held, and Fixed value control will be performed
	using Step 1 SV.
ū□_ /	Step 1 wait value
	Sets Step 1 wait value.
	Setting range:
	0 to 20% of input span
	DC voltage, current inputs: 0 to 20% of scaling span (*1)
	Setting the value to 0 disables this Wait function.

 $^{(^{\}star}1)$ The placement of the decimal point follows the selection.

^(*2) When GGG ! (Set value memory) is selected in [Event input DI1 allocation] or [Event input DI2 allocation], SV1 and SV2 can be set.

When GGG ! (Set value memory) is selected in both [Event input DI1 allocation] and [Event input DI2 allocation], SV1, SV2, SV3 and SV4 can be set.

Characters, Factory Default	Setting Item, Function, Setting Range
42 III	Step 2 SV
	Sets Step 2 SV.
	Setting range:
	Scaling low limit to Scaling high limit (*1)
[Step 2 time
00.00	• Sets Step 2 time.
	• Setting range: [=]=]=], or 00:00 to 99:59
	If EIII is set, Step 2 time will be held, and Fixed value control will be performed
	using Step 2 SV.
<u>5</u> □_2	Step 2 wait value
	• Sets Step 2 wait value.
	• Setting range:
	0 to 20% of input span
	DC voltage, current inputs: 0 to 20% of scaling span (*1)
	Setting the value to 0 disables this Wait function.
53 <u></u>	Step 3 SV
	• Sets Step 3 SV.
	Setting range:
	Scaling low limit to Scaling high limit (*1)
Γ□_ 3	Step 3 time
00.00	• Sets Step 3 time.
	• Setting range:
	[= = = , or 00:00 to 99:59
	If is set, Step 3 time will be held, and Fixed value control will be performed
	using Step 3 SV.
	Step 3 wait value • Sets Step 3 wait value.
:	Setting range:
	0 to 20% of input span
	DC voltage, current inputs: 0 to 20% of scaling span (*1)
	Setting the value to 0 disables this Wait function.
44	Step 4 SV
$\Box \Box \Box \Box$	Sets Step 4 SV.
	Setting range:
	Scaling low limit to Scaling high limit (*1)
Γ <u></u> _4	Step 4 time
00.00	• Sets Step 4 time.
	• Setting range:
	FIFTER is not Stop 4 time will be held, and Fixed value control will be neglected.
	If is set, Step 4 time will be held, and Fixed value control will be performed
	using Step 4 SV.

^(*1) The placement of the decimal point follows the selection.

Characters, Factory Default	Setting Item, Function, Setting Range
J Y	Step 4 wait value
	Sets Step 4 wait value.
	Setting range:
	0 to 20% of input span
	DC voltage, current inputs: 0 to 20% of scaling span (*1)
	Setting the value to 0 disables this Wait function.
45	Step 5 SV
\Box \Box \Box	Sets Step 5 SV.
	Setting range:
	Scaling low limit to Scaling high limit (*1)
<i>「</i> □_5	Step 5 time
0000	Sets Step 5 time.
	Setting range:
	-i-i-i-, or 00:00 to 99:59
	If is set, Step 5 time will be held, and Fixed value control will be performed
	using Step 5 SV.
J□_ 5	Step 5 wait value
	Sets Step 5 wait value.
	Setting range:
	0 to 20% of input span
	DC voltage, current inputs: 0 to 20% of scaling span (*1)
	Setting the value to 0 disables this Wait function.
48 □□	Step 6 SV
	Sets Step 6 SV.
	Setting range:
	Scaling low limit to Scaling high limit (*1)
Γ🗆 _ 6	Step 6 time
0000	Sets Step 6 time.
	• Setting range:
	=====, or 00:00 to 99:59
	If initial is set, Step 6 time will be held, and Fixed value control will be performed
	using Step 6 SV.
<u> </u>	Step 6 wait value
	Sets Step 6 wait value.
	Setting range:
	0 to 20% of input span
	DC voltage, current inputs: 0 to 20% of scaling span (*1)
, -,,,	Setting the value to 0 disables this Wait function.
57 <u> </u>	Step 7 SV
	• Sets Step 7 SV.
	Setting range:
	Scaling low limit to Scaling high limit (*1)

^(*1) The placement of the decimal point follows the selection.

Characters, Factory Default	Setting Item, Function, Setting Range
7_7	Step 7 time
0000	Sets Step 7 time.
	Setting range:
	[= = =], or 00:00 to 99:59
	If is set, Step 7 time will be held, and Fixed value control will be performed
	using Step 7 SV.
	Step 7 wait value
	Sets Step 7 wait value. Setting range:
	• Setting range:
	0 to 20% of input span DC voltage, current inputs: 0 to 20% of scaling span (*1)
	Setting the value to 0 disables this Wait function.
48III	Step 8 SV
	• Sets Step 8 SV.
	Setting range:
	Scaling low limit to Scaling high limit (*1)
Γ <u></u> _8	Step 8 time
0000	Sets Step 8 time.
	Setting range:
	=====, or 00:00 to 99:59
	If is set, Step 8 time will be held, and Fixed value control will be performed
	using Step 8 SV.
<u>J</u>	Step 8 wait value
	• Sets Step 8 wait value.
	• Setting range:
	0 to 20% of input span
	DC voltage, current inputs: 0 to 20% of scaling span (*1) Setting the value to 0 disables this Wait function.
<i>59</i> □□	Step 9 SV
	• Sets Step 9 SV.
:iii	• Setting range:
	Scaling low limit to Scaling high limit (*1)
Γ <u></u> 9	Step 9 time
0000	• Sets Step 9 time.
	Setting range:
	======, or 00:00 to 99:59
	If First is set, Step 9 time will be held, and Fixed value control will be performed
	using Step 9 SV.
<u> </u>	Step 9 wait value
	• Sets Step 9 wait value.
	• Setting range:
	0 to 20% of input span
	DC voltage, current inputs: 0 to 20% of scaling span (*1)
	Setting the value to 0 disables this Wait function. the decimal point follows the selection

^(*1) The placement of the decimal point follows the selection.

7.2 Sub Setting Mode

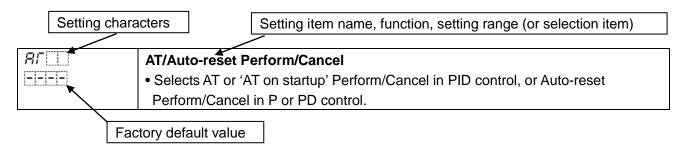
To enter Sub setting mode, press the \wedge and \circ keys (in that order) together in RUN mode.

Use the \wedge or \vee key for settings (or selections).

To register the set data, use the \(\mathbb{O} \) key.

Explanation of setting items:

- Upper left: PV Display: Indicates setting characters.
- Lower left: SV Display: Indicates factory default value.
- Right side: Indicates the setting item, explanation of its function and setting range (or selection item).



Characters,	Setting Item, Function, Setting Range		
Factory Default	AT/A to wood Defend Occasi		
[-i-i-i-i	AT/Auto-reset Perform/Cancel		
	Selects AT or 'AT on startup' Perform/Cancel in PID control action, or Auto-reset		
	Perform/Cancel in P or PD control action.		
	Refer to Sections '8.5 Setting PID Constants (by Performing AT)' (p. 84), and		
	'8.6 Performing Auto-reset' (p. 87).		
	• Selection item:		
	EIIII AT/AT on startup/Auto-reset Cancel		
	AT Perform		
	パート 'AT on startup' Perform		
	ートE「 Auto-reset Perform		
	Not available for ON/OFF control or PI control.		
P	OUT1 proportional band		
□□ ID	Sets OUT1 proportional band.		
	• Setting range: 0 to input span [°] C (°F)		
	Thermocouple, RTD input without decimal point: 0 to input span℃ (℉)		
	Thermocouple, RTD input with decimal point: 0.0 to input span℃ (℉)		
	DC voltage, current inputs: 0.0 to 1000.0%		
	OUT1 becomes ON/OFF control when set to 0 or 0.0.		
;	Integral time		
200	Sets the integral time.		
	Auto-reset can be performed when PD is control action (I = 0).		
	Setting range: 0 to 3600 seconds		
	Setting the value to 0 disables integral action.		
	Not available if OUT1 is in ON/OFF control.		
	Derivative time		
□□5 <i>0</i>	Sets the derivative time.		
	Setting range: 0 to 1800 seconds		
	Setting the value to 0 disables derivative action.		
	Not available if OUT1 is in ON/OFF control.		

Characters,	Setting Item, Function, Setting Range
Factory Default	ARW
50	
	Sets ARW (anti-reset windup). Setting range: 0 to 100%
	Setting range: 0 to 100% A stitute set as 0.0774 is in RIB sector.
-585	Available only when OUT1 is in PID control.
	Manual reset
iiiiiiii	Sets the reset value manually. If outs reset is executed, the reset value will be sutematically set.
	If auto-reset is executed, the reset value will be automatically set.
	• Setting range: ±Proportional band value
	If a value larger than 100.0% is set in [OUT1 proportional band], the setting range
	will be ±100.0.
<u>c</u>	Available when OUT1 is in P or PD control.
	OUT1 proportional cycle
Factory default:	Sets proportional cycle for OUT1.
Relay contact	For relay contact output, if the proportional cycle time is decreased, the frequency
output: 30 sec.	of the relay action increases, and the life of the relay contact is shortened.
Non-contact voltage	Setting range: 0.5, or 1 to 120 seconds
output: 3 sec.	Not available for direct current output type, or if OUT1 is in ON/OFF control.
HY50	OUT1 ON/OFF hysteresis
	• Sets ON/OFF hysteresis for OUT1.
	• Setting range: 0.1 to 1000.0°C (°F),
	DC voltage, current inputs: 1 to 10000 (*1)
, ,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,	Available only when OUT1 is in ON/OFF control.
oLHO	OUT1 high limit
□ <i>100</i>	• Sets OUT1 high limit value.
	• Setting range: OUT1 low limit value to 100%
	(Direct current output type: OUT1 low limit value to 105%)
	Not available if OUT1 is relay contact output type or non-contact voltage output type, and if OUT1 is in
, , [7]	ON/OFF control.
ell o	OUT1 low limit
	Sets OUT1 low limit value. Catting and 200 to OUT4 high limit value.
	• Setting range: 0% to OUT1 high limit value
	(Direct current output type: -5% to OUT1 high limit value)
	Not available if OUT1 is relay contact output type or non-contact voltage output type, and if OUT1 is in
or8f	ON/OFF control.
	OUT1 rate-of-change
iiiiiiiii	• Sets changing value of OUT1 MV for 1 second.
	See 'OUT1 rate-of-change' on p. 63.
	• Setting range: 0 to 100 %/second
	Setting the value to 0 disables this function.
(+4) Ti	Not available if OUT1 is in ON/OFF control. the decimal point follows the selection.

^(*1) The placement of the decimal point follows the selection.

Characters,	Setting Item, Function, Setting Range
Factory Default	OUT2 cooling method
8: -	Selects OUT2 cooling method from air, oil or water cooling.
/// / []	Selects OO12 cooling method from all, of or water cooling.
	OUT2 proportional band
	Air cooling
	Oil cooling Water cooling
	SV
	(Fig. 7.2-1)
	• Selection item:
	Air cooling (linear characteristics)
	Oil cooling (1.5th power of the linear characteristics)
	<i>ūRF</i> Water cooling (2nd power of the linear characteristics)
	Available when Heating/Cooling control [DS, DA, EV2(*1), EV2+D□ options] is ordered. Not available if OUT1 is in ON/OFF control or if OUT2 is in ON/OFF control.
P_6	OUT2 proportional band
	Sets the proportional band for OUT2.
	Setting range:
	Thermocouple, RTD input without decimal point: 0 to Input span °C (°F)
	Thermocouple, RTD input with decimal point: 0.0 to Input span $^{\circ}$ C ($^{\circ}$ F)
	DC voltage, current inputs: 0.0 to 1000.0%
	When set to 0 or 0.0, OUT2 becomes ON/OFF control, and the item selected in
	[OUT2 cooling method] will be disabled.
	Available when Heating/Cooling control [DS, DA, EV2(*1), EV2+D□ option] is ordered.
	Not available if OUT1 is in ON/OFF control.
c_6	OUT2 proportional cycle
□□3 <i>0</i>	Sets proportional cycle for OUT2.
Factory default:	For relay contact output, if the proportional cycle time is decreased, the frequency
EV2(*2), EV2+DR: 30 sec.	of the relay action increases, and the life of the relay contact is shortened.
DS: 3 sec.	Setting range: 0.5, or 1 to 120 seconds
	Available when Heating/Cooling control [DS, DA, EV2(*1), EV2+D□] is ordered.
	Not available if OUT1 is in ON/OFF control, OUT2 is in ON/OFF control or OUT2 is direct current output type.
HY56	OUT2 ON/OFF hysteresis
□□ <i>lD</i>	Sets ON/OFF hysteresis for OUT2.
	• Setting range: 0.1 to 1000.0°C (°F),
	DC voltage, current inputs: 1 to 10000 (*2)
	Available when Heating/Cooling control [DS, DA, EV2(*1), EV2+D option] is ordered.
oL Hb	Available when OUT2 is in ON/OFF control. OUT2 high limit
0.70	OUT2 high limit • Sets OUT2 high limit value.
100	Setting range: OUT2 low limit value to 100%
	(Direct current output type: OUT2 low limit value to 105%)
	Available when Heating/Cooling control [DS, DA, EV2(*1), EV2+D□] is ordered.
	Not available if OUT2 is relay contact output type or non-contact voltage output type and OUT1 is in ON/OFF
	control.
	Not available if OUT2 is relay contact output type or non-contact voltage output type and OUT2 is in ON/OFF
(*1) When [7] 19 (He	control.

^(*1) When 🗆 15 (Heating/Cooling control relay contact output) is selected in [Event output EV2 allocation]}.

^(*2) The placement of the decimal point follows the selection.

Characters,		Settina	Item, Function, Setting Range
Factory Default			3 3
0116	OUT2 low I		
	Sets OUT2 low limit value.		
	 Setting rar 	nge: 0% to OUT2 h	
	Not available i control.	n Heating/Cooling control f OUT2 is relay contact of	t output type: -5% to OUT2 high limit value) of [DS, DA, EV2(*1), EV2+D] is ordered. output type or non-contact voltage output type and OUT1 is in ON/OFF output type or non-contact voltage output type and OUT2 is in ON/OFF
db	control.		
	Overlap/De		ad band for OUT1 and OUT2.
		veriap band of dea ie: Dead band	ad balld for OOTT alld OOTZ.
		e: Overlap band	
		nge: -200.0 to 200.0	°C (°F)
	1	e, current inputs: -2	
	_	•	DI [DS, DA, EV2(*1), EV2+D□] is ordered.
conf	Direct/Reve		1, [50, 51, Ev2(1), Ev2150] is ordered.
HERE			ting) or Direct (Cooling) control action.
	HERF	Reverse (Heatin	
	cool	Direct (Cooling)	· .
8 (EV1 alarm	•	40
		alarm value.	
kk	Corresponds to [EV1 alarm value] in Initial setting mode.		
		-	/1 low limit alarm value in the following cases:
	Output, High/Low limit range independent alarm), or U (Alarm output, High/Low limits with standby independent alarm) is selected in [Event output EV1]		
	allocation].	,
	Setting rar	rge:	
	High limit al	arm	-(Input span) to Input span °C (°F) (*2) (*3)
	Low limit ala	arm	-(Input span) to Input span °C (°F) (*2) (*3)
	High/Low lir	nits alarm	0 to Input span °C (°F) (*2) (*3)
	High/Low lir	nits independent	0 to Input span °C (°F) (*2) (*3)
	alarm		
	High/Low lir	nit range alarm	0 to Input span °C (°F) (*2) (*3)
	High/Low lir	nit range	0 to Input span °C (°F) (*2) (*3)
	independen	t alarm	
	Process hig	h alarm	Input range low limit to Input range high limit (*2) (*4)
	Process low	alarm	Input range low limit to Input range high limit (*2) (*4)
	High limit w	th standby alarm	-(Input span) to Input span °C (°F) (*2) (*3))
		th standby alarm	-(Input span) to Input span °C (°F) (*2) (*3)
	High/Low lir	nits with standby	0 to Input span °C (°F) (*2) (*3)
	alarm		
	High/Low lir	nits with standby	0 to Input span °C (°F) (*2) (*3)
	independen		
		•	(Alarm output, High limit alarm) to 🔯 🔁 (Alarm output, High/Low
		dby independent alarm)	is selected in [Event output EV1 allocation].

^(*1) When $\Box \mathcal{G}$ (Heating/Cooling control relay contact output) is selected in [Event output EV2 allocation] (*2) The placement of the decimal point follows the selection.

^(*3) For DC voltage, current inputs, the input span is the same as the scaling span.

^(*4) For DC voltage, current inputs, input range low (or high) limit value is the same as scaling low (or high) limit value.

Characters,	Setting Item, Function, Setting Range
Factory Default	EV1 high limit alarm value
	Sets EV1 high limit alarm value.
:i	This value is available only for the following:
	□□□□□□□□□□□□□□□□□□□□□□□□□□□□□□□□□□□□□
	output, High/Low limit range independent alarm), or \$\overline{\mathcal{G}} \forall \overline{\mathcal{E}}\$ (Alarm output,
	High/Low limits with standby independent alarm) is selected in [Event output EV1]
	allocation].
	Corresponds to [EV1 high limit alarm value] in Initial setting mode.
	Setting range: Same as those of EV1 alarm value
82	EV2 alarm value
	Sets EV2 alarm value.
	Corresponds to [EV2 alarm value] in Initial setting mode.
	EV2 alarm value matches EV2 low limit alarm value in the following cases:
	□□□Ч (Alarm output, High/Low limits independent alarm), □□□□ (Alarm
	output, High/Low limit range independent alarm), or ☐☐ /ट (Alarm output
	High/Low limits with standby independent alarm) is selected in [Event output EV2
	allocation].
	Setting range: Same as those of EV1 alarm value
	Available when Event output EV2 (EV2, EV2+D) is ordered.
	Available only when $\square GG$ (Alarm output, High limit alarm) to $\square G$ (Alarm output, High/Low limits with
	standby independent alarm) is selected in [Event output EV2 allocation].
R2H	EV2 high limit alarm value
	Sets EV2 high limit alarm value.
	This value is available only for the following:
	□□□□□ (Alarm output, High/Low limits independent alarm), □□□□ (Alarm
	output, High/Low limit range independent alarm), or 🔲 🗗 (Alarm output,
	High/Low limits with standby independent alarm) is selected in [Event output EV2
	allocation].
	Corresponds to [EV2 high limit alarm value] in Initial setting mode.
	 Setting range: Same as those of EV1 alarm value Available when Event output EV2 (EV2, EV2+D□) is ordered.
H (Heater burnout alarm 1 value
	Sets the heater current value for Heater burnout alarm 1.
	Corresponds to [Heater burnout alarm 1 value] in Initial setting mode.
H I and CT1	Characters H I and CT1 current value are indicated alternately on the PV Display.
current value are	When OUT1 is ON, the CT1 current value is updated.
alternately indicated	When OUT1 is OFF, the unit memorizes the previous value when OUT1 was ON.
on the PV Display.	Upon returning to set limits, the alarm will stop.
	• Setting range:
	20 A: 0.0 to 20.0 A
	100 A: 0.0 to 100.0 A
	Setting to 0.0 disables the alarm.
	Not available for direct current output type.
	Available only when Heater burnout alarm (C5W, EIW, W options) is ordered.

Characters, Factory Default	Setting Item, Function, Setting Range
H2[[[Heater burnout alarm 2 value
	Sets the heater current value for Heater burnout alarm 2.
H⋛ and CT2	Available only when using 3-phase.
current value are	Corresponds to [Heater burnout alarm 2 value] in Initial setting mode.
alternately	Characters H₽ and CT2 current value are indicated alternately on the PV
indicated on the	Display.
PV Display.	When OUT1 is ON, the CT2 current value is updated.
	When OUT1 is OFF, the unit memorizes the previous value when OUT1 was ON.
	Upon returning to set limits, the alarm will stop.
	Setting range:
	20 A: 0.0 to 20.0 A
	100 A: 0.0 to 100.0 A
	Setting to 0.0 disables the alarm.
	Not available for direct current output type.
	Available only when Heater burnout alarm (C5W, EIW, W options) is ordered.
LP_F	Loop break alarm time
	Sets the time to assess the Loop break alarm.
	Corresponds to [Loop break alarm time] in Initial setting mode.
	Refer to 'Loop Break Alarm' on p.50.
	• Setting range: 0 to 200 minutes
LP_H	Setting to 0 (zero) disables the alarm.
,	Loop break alarm spanSets the temperature to assess the Loop break alarm.
	Corresponds to [Loop Break alarm span] in Initial setting mode.
	Refer to 'Loop Break Alarm' on p.50.
	Setting range:
	Thermocouple, RTD input without decimal point: 0 to 150°C (°F)
	Thermocouple, RTD input with decimal point: 0.0 to 150.0°C (°F)
	DC voltage, current inputs: 0 to 1500 (*1)
	Setting to 0 (zero) disables the alarm.
/*1) The placement of t	he desired point follows the colection

^(*1) The placement of the decimal point follows the selection.

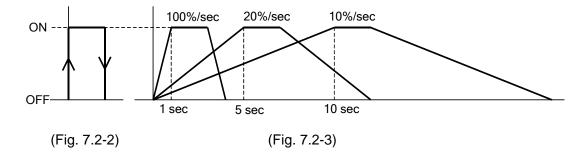
[OUT1 rate-of-change]

For Heating control, if PV is lower than SV, the output is generally turned from OFF to ON as shown in (Fig. 7.2-2).

If OUT1 rate-of-change is set, the output can be changed by the rate-of-change (Fig. 7.2-3).

This control is suitable for high temperature heaters (which are made from molybdenum, tungsten or platinum, etc., and used at approx. 1500 to 1800°C) which are easily burnt out from turning on electricity rapidly.

Usual output Output when Output rate-of-change is set



7.3 Engineering Mode 1

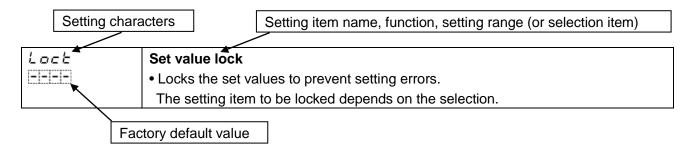
To enter Engineering mode 1, press and hold the \wedge and \vee keys (in that order) together for 3 seconds in RUN mode.

Use the \wedge or \vee key for settings (or selections).

To register the set data, use the Q key.

Explanation of setting items:

- Upper left: PV Display: Indicates setting characters.
- Lower left: SV Display: Indicates factory default value.
- Right side: Indicates the setting item, explanation of its function and setting range (or selection item).



Characters, Factory Default	Setting Item, Function, Setting Range			
Lock	Set valu	e lock		
[-]-[-]-	• Locks t	he set va	lues to prevent setting errors.	
	The se	tting item	to be locked depends on the select	tion.
	Selection	on item:		
			Change via Keypad	Change via Software Communication
		Unlock	All set values can be changed.	All set values can be
	Loci	Lock 1	None of the set values can be	changed.
			changed.	
	Loc2	Lock 2	In Fixed value control, only SV	
			and Alarm value can be changed.	
			In Program control, Step SV,	
			Step time and Alarm value can	
			be changed.	
	Loc3	Lock 3	All set values can be changed.	Setting items – except Input
	Loc4	Lock 4	None of the set values can be	type, Controller/Converter –
			changed.	can be changed temporarily
	Locs	Lock 5	In Fixed value control, only SV	via software communication.
			and Alarm value can be changed.	However, if power is turned
			In Program control, Step SV,	ON again, the setting values
			Step time and Alarm value can	revert to the values before
			be changed.	Lock 3, 4 or 5 was selected.

Characters, Factory Default	Setting Item, Function, Setting Range				
EBI I	Event input DI1 allocation				
000	Selects Event input DI1 from the Event Input Allocation Table.				
		onds to [Event inpu	•		
	Selection		. 211 a	i i i i i i i i i i i i i i i i i i	000.
		put Allocation Tab	le		
		Event input	Input ON	Input OFF	Remarks
		function	(Closed)	(Open)	
		No event			
	00 I	Set value memory		0	0
	□ <i>002</i>	Control ON/OFF	Control OFF	Control ON	Control output OFF function
	003	Direct/Reverse	Direct	Reverse	Always effective
		action	action	action	
	004	Preset output 1 ON/OFF	Preset output	Usual control	If sensor is burnt out, the unit maintains control
	005	Preset output 2 ON/OFF	Preset output	Usual control	with the preset MV. The unit maintains control with the preset MV.
	□006	Auto/Manual control	Manual control	Automatic control	Effective when Auto/Manual control is selected in [OUT/ OFF key function].
	007	Remote/Local	Remote	Local	Effective when External setting input (EIT option) is ordered.
	□008	Program control RUN/STOP	RUN	STOP	Level action when power is turned on
	009	Program control Holding/ Not holding	Holding	Not holding	Level action when power is turned on
	□ <i>0 10</i>	Program control Advance function	Advance function	Usual control	
	□ <i>0</i>	Integral action holding	Integral action holding	Usual integral action	Control continues with the integral value being held.
		available only when Ever /BCD2, available when Se			put (EIW, EIT, EI options) is
ER! 5	Event in	put DI2 allocation			
□000	Selects	Event input DI2 from	m the Event Inpu	t Allocation Table	
	Corresp	onds to [Event inpu	t DI2 allocation] i	in Initial setting m	ode.
	For BCS2	on item: Same as Eva available only when Even /BCD2, available when Se	it input (EIW, EI option	ns) is ordered.	put (EIW, EIT, EI options) is

Characters, Factory Default	Setting Item, Function, Setting Range		
E80 1	Event output EV1 allocation		
000		Event output EV1 from the Event Output Allocation Table below.	
	Corresponds to [Event output EV1 allocation] in Initial setting mode.		
	When changing Event output EV1 allocation, refer to Section "8.10 Items to be		
	Initialized by Changing Settings" (p.98).		
	• Selection item:		
	Event Output Allocation Table		
	000	No event	
	00 I	Alarm output, High limit alarm	
	002	Alarm output, Low limit alarm	
	003	Alarm output, High/Low limits alarm	
	004	Alarm output, High/Low limits	
		independent alarm	
	005	Alarm output, High/Low limit range	
		alarm	
	005	Alarm output, High/Low limit range	
		independent alarm	
	□007	Alarm output, Process high alarm	
	008	Alarm output, Process low alarm	
	009	Alarm output, High limit with standby	
	□0 IO	Alarm output, Low limit with standby	
		Alarm output, High/Low limits with standby alarm	
	0 12	Alarm output, High/Low limits	
		with standby independent alarm	
	□0 I3	Heater burnout alarm output	
	□0 14	Loop break alarm output	
	□0 IS	Time signal output	Turns OFF or ON during Program
			control, by setting OFF time and
			ON time within the step set in
		<u> </u>	[Step number].
	0 15	Output during AT	Turns ON during AT.
	רו ם	Pattern end output	Turns ON when Program control ends, and remains ON until turned
			OFF by pressing the @ key.
	O 18	Output by communication	Turns OFF or ON by communication
		command	command 00E4H during Serial
		Sommand	communication.
			B0 EV1 output 0: OFF
			1: ON
			B1 EV2 output 0: OFF
0.170	-		1: ON
A 15A	EV1 alarm value 0 Enabled/Disabled		
no		V1 alarm value is 0 (zero), alarm action	
		onds to [EV1 alarm value 0 Enabled/Di	isabled] in initial setting mode.
	• Selectio		
	9640	Disabled	
		Enabled hen □00 / (Alarm output, High limit alarm) to □0	305 (Alarm output High/Low limit range
		then $\Box BBF$ (Alarm output, High limit alarm) to $\Box C$	
		mits with standby independent alarm) are selected	

Characters,	Setting	Item, Function, Setting Range		
Factory Default		3 3		
8 (EV1 alarm value			
	Sets EV1 alarm value.			
	Corresponds to [EV1 alarm value] in Initial setting mode.			
	EV1 alarm value matches EV1 low limit alarm value in the following cases:			
		h/Low limits independent alarm), \$\instructure{\Omega}\overline{\Omega}\ov		
	_	e independent alarm), or 🔟 🗗 (Alarm output,		
	High/Low limits with standby independent alarm) is selected in [Event output EV1			
	allocation].			
	Setting range: High limit plans	(Input apon) to Input apon °C (°E) (ta) (ta)		
	High limit alarm	-(Input span) to Input span °C (°F) (*1) (*2)		
	Low limit alarm	-(Input span) to Input span °C (°F) (*1) (*2)		
	High/Low limits alarm	0 to Input span °C (°F) (*1) (*2)		
	High/Low limits independent alarm	0 to Input span °C (°F) (*1) (*2)		
	High/Low limit range alarm	0 to Input span °C (°F) (*1) (*2)		
	High/Low limit range	0 to Input span °C (°F) (*1) (*2)		
	independent alarm	o to input span \circ (1)(1)(2)		
	Process high alarm	Input range low limit to Input range high limit (*1) (*3)		
	Process low alarm	Input range low limit to Input range high limit (*1) (*3)		
	High limit with standby alarm	-(Input span) to Input span °C (°F) (*1) (*2)		
	Low limit with standby alarm	-(Input span) to Input span °C (°F) (*1) (*2)		
	High/Low limits with standby	0 to Input span °C (°F) (*1) (*2)		
	alarm			
	High/Low limits with standby	0 to Input span [°] C (°F) (*1) (*2)		
	independent alarm			
	Available when any alarm from \$\Bar{\tau} \Bar{\tau}\$	l (Alarm output, High limit alarm) to □□ l≥ (Alarm output, High/Low		
		is selected in [Event output EV1 allocation].		
A IH	EV1 high limit alarm value			
	• Sets EV1 high limit alarm val			
	This value is available only for			
	` ' '	h/Low limits independent alarm), $\square \square \square$		
		je independent alarm), 🔲 🗗 (Alarm output,		
		by independent alarm) is selected in [Event output EV1		
	allocation].	nit alarm value] in Initial setting mode.		
	Setting range: Same as thos			
A IHY	EV1 alarm hysteresis	o or E v r diami value		
ÜÜÜ	Sets EV1 alarm hysteresis.			
	<u> </u>	nysteresis] in Initial setting mode.		
	• Setting range: 0.1 to 1000.0°	•		
	DC voltage, current inputs: 1			
	Available when any alarm from \$\Bigcit \mathcal{O} \Bigcit\$	l (Alarm output, High limit alarm) to ☐☐ 12 (Alarm output, High/Low		
	limits with standby independent alarm)	is selected in [Event output EV1 allocation].		

^(*1) The placement of the decimal point follows the selection.

^(*2) For DC voltage, current inputs, the input span is the same as the scaling span.

^(*3) For DC voltage, current inputs, input range low (or high) limit value is the same as scaling low (or high) limit value.

Characters,	Setting Item, Function, Setting Range		
Factory Default			
8 189	EV1 alarm delay time		
	Sets EV1 alarm action delay time. Correspondents [EV4 plants delay times] in Initial patting made.		
	Corresponds to [EV1 alarm delay time] in Initial setting mode.		
	When setting time has elapsed after the input enters the alarm output range, the alarm is activated.		
	Setting range: 0 to 10000 seconds		
	Available when any alarm from $\square GG \mid$ (Alarm output, High limit alarm) to $\square G \mid Z$ (Alarm output, High/Low	v	
	limits with standby independent alarm) is selected in [Event output EV1 allocation].	•	
A ILA	EV1 alarm Energized/De-energized		
noñL	• Selects Energized/De-energized status for EV1 alarm.		
	Corresponds to [EV1 alarm Energized/De-energized] in Initial setting mode.		
	(Refer to 'EV1/EV2 Energized/De-energized' on p.50.)		
	• Selection item:		
	nont Energized		
	r E 出っ De-energized		
	Available when any alarm from $\square GG \mid$ (Alarm output, High limit alarm) to $\square G \mid Z$ (Alarm output, High/Low	v	
	limits with standby independent alarm) is selected in [Event output EV1 allocation].	•	
<i>[5]</i>	TS1 output step number		
1	• Sets the step number for which Time signal output TS1 is turned OFF or ON		
	during Program control.		
	Corresponds to [TS1 output step number] in Initial setting mode.		
	• Setting range: 1 to 9		
	Available only when 🗆 15 (Time signal output) is selected in [Event output EV1 allocation].		
rh IF	TS1 OFF time		
00.00	• Sets Time signal output TS1 OFF time.		
	Corresponds to [TS1 OFF time] in Initial setting mode.		
	• Setting range: 00:00 to 99:59 (*1)		
	Available only when 🗆 15 (Time signal output) is selected in [Event output EV1 allocation].		
[5 10	TS1 ON time		
0000	Sets Time signal output TS1 ON time.		
	Corresponds to [TS1 ON time] in Initial setting mode.		
	• Setting range: 00:00 to 99:59 (*1)		
	Available only when 🗆 15 (Time signal output) is selected in [Event output EV1 allocation].		

^(*1) Time unit follows the selection in [Step time unit].

Characters, Factory Default	Setting Item, Function, Setting Range		
E802	Event output EV2 allocation		
000	Selects Event output EV2 from the Event Output Allocation Table below.		
	Corresponds to [Event output EV2 allocation] in Initial setting mode.		
	• When cl	nanging Event output EV2, refer to Sec	ction "8.10 Items to be Initialized
	by Chan	ging Settings" (p.98).	
	Selection item:		
	Event Output Allocation Table		
		No event	
	□00 I	Alarm output, High limit alarm	
	002	Alarm output, Low limit alarm	
	003	Alarm output, High/Low limits alarm	
	004	Alarm output, High/Low limits	
		independent alarm	
	005	Alarm output, High/Low limit range	
		alarm	
	005	Alarm output, High/Low limit range	
		independent alarm	
	<u> </u>	Alarm output, Process high alarm	
	008	Alarm output, Process low alarm	
	009	Alarm output, High limit with	
		standby alarm	
	□ <i>0 10</i>	Alarm output, Low limit with	
		standby alarm	
		Alarm output, High/Low limits	
	0 12	with standby alarm Alarm output, High/Low limits	
	<i>u 1</i>	with standby independent alarm	
	O 13	Heater burnout alarm output	
	0 14	Loop break alarm output	
	O 15	Time signal output	Turns OFF or ON during Program
			control, by setting OFF time and
			ON time within the step set in
			[Step number].
	□0 <i>1</i> 6	Output during AT	Turns ON during AT.
	□ <i>0 1</i> 7	Pattern end output	Turns ON when Program control
			ends, and remains ON until turned
			OFF by pressing the @ key.
	□ <i>0 18</i>	Output by communication	Turns OFF or ON by communication
		command	command 00E4H during Serial
			communication.
			B0 EV1 output 0: OFF
			1: ON
			B1 EV2 output 0: OFF
			1: ON
	O 19	Heating/Cooling control	Works as Control output OUT2
		relay contact output (*1)	(Heating/Cooling control).
		nly when Event output EV2 (EV2, EV2+D \square option	s) is ordered.
(*1) Not available if He	ating/Cooling	control (EV2+D□ option) is ordered.	

^(*1) Not available if Heating/Cooling control (EV2+D \square option) is ordered.

Characters,	Setting Item, Function, Setting Range		
Factory Default			
<i>R25R</i>	EV2 alarm value 0 Enabled/Disabled		
00	• When EV2 alarm value is 0 (zero), alarm action can be Enabled or Disabled.		
	Corresponds to [EV2 alarm value 0 Enabled/Disabled] in Initial setting mode.		
	Selection item:		
	Disabled		
	보트도 Enabled		
	independent alarm), 🗆 🛮 🗗 🖰 (Alarm or	t (EV2, EV2+D□ options) is ordered. High limit alarm) to □□□□ (Alarm output, High/Low limit range utput, High limit with standby alarm) to □□□□ (Alarm output, High/Low are selected in [Event output EV2 allocation].	
<i>R2</i> □□	EV2 alarm value		
	Sets EV2 alarm value.		
	Corresponds to [EV2 alarm v	-	
		/2 low limit alarm value in the following cases:	
	· · · · · · · · · · · · · · · · · · ·	/Low limits independent alarm), 🗆 🛮 🗗 🕏 (Alarm output,	
		ndent alarm), or 🗆 🗗 (Alarm output, High/Low	
		lent alarm) is selected in [Event output EV2 allocation].	
	Setting range:		
	High limit alarm	-(Input span) to Input span °C (°F) (*1) (*2)	
	Low limit alarm	-(Input span) to Input span °C (°F) (*1) (*2)	
	High/Low limits alarm	0 to Input span °C (°F) (*1) (*2)	
	High/Low limits independent	0 to Input span °C (°F) (*1) (*2)	
	alarm		
	High/Low limit range alarm	0 to Input span °C (°F) (*1) (*2)	
	High/Low limit range	0 to Input span °C (°F) (*1) (*2)	
	independent alarm		
	Process high alarm	Input range low limit to Input range high limit (*1) (*3)	
	Process low alarm	Input range low limit to Input range high limit (*1) (*3)	
	High limit with standby alarm	-(Input span) to Input span °C (°F) (*1) (*2)	
	Low limit with standby alarm	-(Input span) to Input span °C (°F) (*1) (*2)	
	High/Low limits with standby	0 to Input span °C (°F) (*1) (*2)	
	alarm		
	High/Low limits with standby	0 to Input span °C (°F) (*1) (*2)	
	independent alarm		
	Available only when Event output EV2 (EV2, EV2+D options) is ordered. Available when any alarm from GG ! (Alarm output, High limit alarm) to GG ! (Alarm output, High/Low limits with standby independent alarm) is selected in [Event output EV2 allocation].		
R2H	EV2 high limit alarm value		
	Sets EV2 high limit alarm value	lue.	
	This value is available only fo	or the following:	
	,	h/Low limits independent alarm), \(\Quad \overline{D} \overline{B} \) (Alarm	
		ge independent alarm), or $\square \square \square \square \square \square \square \square \square \square$ (Alarm output,	
	High/Low limits with standb	by independent alarm) is selected in [Event output EV2	
	allocation].		
		nit alarm value] in Initial setting mode.	
	Setting range: Same as thos		
	Available only when Event output EV2	2 (EV2, EV2+D□ options) is ordered.	

 $^{(^{\}star}1)$ The placement of the decimal point follows the selection.

^(*2) For DC voltage, current inputs, the input span is the same as the scaling span.

^(*3) For DC voltage, current inputs, input range low (or high) limit value is the same as scaling low (or high) limit value.

Characters, Factory Default	Setting Item, Function, Setting Range		
R2HY	EV2 alarm hysteresis		
ωul	Sets EV2 alarm hysteresis.		
	Corresponds to [EV2 alarm hysteresis] in Initial setting mode.		
	• Setting range: 0.1 to 1000.0°C (°F),		
	DC voltage, current inputs: 1 to 10000 (*1)		
	Available only when Event output EV2 (EV2, EV2+D options) is ordered.		
	Available when any alarm from $\square GG \mid$ (Alarm output, High limit alarm) to $\square G \mid \mathcal{E}$ (Alarm output, High/Low		
	limits with standby independent alarm) is selected in [Event output EV2 allocation].		
859A	EV2 alarm delay time		
	Sets EV2 alarm action delay time.		
	Corresponds to [EV2 alarm delay time] in Initial setting mode.		
	When setting time has elapsed after the input enters the alarm output range, the		
	alarm is activated.		
	Setting range: 0 to 10000 seconds		
	Available only when Event output EV2 (EV2, EV2+D□ options) is ordered.		
	Available when any alarm from \$\sum 00 ! (Alarm output, High limit alarm) to \$\sum 0 ! \cdot 0 \tag{4.5} (Alarm output, High/Low		
77, -	limits with standby independent alarm) is selected in [Event output EV2 allocation].		
82Lā	EV2 alarm Energized/De-energized		
noñL	Selects Energized/De-energized status for EV2 alarm.		
	Corresponds to [EV2 alarm Energized/De-energized] in Initial setting mode.		
	Refer to 'EV1/EV2 Energized/De-energized' (p.50).		
	• Selection item:		
	ロロボム Energized アモビウ De-energized		
	Available only when Event output EV2 (EV2, EV2+D□ options) is ordered.		
	Available when any alarm from \$\overline{\text{GG}}\$! (Alarm output, High limit alarm) to \$\overline{\text{G}}\$!? (Alarm output, High/Low		
<i>[-</i> 424	limits with standby independent alarm) is selected in [Event output EV2 allocation].		
, 75 7	 TS2 output step number Sets the step number for which Time signal output TS2 is turned OFF or ON 		
11	during Program control.		
	Corresponds to [TS2 output step number] in Initial setting mode.		
	Setting range: 1 to 9		
	Available only when \$\insertarrow{\pi}\$ (Time signal output) is selected in [Event output EV2 allocation].		
542F	TS2 OFF time		
oaão	Sets Time signal output TS2 OFF time.		
	Corresponds to [TS2 OFF time] in Initial setting mode.		
	• Setting range: 00:00 to 99:59 (*2)		
	Available only when $\Box G$ /5 (Time signal output) is selected in [Event output EV2 allocation].		
142o	TS2 ON time		
00.00	Sets Time signal output TS2 ON time.		
	Corresponds to [TS2 ON time] in Initial setting mode.		
	• Setting range: 00:00 to 99:59 (*2)		
	Available only when \$\sum 0 15\$ (Time signal output) is selected in [Event output EV2 allocation].		

^(*1) The placement of the decimal point follows the selection.

^(*2) Time unit follows the selection in [Step time unit].

Characters, Factory Default		Setting Item, Function, Setting Range	
hot	Sensor correction coefficient		
1000	Sets sensor correction coefficient.		
	Sets slope	of input value from a sensor.	
	PV after sensor correction= Current PV x (Sensor correction coefficient) +		
	(Sensor correction value)		
	Refer to Section '9.1 Input Value Correction' (p. 99).		
	Setting rai	nge: -10.000 to 10.000	
50 <u></u>	Sensor cor	rection	
		cts the input value from the sensor.	
	sensor-mea location. W not concur	ensor cannot be set at the exact location where control is desired, the asured temperature may deviate from the temperature in the controlled then using multiple controllers, sometimes the measured temperatures do due to differences in sensor accuracy or dispersion of load capacities. In e, the control can be set at the desired temperature by adjusting the input nsors.	
	PV after se	ensor correction= Current PV x (Sensor correction coefficient) +	
		(Sensor correction value)	
		ection '9.1 Input Value Correction' (p.99).	
	1	nge: -1000.0 to 1000.0℃ (℉)	
	DC voltage, current inputs: -10000 to 10000 (*1)		
FILE	PV filter time constant		
<u> </u>		Iter time constant.	
	If the value is set too high, it affects control results due to the delay of response.		
<u> </u>		nge: 0.0 to 10.0 seconds	
677L		ation protocol	
noñL		emmunication protocol.	
	Selection		
	noñL	Shinko protocol	
	ñod8	Modbus ASCII	
	ñodr.	Modbus RTU	
	<u> </u>	Shinko protocol (JC command allocated)	
	<u> </u>	Modbus ASCII (JC command allocated)	
	Jādr	Modbus RTU (JC command allocated)	
	Available only when Serial communication (C5W, C5 options) is ordered.		
6000	Instrument number		
	Sets the instrument number.		
		ment numbers should be set one by one when multiple instruments are	
		in Serial communication, otherwise communication is impossible.	
	Setting range: 0 to 95		
(*1) The placement of t		when Serial communication (C5W, C5 options) is ordered.	

^(*1) The placement of the decimal point follows the selection.

Characters, Factory Default	Setting Item, Function, Setting Range		
cāhP	Communication speed		
96	Selects a communication speed equal to that of the host computer.		
	Selection	·	
	1 95	9600 bps	
	192	19200 bps	
	384	38400 bps	
	Available only	when Serial communication (C5W, C5 options) is ordered.	
EAFF	Data bit/Pa		
7880	• Selects da	ata bit and parity.	
	• Selection	·	
	8non	8 bits/No parity	
	Topo	7 bits/No parity	
	888n	8 bits/Even	
	7885	7 bits/Even	
	8000	8 bits/Odd	
	Todd	7 bits/Odd	
	Available only	when Serial communication (C5W, C5 options) is ordered.	
cñ5/	Stop bit		
1	Selects the stop bit.		
	• Selection	item:	
	1	1 bit	
		2 bits	
	Available only	when Serial communication (C5W, C5 options) is ordered.	
cādy	Response	delay time	
□□ <i>ID</i>	 Response 	from the controller can be delayed after receiving command from the	
	host computer.		
	If Response delay time is changed via software communication, the changed delay		
		e reflected from that response data.	
	Setting rail	nge: 0 to 1000 ms	
		when Serial communication (C5W, C5 options) is ordered.	
58_6	SVTC bias		
		esired value (SV) adds SVTC bias value to the value received by the	
	SVTC com		
	Ū	nge: ±20% of input span	
	_	e, current inputs: ±20% of scaling span (*1)	
		en Shinko protocol is selected in [Communication protocol].	
rear	Remote/Lo	en Serial communication (C5W, C5 options) is ordered.	
Lock		emote (Remote operation) or Local (keypad operation) setting of the SV.	
	• Selection		
	Lock	Local	
	rEAL	Remote	
		when External setting input (EIT option) is ordered.	
(*1) The placement of t	•		

 $^{(^{\}star}1)$ The placement of the decimal point follows the selection.

Characters, Factory Default		Setting Item, Function, Setting Range	
ractory Default	External setting input high limit		
1370	Sets External setting input high limit value.		
	(This value corresponds to 20 mA in direct current input.)		
	Setting range: External setting input low limit to Input range high limit		
		al setting input (EIT option) is ordered.	
rrll	External setting inpu		
-200	Sets External setting		
	_	nds to 4 mA in direct current input.)	
	,	range low limit to External setting input high limit	
		al setting input (EIT option) is ordered.	
-r_b	Remote bias		
	During remote action	n, SV includes the remote bias value.	
	Setting range: ±20%	% of input span	
	DC voltage, current i	nputs: ±20% of scaling span (*1)	
	Available only when Externa	al setting input (EIT option) is ordered.	
5-05	Transmission output	t type	
P8	 Selects the transmis 	sion output type.	
		smission output type, refer to Section "8.10 Items to be	
	Initialized by Changi	ng Settings" (p.98).	
	Selection item:		
	PU PV trans		
	ち出 SV transi		
	MV transmission db □ DV transmission		
	L		
<i></i>	·	nission output (EIT option) is ordered.	
Γ-LH 1370	Transmission output	t nigh limit on output high limit value.	
ום ום		nds to 20 mA in direct current output.)	
	• Setting range:		
	PV, SV transmission	Transmission output low limit to Input range high limit value	
	MV transmission	Transmission output low limit to 105.0%	
	DV transmission	Transmission output low limit to Scaling span (*1)	
	Available only when Transmission output (EIT option) is ordered.		
r-LL	Transmission output low limit		
-200	Sets the Transmission	on output low limit value.	
	(This value correpor	nds to 4 mA in direct current output.)	
	Setting range:		
	PV, SV transmission	Input range low limit to Transmission output high limit value	
	MV transmission	-5.0% to Transmission output high limit value	
	DV transmission	-Scaling span to Transmission output high limit value (*1)	
	Available only when Transm	nission output (EIT option) is ordered.	
ñ_ h	Step time unit		
ñ! n□	Selects the Step time unit for the Program control.		
	Selection item:		
		Minutes	
	l .	es:Seconds	
	Available only when Progra	m control is selected in [OUT/OFF key function].	

^(*1) The placement of the decimal point follows the selection.

Characters, Factory Default		Setting Item, Function, Setting Range	
P-E!	Power restore action		
450P	Selects the program status if a power failure occurs mid-program and it is restored.		
	• Selection item:		
	5/ pP	Stops after power is restored.	
	conf	Continues (resumes) after power is restored.	
	HoLd	Suspends (on hold) after power is restored.	
		when Program control is selected in [OUT/OFF key function].	
5 - 5B		art temperature	
		ep temperature when Program control starts.	
		ge: Scaling low limit value to Scaling high limit value (*1)	
	_	when Program control is selected in [OUT/OFF key function].	
5 - 5L		entrol start type	
PB		Program control start type.	
, o	Selects the Selection if	,,	
	PH	PV start	
	PBr	PVR start	
	7 D.	SV start	
- 595	Available only when Program control is selected in [OUT/OFF key function].		
	Number of repetitionsSets the number of repetitions for Program control.		
		ge: 0 to 10000 times	
		when Program control is selected in [OUT/OFF key function].	
- A55			
585F	SV Rise/Fall rate start type • When control output is turned from OFF to ON, or switched from Manual to		
		control, SV start or PV start can be selected for SV rise rate or SV fall	
	rate action.		
	When power is turned ON, PV start is adopted for SV Rise/Fall rate action,		
	regardless of the selected type.		
	• Selection item:		
	585F	SV start	
	PBS	PV start	
-85U	SV rise rate		
	Sets SV ris	e rate (rising value for 1 minute).	
	When the S	SV is adjusted, it approaches the new SV by the preset rate-of-change	
	(°C/min, °F/		
	When the power is turned on, the control starts from the PV, and approaches the		
	SV by the rate-of-change (°C/min, °F/min).		
	_	ge: 0 to 10000°C/min (°F/min)	
	Thermocouple, RTD inputs with a decimal point: 0.0 to 1000.0°C/min (°F/min)		
	_	, current inputs: 0 to 10000/min	
(*1) The placement of t		or 0.0 disables this function.	

 $^{(^{\}star}1)$ The placement of the decimal point follows the selection.

Characters,	Setting Item, Function, Setting Range		
Factory Default			
-85d	SV fall rate		
	Sets SV fall rate (falling value for 1 minute).		
	When the SV is adjusted, it approaches the new SV by the preset rate-of-change		
	(°C/min, °F/min). When the power is turned on, the control starts from the PV and		
	approaches the SV by the rate-of-change (°C/min, °F/min).		
	• Setting range: 0 to 10000°C/min (°F/min)		
	Thermocouple, RTD inputs with a decimal point: 0.0 to 1000.0°C/min (°F/min)		
	DC voltage, current inputs: 0 to 10000/min		
	Setting to 0 or 0.0 disables this function.		
P58	Indication when control output OFF		
off[Selects the indication when control output is OFF.		
	Selection item:		
	□FF indication		
	RoFF No indication		
	P8 PV indication		
	PBRL PV indication + Any Alarm active		
8F_6	AT bias		
□□20	Sets bias value for the AT.		
	AT point is automatically determined by the deviation between PV and SV.		
	Refer to Section '8.5 Setting PID Constants (by performing AT)' (p.84).		
	• Setting range: 0 to 50°C (0 to 100°F) or		
	0.0 to 50.0°C (0.0 to 100.0°F)		
	Available only for PID control.		
	Not available for DC voltage, current inputs		
Ar_E	AT gain Sets proportional band ratio calculated by performing AT or 'AT on startup'.		
UD	• Setting range: 0.1 to 10.0		
EaUF	Output status when input errors occur		
off.	Selects the output status when input errors occur.		
	Selection item:		
	□FF□ Output OFF		
	Output ON		
	Available for direct current and voltage inputs, and direct current output type.		
585U	OUT/OFF key function		
oFF	Selects OUT/OFF key function.		
	Selection item:		
	□FF□ Control output OFF function		
	ก็สิกป์ Auto/Manual control		
	Pro5 Program control		
58ch	Auto/Manual after power ON		
AUF-	When the power to the controller is turned ON, selects whether the unit starts using		
	Automatic control or Manual control.		
	Selection item:		
	RUF D Automatic control		
	⊼8⊓U Manual control		
	Available only when Auto/Manual control is selected in [OUT/OFF key function].		
L	aa.c siny mioni diagramma delivers to delevide in [OO 1/O1 1 Noy function].		

Characters, Factory Default	Setting Item, Function, Setting Range	
Factory Default	Indication time	
00.00		
	Sets time from no operation status until Displays are switched off. Displays relight by pressing any key while in Display class made.	
	Displays relight by pressing any key while in Display sleep mode.	
	When input error (Overscale, Underscale) or burnout has occurred, Displays are	
	lit, and error codes are displayed.	
	If errors are cancelled, Displays will be unlit after indication time has passed again.	
	• Setting range: 00:00 to 60:00 (Minutes:Seconds)	
50.5.4	When set to 00:00, Displays remain ON.	
P5F !	OUT1 MV preset value	
	• If 'Preset output 1 ON/OFF' or 'Preset output 2 ON/OFF' is selected in [Event	
	input allocation], OUT1 MV can be set.	
	Preset output 1 ON/OFF:	
	If sensor is burnt out during Event Input ON, control is performed with the preset	
	MV.	
	Preset output 2 ON/OFF:	
	When Event input is ON, control is performed with the preset MV.	
	Setting range: OUT1 low limit to OUT1 high limit	
	For Direct current output type, and when OUT1 is in ON/OFF control: OUT1 low	
	limit or OUT1 high limit	
	For Relay contact output or Non-contact voltage output type, and when OUT1 is in	
	ON/OFF control: 0.0% or 100.0%	
	For BCS2, available only when Event input (EIW, EIT, EI options) is ordered.	
	For BCR2/BCD2, available when Serial communication (C5W option) or Event input (EIW, EIT, EI options) is	
P552	ordered.	
	OUT2 MV preset value	
	• If 'Preset output 1 ON/OFF' or 'Preset output 2 ON/OFF' is selected in [Event	
	input allocation], OUT2 MV can be set.	
	Preset output 1 ON/OFF:	
	If sensor is burnt out during Event Input ON, control is performed with the preset	
	MV.	
	Preset output 2 ON/OFF:	
	When Event input is ON, control is performed with the preset MV.	
	Setting range: OUT2 low limit to OUT2 high limit Setting range: OUT2 low limit to OUT2 high limit	
	For DA, EV2+DA options, and when OUT2 is in ON/OFF control: OUT2 low limit or	
	OUT2 high limit	
	For DR, DS, EV2+DR, EV2+DS options, and when OUT2 is in ON/OFF control:	
	0.0% or 100.0%	
	Available for the following:	
	 For BCS2, Heating/Cooling control [DS, DA, EV2(*1), EV2+D□ options] or Event input (EIW, EIT, EI options) is ordered. 	
	• For BCR2/BCD2, Heating/Cooling control [DS, DA, EV2(*1), EV2+D□ options], Serial communication	
	(C5W option) or Event input (EIW, EIT, EI options) is ordered.	
FUnc	Controller/Converter function	
cnTr	Selects either controller or converter function.	
	Selection item:	
	<i>⊏⊓</i> Controller	
	<i>⊆⊓</i> ЫГ Converter	
	Available only when OUT1 is direct current output.	
(*1) When 77 10 (He)		

^(*1) When 📅 🖰 (Heating/Cooling control relay contact output) is selected in [Event output EV2 allocation].

Characters, Factory Default		Setting Item, Function, Setting Range	
EdiF	Error indica	tion Enabled/Disabled	
no	 When input errors occur, the error code can be displayed (Enabled) or not displayed (Disabled). 		
	Selection item:		
	00	Disabled	
	4E 4	Enabled	

7.4 Engineering Mode 2

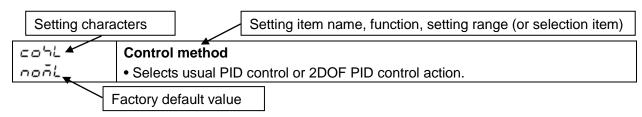
To enter Engineering mode 2, press and hold the \wedge , \vee and \circ keys (in that order) together for approximately 5 seconds in RUN mode.

Use the \wedge or \vee key for settings (or selections).

To register the set data, use the O key.

Explanation of setting items:

- Upper left: PV Display: Indicates setting characters.
- Lower left: SV Display: Indicates factory default value.
- Right side: Indicates the setting item, explanation of its function and setting range (or selection item).



Characters, Factory Default		Setting Item, Function, Setting Range	
co5L	Control me	ethod	
noñL	Selects us	sual PID control or 2DOF PID control action.	
	DOF: Deg	ree(s) of freedom	
	noñL	PID control	
	26oF	2DOF PID control	
ŁPRH	Proportion	al gain 2DOF coefficient (α)	
<u> </u>	Sets Prop	ortional gain 2DOF coefficient.	
	Increasing	Proportional gain 2DOF coefficient (α) results in a quick response,	
	and decreasing it causes a slow response.		
	Setting range: 0.00 to 1.00		
	Available only	y when 2DOF PID control is selected in [Control method].	
ΓΙ Ь Γ	Integral 2D	OOF coefficient (β)	
□ <i>t3</i> 5	Sets Integral	gral 2DOF coefficient.	
	By increas	ing Integral 2DOF coefficient (β), overshoot or undershoot can be	
	controlled	more effectively.	
	However, i	response will be slower than the usual PID control for suppressing the	
	overshoot	overshoot or undershoot.	
	Setting ra	nge: 0.00 to 10.00	
	Available only	when 2DOF PID control is selected in [Control method].	

2DOF PID Control

Two degree-of-freedom PID control has follow-up characteristics and can suppress disturbance when SV is changed.

Two degree-of-freedom means that the above 2 characteristics can be adjusted independently.

Follow-up characteristics when SV is changed, can be adjusted by setting the Proportional gain 2DOF coefficient (α).

To suppress disturbance, Integral 2DOF coefficient (β) are used for adjustment.

The factory default values have been set at the optimum coefficients (α , β) for standard control.

8. Operation and Settings of Standard Functions

8.1 Selecting an input type

Select an input type in [Input type] in Initial setting mode.

Selection item:

E	K -200 to 1370°C	EF	K -328 to 2498°F
E□ .E	K -200.0 to 400.0°C	E□ .F	K -328.0 to 752.0°F
J	J -200 to 1000°C	J∭F	J -328 to 1832°F
- L	R 0 to 1760°C	r F	R 32 to 3200°F
5 E	S 0 to 1760°C	5 F	S 32 to 3200°F
ьШС	B 0 to 1820℃	Ь∭Е	B 32 to 3308°F
ΕΠΕ	E -200 to 800°C	EIIF	E -328 to 1472°F
Γ	T -200.0 to 400.0°C	ſ□ .F	T -328.0 to 752.0°F
$\sigma \square \square \mathcal{L}$	N -200 to 1300°C	$\neg \Box \mathcal{F}$	N -328 to 2372°F
PL2C	PL-Ⅱ 0 to 1390°C	PL 2F	PL-Ⅱ 32 to 2534°F
c I E	C(W/Re5-26) 0 to 2315°C	c F	C(W/Re5-26) 32 to 4199°F
PC .C	Pt100 -200.0 to 850.0℃	PT F	Pt100 -328.0 to 1562.0°F
JPT.E	JPt100 -200.0 to 500.0℃	JPT.F	JPt100 -328.0 to 932.0°F
PT	Pt100 -200 to 850°C	PT	Pt100 -328 to 1562°F
JPCE	JPt100 -200 to 500°C	JPFF	JPt100 -328 to 932°F
420A	4 to 20 mA DC -2000 to 10000		
020A	0 to 20 mA DC -2000 to 10000		
00 IB	0 to 1 V DC -2000 to 10000		
005 <i>8</i>	0 to 5 V DC -2000 to 10000		
/□5 <i>\</i>	1 to 5 V DC -2000 to 10000		

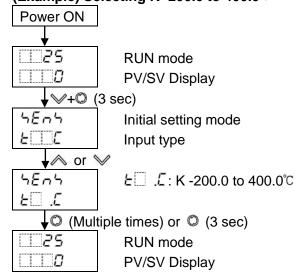
Factory default value is K -200 to 1370℃.

0 to 10 V DC

-2000 to 10000

0 108

(Example) Selecting K -200.0 to 400.0℃



8.2 Selecting PID Control or ON/OFF Control

Selects PID control or ON/OFF control action.

Select PID control or ON/OFF control action in [OUT1 proportional band] in Sub setting mode. If 'OUT1 proportional band' is set to 0 (zero), the unit performs ON/OFF control action. Factory default value is PID control.

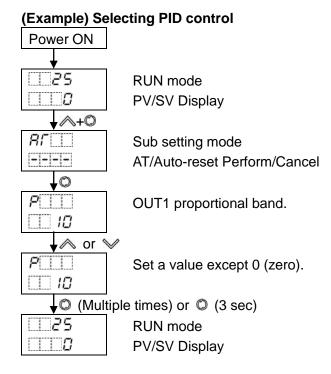
PID control

Proportional (P) action suppresses overshoot and hunting, Integral (I) action corrects offset, and Derivative (D) action converges rapid temperature change due to disturbance in shorter time. Optimum values of P, I, D, ARW for PID control can be automatically set by performing AT.

ON/OFF control

When PV is lower than the SV, the control output is turned ON, and if PV exceeds the SV, the control output is turned OFF.

Overshoot, undershoot and hunting are generated in ON/OFF control action.



- P control action: When [Integral time] and [Derivative time] are set to 0 (zero).
- PD control action: When [Integral time] is set to 0 (zero).
- PI control action: When [Derivative time] is set to 0 (zero).
- Usual PID control or 2DOF PID control can be selected in [Control method] in Section '7.4 Engineering Mode 2' (p.78).

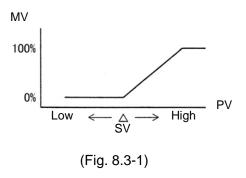
8.3 Selecting Direct/Reverse Action

Selects Direct or Reverse control action.

Select Direct or Reverse control action in [Direct/Reverse action] in Sub setting mode. Factory default value is Reverse action.

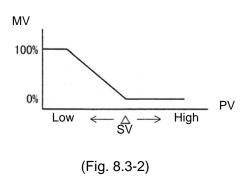
Direct action

In Direct action, MV is increased when PV is higher than SV (positive deviation). Refrigerators, etc. perform Direct action.

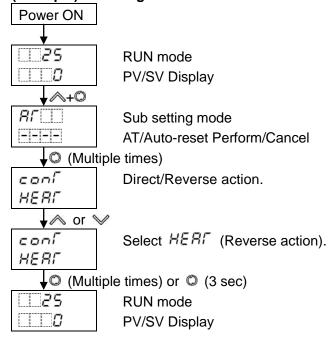


Reverse action

In Reverse action, MV is increased when SV is higher than PV (negative deviation). Electric furnaces, etc. perform Reverse action.



(Example) Selecting Reverse action



8.4 Performing Fixed Value Control

Fixed value control is a typical temperature control action, which reduces deviation from a single SV by comparing with PV.

To perform Fixed value control, set the SV.

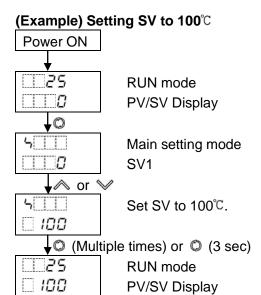
There are 2 ways to set the SV.

- Set the SV in [SV1] in Initial setting mode.
- Set the SV in [SV1] in Main setting mode.

Setting item [SV1] in Initial setting mode corresponds to [SV1] in Main setting mode.

Therefore, if one SV1 is changed, the other SV1 will also be changed.

Factory default value is 0 (zero).



Now, settings are complete.



!\ Notice

- Perform the AT during the trial run.
- During the AT, none of the setting items can be set.
- If power failure occurs during the AT, the AT stops.
- If AT is cancelled during the process, P, I, D and ARW values revert to the values before AT was performed.
- AT will be forced to stop if it has not been completed within 4 hours.
- Sometimes the AT process will not fluctuate if AT is performed at or near room temperature. Therefore AT might not finish normally.

To set PID constants, perform AT.

There are 2 types of AT.

(1) Usual AT

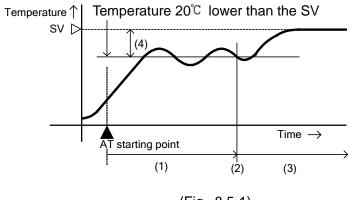
In order to set each value of P, I, D and ARW automatically, the AT process should be made to fluctuate to obtain an optimal value.

For DC voltage, current inputs, the AT process will fluctuate around the SV for conditions of [A], [B] and [C] below.

One of 3 types of fluctuation below is automatically selected depending on the deviation between SV and PV.

[A] If there is a large difference between the SV and PV as the temperature is rising

When AT bias is set to 20°C, the AT process will fluctuate at the temperature 20°C lower than the SV.

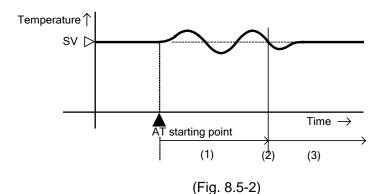


(Fig. 8.5-1)

- (1) Calculating PID constants
- (2) PID constants calculated
- (3) Controlled by the PID constants set by AT.
- (4) AT bias value (Factory default: 20°C)

[B] When the control is stable

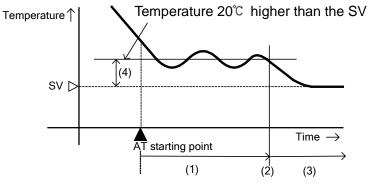
The AT process will fluctuate around the SV.



- (1) Calculating PID constants
- (2) PID constants calculated
- (3) Controlled by the PID constants set by AT.

[C] If there is a large difference between the SV and PV as the temperature is falling

When AT bias is set to 20°C, the AT process will fluctuate at the temperature 20°C higher than the SV.



(Fig. 8.5-3)

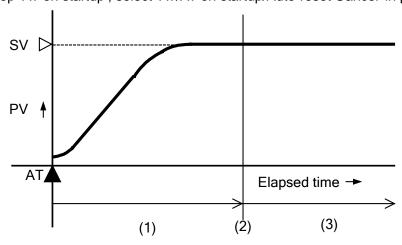
- (1) Calculating PID constants
- (2) PID constants calculated
- (3) Controlled by the PID constants set by AT.
- (4) AT bias value (Factory default: 20°C)

(2) AT on Startup

When usual AT cannot be performed normally due to temperature interference, P, I, D and ARW values can be calculated only when temperature is rising.

As the selected [AT on startup Perform] is internally memorized, 'AT on startup' is performed whenever the power is turned ON.

To stop 'AT on startup', select 'AT/AT on startup/Auto-reset Cancel' in [AT/Auto-reset Perform/Cancel].



- (1) Calculating AT (from startup, until PV is stabilized at SV)
- (2) PID constants calculated
- (3) Controls with PID constants set by 'AT on startup' (Fig. 8.5-4)

[Conditions of Performing 'AT on startup']

• When starting 'AT on startup', if deviation between PV and SV exceeds the proportional band by 2 times or more, 'AT on startup' will perform.

When power is turned ON (*), or when the unit reverts to RUN mode after canceling control output OFF, 'AT on startup' performs.

Even after 'AT on startup' is successfully finished, 'AT on startup' has been still selected in [AT/Auto-reset Perform/Cancel].

When power is turned ON again, or when the unit reverts to RUN mode by cancelling Control output OFF, 'AT on startup' performs again under the above performance conditions.

To stop 'AT on startup', select 'AT/AT on startup/Auto-reset Cancel' in [AT/Auto-reset Perform/Cancel].

(*) For Fixed value control, 'AT on startup' can be performed when power is turned ON. It cannot be performed for Program control.

However, if PV slope and delay time cannot be measured normally for P, I, D calculation, the error code below will be indicated on the PV Display, and automatically 'AT on startup' will stop. If an error has occurred, P, I, D and ARW values revert to the previous value at which 'AT on startup' is performed.

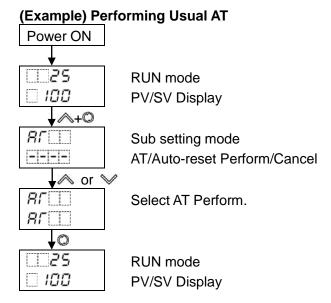
Error Code	Error Contents
E-20	PV slope and delay time cannot be measured normally for P, I, D calculation.

To cancel the error code, press the \(\mathbb{O} \) key.

If 'AT on startup' is performed or stopped, the error code will be cancelled.

[Conditions of Cancelling 'AT on startup']

- When Control output OFF is enabled
- When input is burnt out
- When deviation between SV and PV is not within 2°C or within 2% of proportional band (even though the set integral time has elapsed when the control is stable) in stable control status



Now, selection is complete.

The AT indicator flashes while AT is performing.

After AT is complete, the AT indicator goes off, and control is performed using PID constants calculated by the AT.

If AT does not finish after 4 hours, the error code below will be indicated on the PV Display, and AT will automatically stop.

Error Code	Error Contents
E-20	If AT or 'AT on startup' does not finish after 4 hours.

To cancel the error code, press the \(\mathbb{O} \) key.

The error code will be cancelled in the following cases.

- When Control output OFF function is enabled
- When Program control is stopped and the unit reverts to the Standby (Program control waiting) mode.
- When 'Control output OFF function' or 'Auto/Manual control' is selected in [OUT/OFF key function].
- When 'AT/AT on startup/Auto-reset Cancel' is selected in [AT/Auto-reset Perform/Cancel].

8.6 Performing Auto-reset

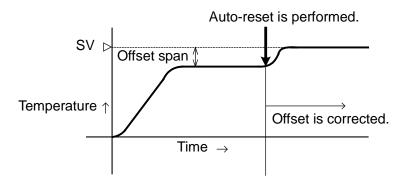


Notice

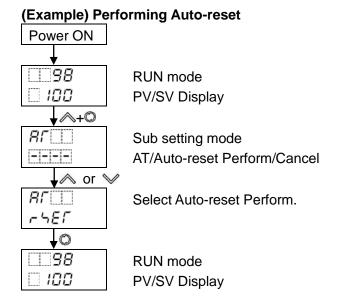
- Auto-reset is cancelled in approximately 4 minutes. It cannot be cancelled while performing this function.
- If input is burnt out, Auto-reset will be forced to stop.

Auto-reset is performed to correct the offset at the point at which PV indication is stabilized within the proportional band during the PD control. Since the corrected value is internally memorized, it is not necessary to perform the Auto-reset again as long as the process is the same.

However, when OUT1 proportional band (P) is set to 0 or 0.0, the corrected value is cleared to 0 (zero).



(Fig. 8.6-1)



Now, selection is complete.

The AT indicator flashes while Auto-reset is performing.

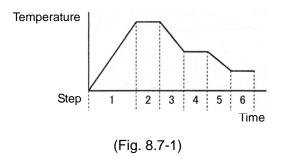
Auto-reset is completed in approximately 4 minutes.

After Auto-reset is complete, the AT indicator goes off, and control is performed using the offset corrected value.

8.7 Performing Program Control

In Program control, SV changes as time elapses, and PV is controlled in order to reach each SV. SV and time can be set for every step, and a maximum of 9 steps can be repeatedly controlled. SV can be set as (Fig. 8.7-1).

(e.g.) Program control of electric furnaces in ceramic manufacture, food machinery, etc.



Major functions of Program control are shown below.

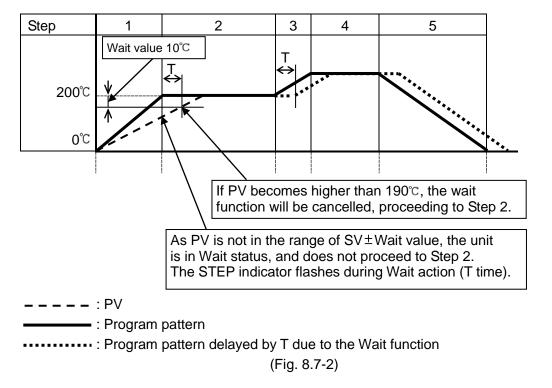
Number of patterns and steps: 1 pattern; 9 steps

Wait function

While Program control is running, the program does not proceed to the next step until the deviation between PV and SV enters SV±Wait value at the end of step. The PV Display flashes while the Wait function is working.

The Wait function is cancelled on the condition that:

- When program pattern is rising: PV is higher than SV- Wait value
- When program pattern is falling: PV is lower than SV+ Wait value



Program control Holding/Not holding

During Program control, progress of current step is suspended, and then

Fixed value control is performed using the SV from the point of suspension.

Program control Holding/Not holding can be selected in [Event input DI1/DI2 allocation].

Advance function

Interrupts current step while Program control is running, and proceeds to the beginning of the next step.

By pressing the key for approx. 1 second during Program control, Advance function initiates. Select this function in [Event input DI1/DI2 allocation].

Pattern end output

If Pattern end output is selected in [Event output EV1/EV2 allocation], pattern end output is turned ON after Program control is finished, and the SV Display flashes PEnd.

By pressing the ® key for approx. 1 second, pattern end output is turned OFF, and the unit enters Standby mode.

Step time unit

Step time unit can be selected: Hours:Minutes, Minutes:Seconds

Factory default value is Hours:Minutes.

Power Restore Action (Program control after power is restored)

If power fails during Program control, selects a status after the power is restored.

Factory default value is 'Stops after power is restored'.

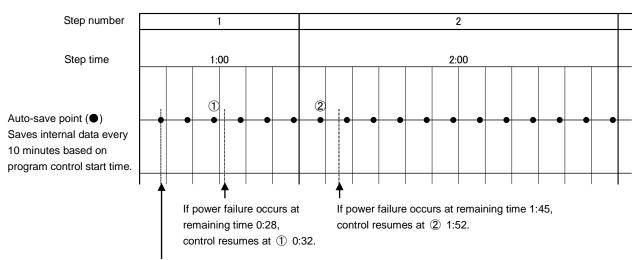
Power Restore Action	Description
Stops after power is	Stops Program control, and returns to Standby (Program control
restored.	waiting) mode.
Continues after power is	Continues (resumes) Program control.
restored. (*)	
Suspends after power is	Suspends (on hold) current program, and performs Fixed value
restored. (*)	control using the SV from the point of suspension.
	Pressing the @ key cancels suspension, and Program control
	resumes.

^(*) Progressing time error when power is restored: 10 minutes

This controller saves internal status every 10 minutes after Program control starts.

Internal status is also saved when step is changed.

When power is restored, the unit starts from the last auto-save point.



PV start is used. SV and time are advanced to the remaining time 0:52, and program control starts.

(Fig. 8.7-3)

Program start temperature

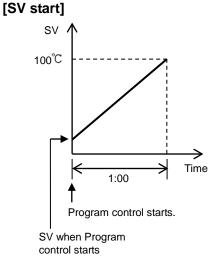
When Program control starts, it starts from the value set in [Program start temperature]. Factory default value is 0°C.

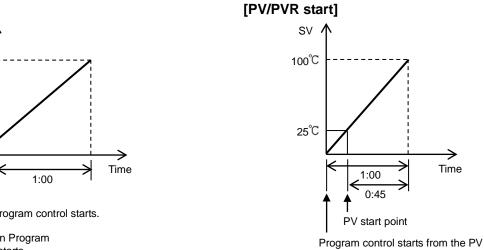
Program control start type

One type can be selected: PV start, PVR start, SV start.

Factory default value is PV start.

Program control start type	Description
PV start	When Program control starts, the SV and step time are advanced to the PV,
	then Program control starts.
	However, if [Program start temperature] at the time of Program control start is
	higher than the PV (when PV start is initiated), then Program control will start
	from the SV set in [Program start temperature].
PVR start	In pattern repeating, the SV and step time are advanced to the PV, then the
	Program control starts.
SV start	Program control starts from the SV which has been set in [Program start
	temperature].





(Fig. 8.7-4)

start point (measured value 25°C).

Time

(Fig. 8.7-5)

Repeat function

When Program control is finished, control can be repeated from Step 1.

The user determines the number of repetitions.

Factory default value is 0 (zero).

Select 'Program control' in [OUT/OFF key function] in Engineering mode 1. Factory default value is Control output OFF function.

Set the following items in Engineering mode 1:

Step time unit, Power restore action, Program start temperature,

Program control start type, Number of repetitions

Program pattern can be set in Main setting mode.

Example of program pattern setting

Step	1	2	3	4	5
SV (℃)	200	200	300	300	0
Time	1:00	2:00	0:30	1:00	2:00
Wait value (°C)	10	0	10	0	0
300℃					
200℃					
0℃					
	← →	← 2:00 >	0:30	< 1:00 >	< 2:00 →
	L_Prograr	n control starts			

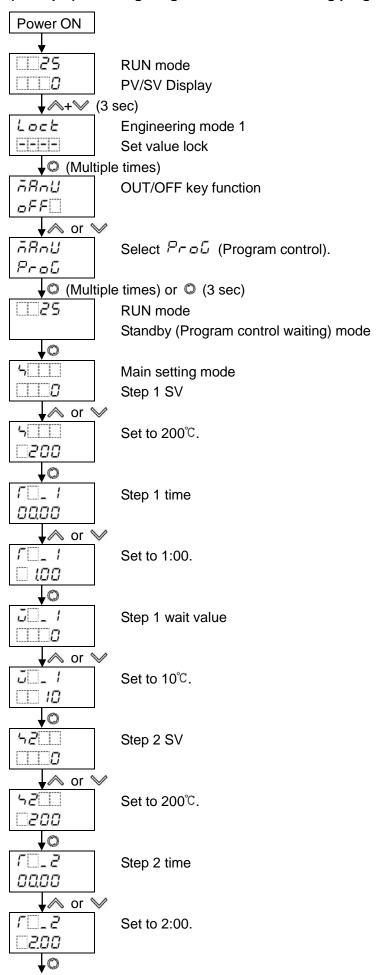
(Fig. 8.7-6)

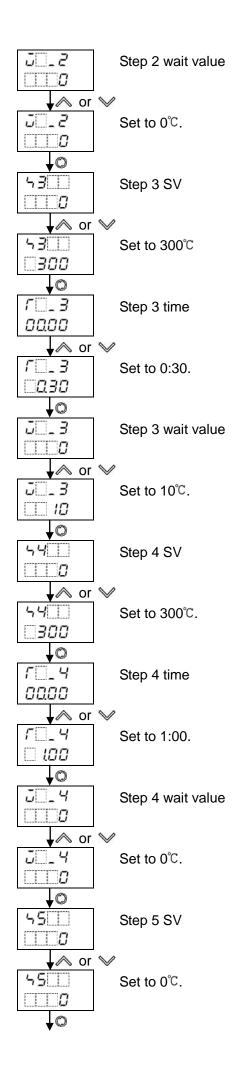
In the above program pattern, control is performed at each step as follows.

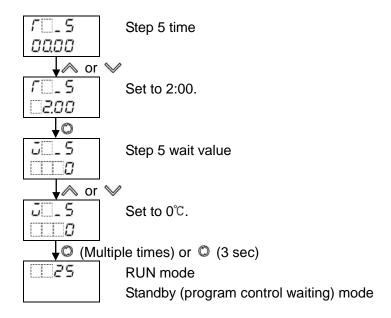
- Step 1: The SV gradually rises to 200°C for 1 hour.

 When step ends, Wait function works so that control cannot proceed to the next step until PV reaches 190°C when step ends.
- Step 2: Fixed value control is performed to keep SV at 200°C for 2 hours.
- Step 3: Control is performed so that the SV gradually rises to 300°C for 30 minutes. When step is finished, Wait function works so that control cannot proceed to the next step until PV reaches 290°C.
- Step 4: Fixed value control is performed to keep SV at 300°C for 1 hour.
- Step 5: Control is performed so that the SV gradually falls to 0^oC for 2 hours.

(Example) Selecting Program control and Setting program pattern of (Fig. 8.7-6)







Now, selection is complete.

Program control RUN

To perform Program control, press and hold the key for approx. 1 second in Standby (program control waiting) mode.

Program control starts using the start type selected in [Program control start type].

While Wait function is working, the PV Display flashes.

Program control STOP

To stop Program control, press and hold the key for approx. 1 second during Program control. Program control will stop, and the unit will revert to Standby (Program control waiting) mode.

Proceeding to the next step during Program control (Advance function)

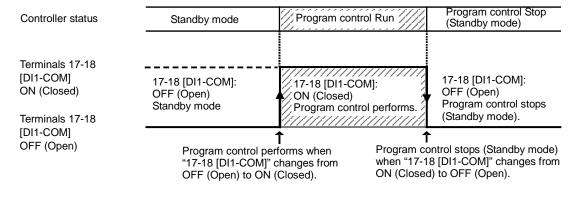
By pressing the key for approx. 1 second during Program control, the performing step is interrupted, proceeding to the next step. (Advance function)

While Wait function is working, the Wait function is cancelled, and proceeds to the next step.

If \$\instyle DDB\$ (Program control RUN/STOP)' is selected in [Event input DI1 allocation], Program control RUN/STOP can be switched by terminals 17-18 [DI1-COM]:

Signal edge action from OFF to ON / ON to OFF is engaged.

However, for the action when power is turned ON, Level action [ON (Closed) or OFF (Open)] is engaged.



(Fig. 8.7-7)

8.8 Event Output EV1 Allocation

Selects Event output EV1 allocation.

There are 2 methods in selection of Event output EV1 allocation.

- Select in [Event output EV1 allocation] in Initial setting mode.
- Select in [Event output EV1 allocation] in Engineering mode 1.
 Setting item [Event output EV1 allocation] in Initial setting mode corresponds to [Event output EV1

allocation] in Engineering mode 1. Therefore, if one [Event output EV1 allocation] is changed, the other [Event output EV1 allocation]

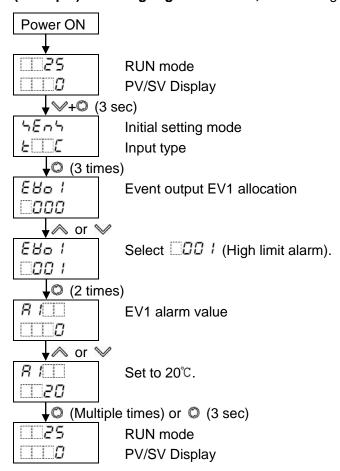
will also be changed.

Factory default value is No event.

Selection item:

<u> </u>	No event	
<u> </u>	Alarm output, High limit alarm	
□002	Alarm output, Low limit alarm	
	Alarm output, High/Low limits alarm	
□004	Alarm output, High/Low limits independent alarm	
005	Alarm output, High/Low limit range alarm	
005	Alarm output, High/Low limit range	
	independent alarm	
□007	Alarm output, Process high alarm	
008	Alarm output, Process low alarm	
009	Alarm output, High limit with standby alarm	
□ <i>0 10</i>	Alarm output, Low limit with standby alarm	
	Alarm output, High/Low limits with standby alarm	
□0 12	Alarm output, High/Low limits with standby independent alarm	
□ <i>0 13</i>	Heater burnout alarm output	
□ <i>0 1</i> 4	Loop break alarm output	
□ <i>0 1</i> 5	Time signal output	Turns OFF or ON during Program control,
		by setting OFF time and ON time within
		the step set in [Step number].
□ <i>0 1</i> 6	Output during AT	Turns ON during AT.
רו ס	Pattern end output	Turns ON when Program control ends, and
		remains ON until turned OFF by pressing
		the @ key.
O 18	Output by communication command	Turns OFF or ON by communication
		command 00E4H during Serial
		communication.
		B0 EV1 output 0: OFF
		1: ON
		B1 EV2 output 0: OFF
		1: ON
L	-	

(Example) Selecting High limit alarm, and setting EV1 alarm value to 20℃



Now, settings are complete.

8.9 Indicating MV, Remaining Time (Program Control)

In Fixed value control and Program control, MV and remaining time are indicated.

To indicate MV, press and hold the \infty key for approx. 3 seconds on the PV/SV Display.

The unit enters Monitor mode, and indicates MV.

While MV is indicating, the decimal point flashes.

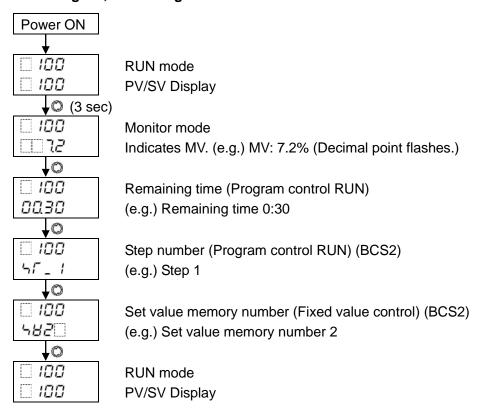
While in Standby (Program control waiting) mode of Program control, the unit cannot move to Monitor mode.

In Monitor mode, the following contents are switched every time the Q key is pressed.

Model	Indicated Contents		
BCS2	Fixed value control	Indicates MV, Set value memory number (in that order).	
	Program control	Indicates MV, Remaining time, Step number (in that order).	
BCR2, BCD2	Fixed value control	Indicates only MV. (*)	
	Program control	Indicates MV, Remaining time (in that order). (*)	

^(*) For the BCR2, BCD2, Set value memory number (Fixed value control) and step number (Program control) are indicated on the MEMO/STEP Display.

Indicating MV, Remaining time



8.10 Items to be Initialized by Changing Settings

If settings are changed, the following items will be initialized.

•: Initialized

X: Not initialized

Setting item to be	L	Event output	Event output	Transmission
Item changed to be initialized	Input Type	EV1 allocation	EV2 allocation	output
SV1 to SV9	•	X	Х	X
Steps 1 to 9 wait value	•	Х	Х	Х
AT bias	•	Х	Х	Х
OUT1 proportional band	•	X	Х	Х
Manual reset	•	X	Х	Х
SV rise rate	•	Х	Х	Х
SV fall rate	•	Х	Х	Х
Scaling high limit	•	Х	Х	X
Scaling low limit	•	Х	Х	Х
Program start temperature	•	Х	Х	Х
EV1 alarm value	•	•	Х	Х
EV1 high limit alarm value	•	•	Х	Х
Loop break alarm time	•	Х	Х	Х
Loop break alarm span	•	X	Х	Х
SVTC bias	•	X	Х	Х
Remote bias	•	X	Х	Х
EV2 alarm value	•	Х	•	Х
EV2 high limit alarm value	•	X	•	X
Transmission output high limit	•	Х	Х	•
(Except MV transmission)				
Transmission output low limit	•	X	X	•
(Except MV transmission)				
OUT2 proportional band	•	X	X	X
EV1 alarm value 0 Enabled/Disabled	Х	•	X	X
EV1 alarm hysteresis	X	•	X	X
EV1 alarm delay time	X	•	X	X
EV1 alarm Energized/De-energized	X	•	X	X
EV2 alarm value 0 Enabled/Disabled	X	X	•	X
EV2 alarm hysteresis	X	X	•	X
EV2 alarm delay time	X	X	•	Х
EV2 alarm Energized/De-energized	X	X	•	X
Sensor correction coefficient	•	X	X	Х
Sensor correction	•	X	X	Х
External setting input high limit	•	X	X	Х
External setting input low limit	•	X	X	X

9. Attached Function

9.1 Input Value Correction

Input value can be corrected in [Sensor correction coefficient] and [Sensor correction] in Engineering mode 1.

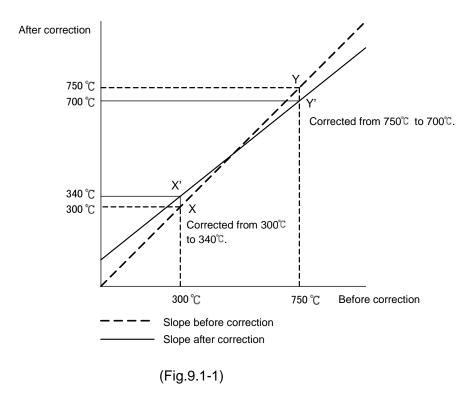
In [Sensor correction coefficient], set the slope of temperature change.

In [Sensor correction], set the difference between temperatures before correction and after correction.

PV after input correction is expressed with the following formula.

PV after input correction = Current PV x Sensor correction coefficient + (Sensor correction value)

The following shows an example of input value correction using 'Sensor correction coefficient' and 'Sensor correction value'.



(1) Select any 2 points of PV to be corrected, and determine the PV after correction.

PV before correction: 300° C \rightarrow PV after correction: 340° C

PV before correction: 750°C → PV after correction: 700°C

(2) Calculate Sensor correction coefficient from Step (1).

$$(Y'-X')/(Y-X) = (700-340)/(750-300) = 0.8$$

- (3) Enter a PV value of 300°C using an mV generator or dial resistor.
- (4) Set Step (2) value as a Sensor correction coefficient.
- (5) Read the PV.

240°C will be indicated.

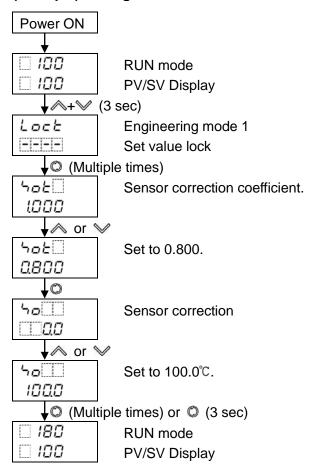
(6) Calculate the sensor correction value.

Calculate the difference between 'PV after correction' and Step (5) PV.

340°C − 240°C = 100°C

- (7) Set Step (6) value as a Sensor correction value.
- (8) Enter an electromotive force or resistance value equivalent to 750°C using an mV generator or dial resistor.
- (9) Read the PV, and confirm that 700°C is indicated.

(Example) Setting Sensor correction coefficient to 0.800, and Sensor correction to 100.0℃



Now, settings are complete.

9.2 Set Value Lock

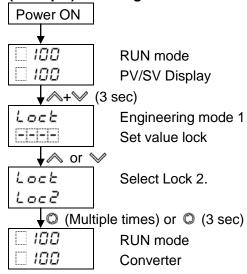
Locks the set values to prevent setting errors.

Make a selection in [Set value lock] in Engineering mode 1.

The setting item to be locked depends on the selection.

Selection Item	Change via Keypad	Change via Software Communication
Unlock	All set values can be changed.	All set values can be changed.
Lock 1	None of the set values can be changed.	
Lock 2	In Fixed value control, only SV and	
	Alarm value can be changed.	
	In Program control, Step SV, Step time	
	and Alarm value can be changed.	
Lock 3	All set values can be changed.	Setting items – except Input type,
Lock 4	None of the set values can be changed.	Controller/Converter – can be changed
Lock 5	In Fixed value control, only SV and	temporarily via software communication.
	Alarm value can be changed.	However, if power is turned ON again,
	In Program control, Step SV, Step time	the setting values revert to the values
	and Alarm value can be changed.	before Lock 3, 4 or 5 was selected.



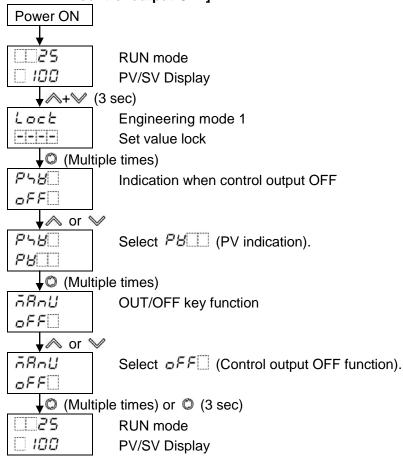


9.3 Control Output OFF Function

The control action and output of an instrument (or instruments) can be turned OFF without turning OFF their power supplies using this function.

Select 'Control output OFF function' in [OUT/OFF key function] in Engineering mode 1. Factory default value is Control output OFF function.

(Example) Selecting 'Control output OFF function', and 'PV indication' in [Indication when control output OFF]

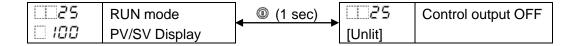


Now, selection is complete.

To turn the control output OFF, press the <a>® key for approximately 1 second on the PV/SV Display. PV is indicated on the PV Display. Indication differs depending on the selection in [Indication when control output OFF].

Once the control output OFF function is enabled, the function cannot be cancelled even if the power to the instrument is turned OFF and ON again.

To cancel the function, press the we again for approx. 1 second.



9.4 Switching Auto/Manual Control (Auto/Manual Control Function)

Control action can be switched from automatic to manual and vice versa.

When power to the controller is turned ON, Automatic or Manual control is selectable.

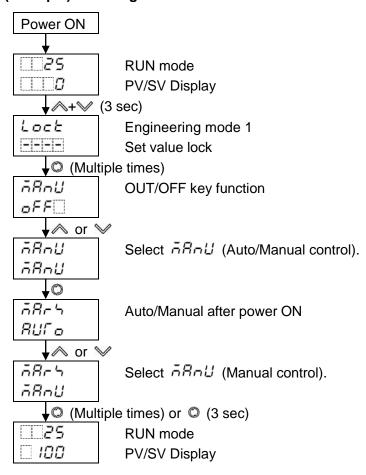
Select 'Auto/Manual control' in [OUT/OFF key function] in Engineering mode 1.

Factory default value is Control output OFF function.

Select 'Automatic control' or 'Manual control' in [Auto/Manual after power ON] in Engineering mode 1.

Factory default value is Automatic control.

(Example) Selecting 'Auto/Manual control 'and 'Manual control' after power ON



Now, selection is complete.

By pressing the we key in PV/SV Display for approx. 1 second, Auto/Manual control function can be switched.

If control action is switched from automatic to manual and vice versa, balanceless-bumpless function works to prevent a sudden change in the MV.

When automatic control is switched to manual control, MV flashes on the SV Display.

The MV on the SV Display can be increased or decreased by pressing the \infty or \infty key.

Data is saved 1 second after MV is changed, and manual control is performed.

When power is turned ON, control resumes using the previously saved MV (if manual control is selected in [Auto/Manual after power ON]).

However, if $\Box DDB$ (Auto/Manual control) is selected in [Event input DI1/DI2 allocation], then Event input status has priority.

By pressing the we key again for approx. 1 second, the unit reverts to automatic control.

□ 100	RUN mode	@ (1 sec)	□ 100	MV flashes (Manual control).
□ 100	PV/SV Display		□ IΩ5	MV increases/decreases with
	(Automatic control)			or ✓ key.

A Caution

Input/Output response time of this instrument is approx. 1 second.

When using as a converter, the converter input will be 1 sec slower due to the response time. (In such cases please use a converter with input time slower than the response time above.)

This instrument can be used as a simplified converter.

Converts each input value (thermocouple, RTD, DC voltage and current inputs) to '4 to 20 mA DC', and outputs it.

When OUT1 is direct current output type, the controller can be used as a converter.

Select 'Converter' in [Controller/Converter] in Engineering mode 1.

Factory default value is 'Controller'.

When this instrument is switched from controller to converter, values in the table below (Table 9.5-1) are automatically set. The SV Display turns blank.

When this instrument is switched from converter to controller, the PV Display indicates $I \cap I$ for 1 second, and factory default values are set.

(Table 9.5-1)

Set Value (or Selection)
Scaling low limit value
Scaling low limit value
Scaling low limit value
Scaling low limit value
AT/AT on startup/Auto-reset Cancel
Scaling span
0
0
0 (Initialized)
(Reset value, calculated by Auto-reset function)
100
0
0
Scaling span
Direct action
Disabled
0 or Input range low limit value (Scaling low limit value)
0 or Input range low limit value (Scaling low limit value)
1.0 (DC voltage, current input: The placement of
the decimal point follows the selection.)
0
Energized

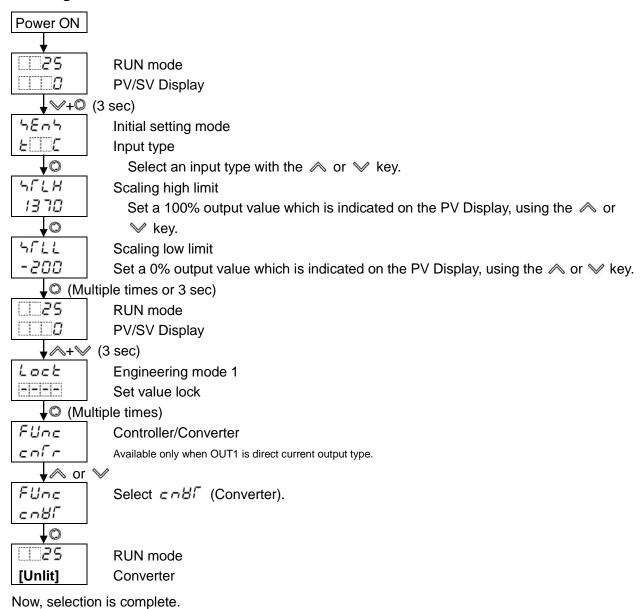
^(*1) When input range is changed while this instrument is used as a converter, SV1 to SV4, OUT1 and OUT2 proportional bands will be automatically set to values corresponding to the input range.

^(*2) If "AT on startup" is successfully completed and "AT on startup Perform" has been still selected, "AT on startup" will be stopped (AT/AT on startup/Auto-reset Cancel).

^(*3) The reset value calculated by Auto-reset function will be initialized.

Setting Item	Set Value (or Selection)
Loop break alarm time	0
Loop break alarm span	0
Event input DI1 allocation (BCS2: EIW, EIT, EI options, BCR2/BCD2: C5W, EIW, EIT, EI options)	No event
Event input DI2 allocation (BCS2: EIW, EI options, BCR2/BCD2: C5W, EIW, EIT, EI options)	No event
Event output EV1 allocation	No event
Event output EV2 allocation (EV2, EV2+D□ options)	No event
Remote/Local (EIT option)	Local
Transmission output type (EIT option)	PV transmission
Transmission output high limit (EIT option)	Input range high limit
Transmission output low limit (EIT option)	Input range low limit
SV rise rate	0
SV fall rate	0
OUT/OFF key function	Control output OFF function

9.5.1 Selecting Converter Function



9.5.2 Fine Adjustment of Converter Output (4 to 20 mA DC)

4 to 20 mA DC will be output corresponding to the input from Scaling low limit to Scaling high limit. Fine adjustment range: 1/Scaling span

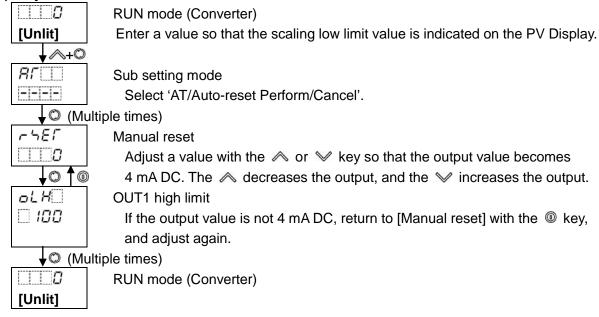
Fine Adjustment Method for Converter Output

Be sure to perform Zero side first in fine adjustment of converter output.

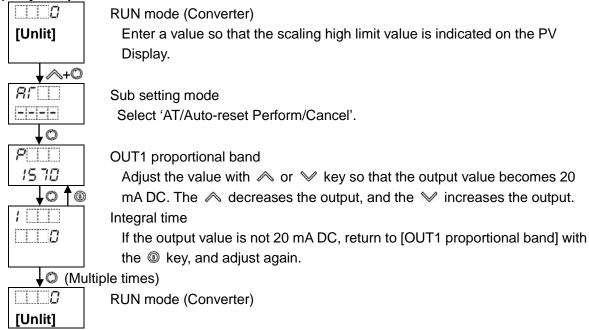
Perform Zero side adjustment in [Manual reset].

Perform Span side adjustment in [OUT1 proportional band].

(1) Adjust Zero side.



(2) Adjust Span side.



(3) Repeat (1) and (2) until the correct value is output.

9.5.3 Converter Setting Example

When the input is any other value except 4 to 20 mA DC Input and output conditions:

Input: 6 to 14 mA DC (Indication: 30.0 to 130.0),

Output: 4 to 20 mA DC

Setting method

(1) Calculating Scaling high and low limit values of 4 to 20 mA DC

Indication value per mA DC: $(130.0 - 30.0) \div (14 - 6) = 100 \div 8 = 12.5$

Scaling high limit value: $130.0 + (20 - 14) \times 12.5 = 205.0$

Scaling low limit value $30.0 - (6 - 4) \times 12.5 = 5.0$

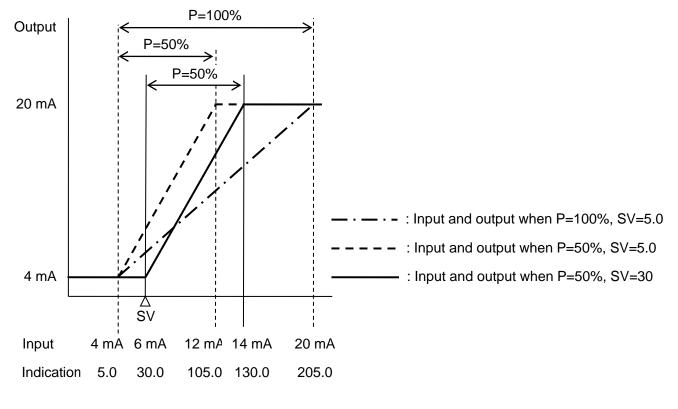
(2) Calculating OUT1 Proportional band of 6 to 14 mA DC (Slope setting)

OUT1 Proportional band (P) = $\{(14-6) \div (20-4)\}$ x 100 = 0.5 x 100 = 50 (%)

(3) Calculating SV (desired value) so that 4 mA DC output can be obtained from 6 mA DC input (Parallel shift setting)

 $SV = \{(6-4) \times 12.5\} + 5.0 \text{ (Scaling low limit)} = 30.0$

Input, Output and Indication



(Fig. 9.5.3-1)

9.6 Clearing Data

If data is cleared, data will revert to factory default values.

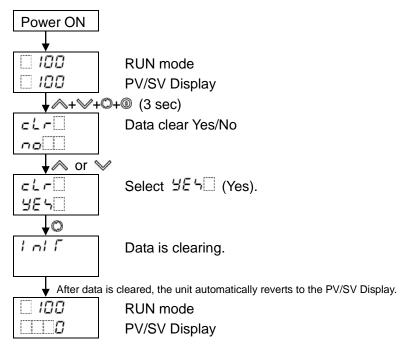
To clear data, press and hold \wedge , \vee , \bigcirc , \bigcirc (in that order) together for approx. 3 seconds on the PV/SV Display.

The unit enters [Data clear Yes/No] mode.

Select 'Yes', and press the O key. Data will be cleared.

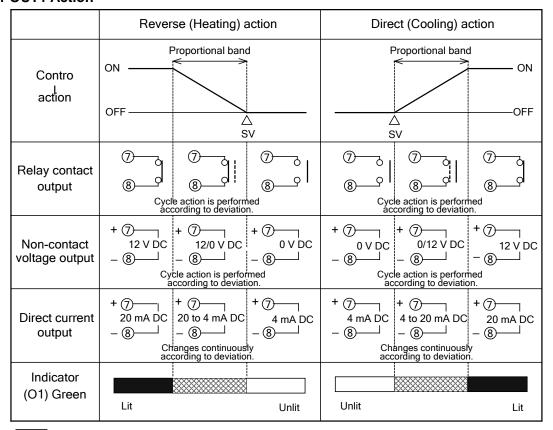
While data is clearing, I of I is indicated on the PV Display.

Clearing Data



10. Action Explanation

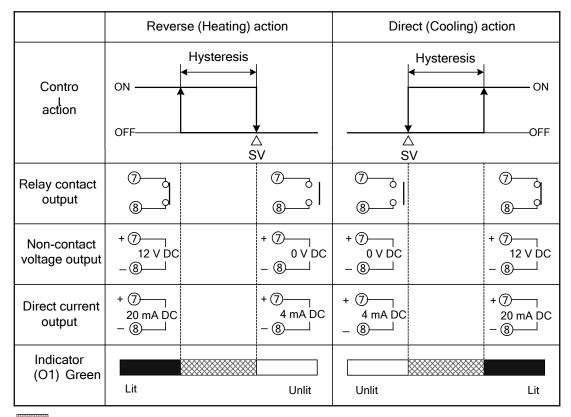
10.1 OUT1 Action



: Turns ON (lit) or OFF (unlit).

BCR2, BCD2: OUT1 terminal numbers become 15, 16.

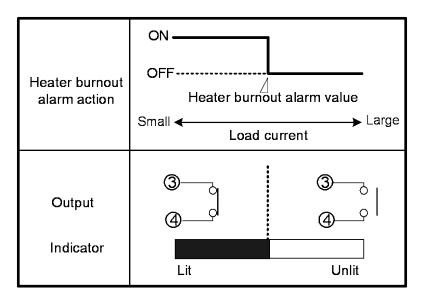
10.2 OUT1 ON/OFF Control Action



: Turns ON (lit) or OFF (unlit).

BCR2, BCD2: OUT1 terminal numbers become 15, 16.

10.3 Heater Burnout Alarm Action

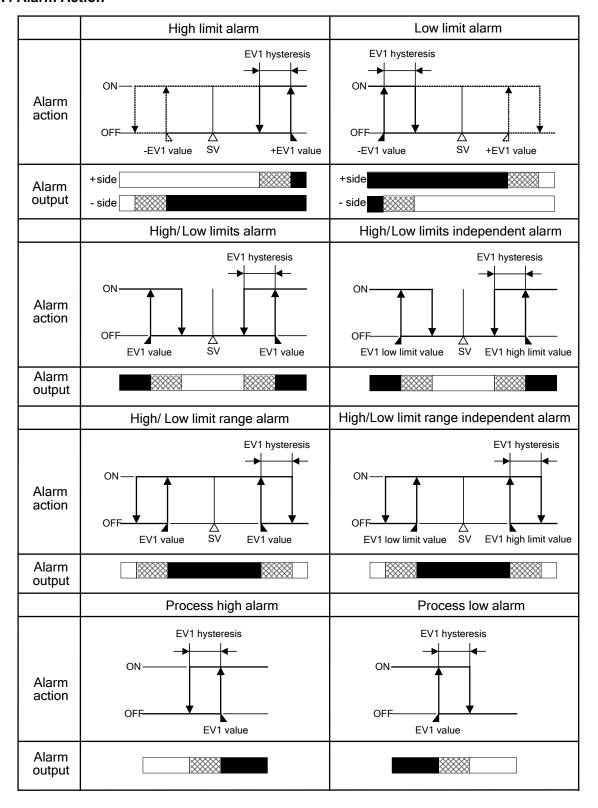


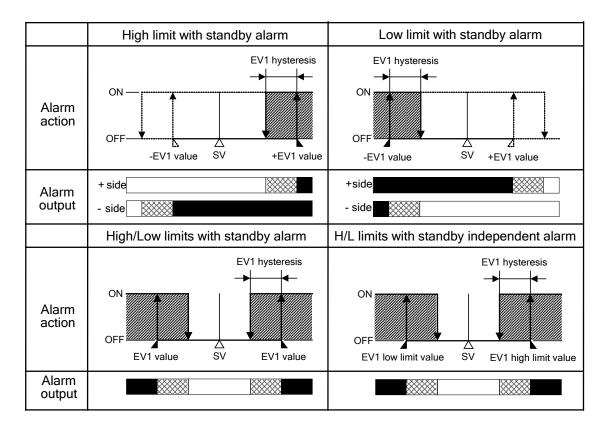
BCS2: Event output 1 terminal numbers become 3, 4. Event output 2 terminal numbers become 5, 6.

BCR2, BCD2: Event output 1 terminal numbers become 17, 18. Event output 2 terminal numbers become 19, 20.

If EV2+D□ option is added: Event output 2 terminal numbers become 6, 7.

10.4 Alarm Action





: Event output 1 terminals 3 and 4: ON (closed).

: Event output 1 terminals 3 and 4: ON (closed) or OFF (open).

: Event output 1 terminals 3 and 4: OFF (open).

: Alarm output is in Standby.

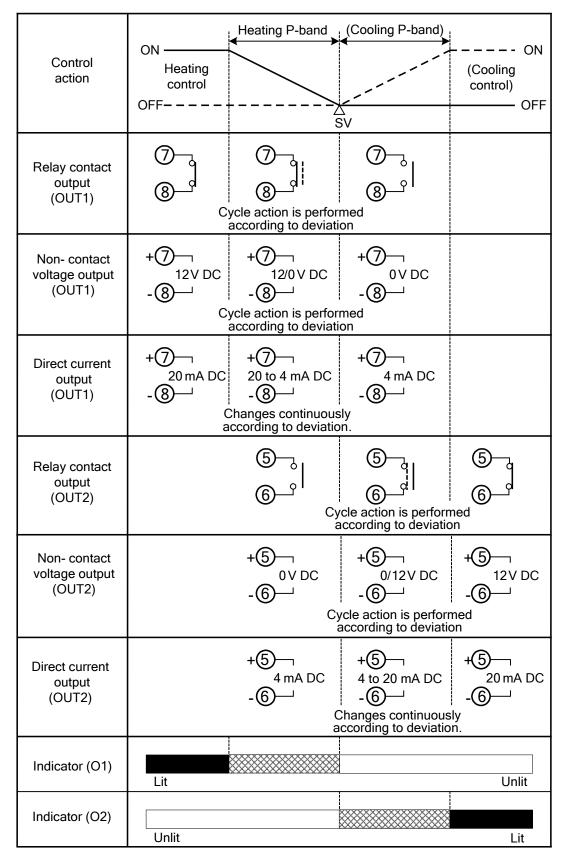
- EV1 value, EV1 high limit value, and EV1 hysteresis represent EV1 alarm value, EV1 high limit alarm value and EV1 alarm hysteresis respectively.
 For EV2, read "EV2" for "EV1".
- EV1 indicator lights when Event output 1 terminals 3 and 4 are ON, and goes off when their output terminals 3 and 4 are OFF.

EV2 indicator lights when Event output 2 terminals 5 and 6 are ON, and goes off when their output terminals 5 and 6 are OFF.

BCR2, BCD2: Event output 1 terminal numbers become 17, 18.
 Event output 2 terminal numbers become 19, 20.

If EV2+D□ option is added: Event output 2 terminal numbers become 6, 7.

10.5 OUT2 (Heating/Cooling Control) Action



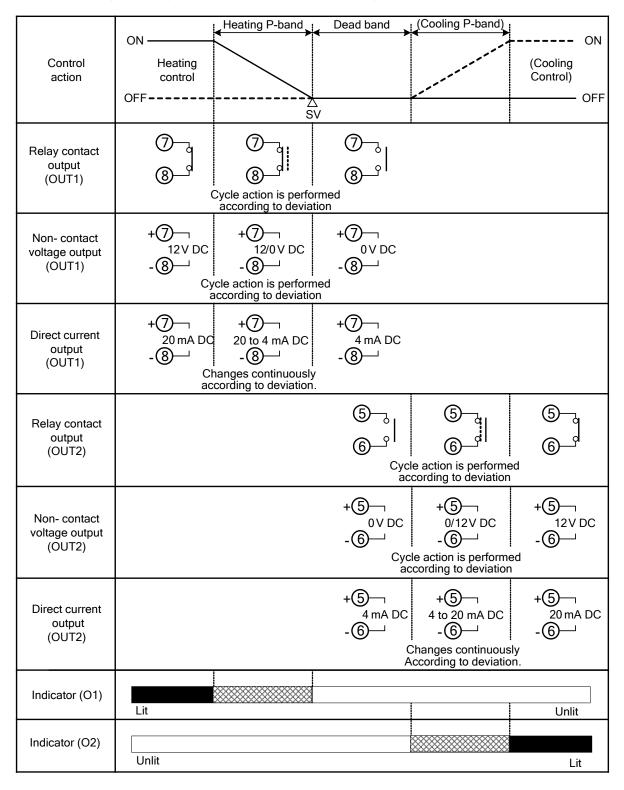
: Turns ON (lit) or OFF (unlit).

—— : Represents Heating control action.

---: Represents Cooling control action.

BCR2, BCD2: OUT1 terminal numbers become 15, 16.
 OUT2 terminal numbers become 19, 20.

10.6 OUT2 (Heating/Cooling Control) Action (When Setting Dead Band)



: Turns ON (lit) or OFF (unlit).

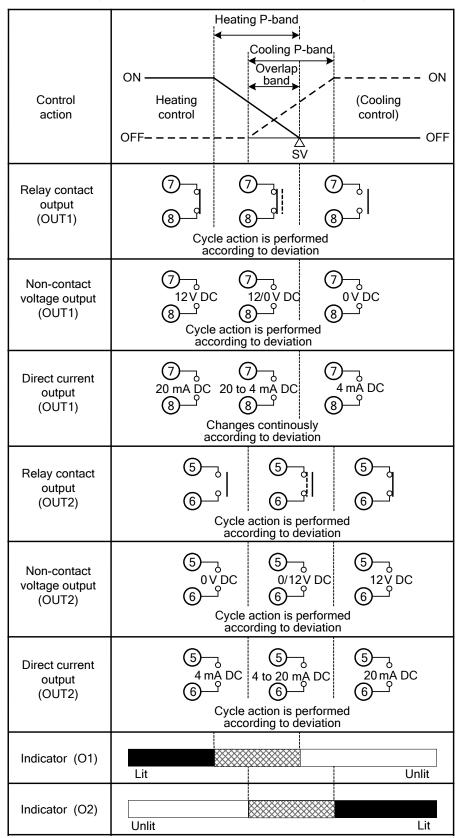
---- : Represents Heating control action.

---: Represents Cooling control action.

• BCR2, BCD2: OUT1 terminal numbers become 15, 16.

OUT2 terminal numbers become 19, 20.

10.7 OUT2 (Heating/Cooling Control) Action (When Setting Overlap Band)



: Alternates between ON (lit) and OFF (unlit).

---- : Represents Heating control action.

---: Represents Cooling control action.

• BCR2, BCD2: OUT1 terminal numbers become 15, 16.

OUT2 terminal numbers become 19, 20.

11. Specifications

11.1 Standard Specifications

Rating

Rated scale		Input	Scale	Range	Resolution
		K	-200 to 1370°C	-328 to 2498°F	1℃ (°F)
		\ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \	-200.0 to 400.0℃	-328.0 to 752.0°F	0.1℃ (°F)
		J	-200 to 1000°C	-328 to 1832°F	1℃ (°F)
		R	0 to 1760°C	32 to 3200°F	1℃ (°F)
		S	0 to 1760°C	32 to 3200°F	1℃ (°F)
		В	0 to 1820℃	32 to 3308°F	1℃ (°F)
		E	-200 to 800°C	-328 to 1472°F	1℃ (°F)
		Т	-200.0 to 400.0℃	-328.0 to 752.0°F	0.1℃ (°F)
		N	-200 to 1300°C	-328 to 2372°F	1℃ (°F)
		PL-II	0 to 1390°C	32 to 2534°F	1℃ (°F)
		C(W/Re5-26)	0 to 2315℃	32 to 4199°F	1℃ (°F)
		D4400	-200.0 to 850.0℃	-328.0 to 1562.0°F	0.1°C (°F)
		Pt100	-200 to 850°C	-328 to 1562°F	1°C (°F)
		ID#400	-200.0 to 500.0℃	-328.0 to 932.0°F	0.1℃ (°F)
		JPt100	-200 to 500°C	-328 to 932°F	1°C (°F)
		4 to 20 mA	-2000 to	10000 (*)	1
		0 to 20 mA	-2000 to	10000 (*)	1
		0 to 1 V	-2000 to 10000 (*)		1
		0 to 5 V	-2000 to 10000 (*)		1
		1 to 5 V	-2000 to 10000 (*)		1
		0 to 10 V	10 V -2000 to 10000 (*) 1		
		(*) Scaling and decimal point place selection are possible.			
Input	Thermocouple	K, J, R, S, B, E, T, N, PL- II, C(W/Re5-26)			
		External resistance: 100 Ω max.			
		However, for B input, External resistance: 40 Ω max.			
	RTD	Pt100, JPt100 3-wire type			
		Allowable input lead wire resistance: 10 Ω max. per wire			
	Direct current	0 to 20 mA DC, 4 to 20 mA DC			
		Input impedance: 50 Ω			
		Allowable input current: 50 mA max.			
	DC voltage	0 to 1 V DC			
		l .	nce: 1 M Ω min.	OV.	
			ut voltage: 5 V DC m		
		Allowable signal source resistance: 2 kΩ max. 0 to 5 V DC, 1 to 5 V DC, 0 to 10 V DC			
		l	·	,0	
Allowable input voltage: 15 V DC max. Allowable signal source resistance: 100 Ω max.		Input impedance: 100 kΩ min. Allowable input voltage: 15 V DC max.			
Power	BC 2 00-	100 to 240 V AC 50/60 Hz			
supply voltage	BC 2 10-	24 V AC/DC 50/60 Hz			
Allowable	BC 2 00-	85 to 264 V AC			
voltage fluctuation	BC 2 10- 20 to 28 V AC/DC				

General Structure

General Structur	i e	7		
External	BCS2	48 x 48 x 68 mm (W x H x D) (Depth of control panel interior: 60 mm)		
dimensions BCR2 48 x 96 x 68 mm (W x H x D) (Depth of control panel			nm (W x H x D) (Depth of control panel interior: 60 mm)	
BCD2		96 x 96 x 68 n	nm (W x H x D) (Depth of control panel interior: 60 mm)	
Mounting		Flush		
Case			nt resin, Black	
Front panel		Membrane sh		
Drip-proof/Dust-	proof		P66, Rear case: IP20, Terminal section: IP00	
Standards	EN	· ·	·	
Standards		EN61010-1 (Pollution degree 2, Overvoltage category Ⅱ) EMI: EN61326		
	EC			
	(EMC	Electric-field strength of radiated disturbance: EN55001 Group 1		
	directive)		Class A	
			e voltage: EN55011 Group 1 Class A	
		EMS: EN6132	26	
Indication	PV Display	Indicates PV.	d LED display	
structure			ed LED display	
		BCS2	Character size: 12.4 x 5.8 mm (H x W)	
		BCR2	Character size: 14 x 5.8 mm (H x W)	
		BCD2	Character size: 24 x 11 mm (H x W)	
	SV Display	Indicates SV.	and ED display	
			een LED display	
		BCS2	Character size: 8.8 x 3.9 mm (H x W)	
		BCR2	Character size: 14 x 5.8 mm (H x W)	
		BCD2	Character size: 14 x 7 mm (H x W)	
	MEMO/STEP	Indicates Set value memory number (Fixed value control) or Step		
	Display	number (Program control). 7-segment Green LED display		
	(BCR2,			
	BCD2)	BCR2	Character size: 14 x 5.8 mm (H x W)	
		BCD2	Character size: 14 x 7 mm (H x W)	
	Action	O1 (Green)	Lit when control output OUT1 is ON.	
	indicators		For direct current output type, flashes corresponding to the MV in 125 ms cycles.	
		O2 (Yellow)	Lit when control output OUT2 (EV2, DS, DA, EV2+D	
		32 (10110W)	options) is ON.	
			For direct current output type (DA, EV2+DA options),	
			flashes corresponding to the MV in 125 ms cycles.	
		EV1 (Red)	Lit when Event output 1 is ON.	
		EV2 (Red)	Lit when Event output 2 (EV2, EV2+D□ options) is	
			ON.	
			Unlit if ### (Heating/Cooling control relay contact	
		ΛΤ (Valla)	output) is selected in [Event output EV2 allocation].	
		AT (Yellow)	Flashes while AT, 'AT on startup' or Auto-reset is performing.	
		R/L (Yellow)	Lit during Remote action from Remote/Local switching (EIT option).	
		T/R (Yellow)	Lit during Serial communication (C5W, C5 options) TX	
		(1511544)	(transmitting) output.	
		MEMO	Lit when Set value memory number (Fixed value	
		(Yellow)	control) is indicated.	
			(BCR2, BCD2)	
		STEP	Lit when a step number (Program control) is indicated.	
		(Green)	(BCR2, BCD2)	

Terminal arrangement	Refer to 'Terminal arrangement'. (p.19)	
Console connector	By connecting to the tool cable (CMD-001, sold separately), the	
	following operations can be conducted from an external computer using	
	the Console software SWC-BCx01M.	
	Reading and setting of SV, PID and various set values	
	Reading of PV and action status	

Setting Structure

Function	UP key	Increases the numeric value.		
key		By pressing this key for 1 second during Program control, the performing		
		step is interrupted, proceeding to the beginning of the next step.		
		(Advance function)		
	DOWN key	Decreases the numeric value.		
	MODE key	Selects a setting mode, or registers the set data.		
		By pressing this key for 3 seconds during RUN mode, the unit enters		
		Monitor mode.		
	OUT/OFF key	The following function can be selected in [OUT/OFF key function].		
		Selection Item Action		
		Control output OFF function	Turns the control output ON or OFF.	
		Auto/Manual control	Switches the Auto/Manual control.	
		Program control	Starts/Stops the Program control.	

Indication Performance

Basic accuracy		At ambient temperature 23°C (for a single unit mounting)	
	Thermocouple	Within ±0.2% of each input span±1 digit	
		However R, S inputs, 0 to 200°C (32 to 392°F): Within ± 6 °C (12°F)	
		B input, 0 to 300℃ (0 to 572°F): Accuracy is not guaranteed.	
		K, J, E, T, N inputs, Less than 0°C (32°F): Within ±0.4% of input	
		span±1 digit	
	RTD	Within ±0.1% of each input span±1 digit	
	Direct current,	Within ±0.2% of each input span±1 digit	
	DC voltage		
Effect of ambient temperature		Within 50 ppm/°C of each input span	
Input sampling period		125 ms	
Time accuracy		Within ±1.0% of setting time	

Control Performance

Control action	PID control (with AT function)
	PI control: When derivative time is set to 0
	PD control (with Auto-reset, Manual reset function):
	When integral time is set to 0
	P control (with Auto-reset, Manual reset function):
	When derivative time and integral time are set to 0.
	ON/OFF control: When proportional band is set to 0 (or 0.0)
OUT1	Thermocouple, RTD inputs without decimal point: 0 to input span
proportional	Thermocouple, RTD inputs with decimal point: 0.0 to input span
band	Direct current, voltage inputs: 0.0 to 1000.0%
Integral time	0 to 3600 sec
Derivative time	0 to 1800 sec
OUT1 propor-	0.5, or 1 to 120 sec
tional cycle	
ARW	0 to 100%

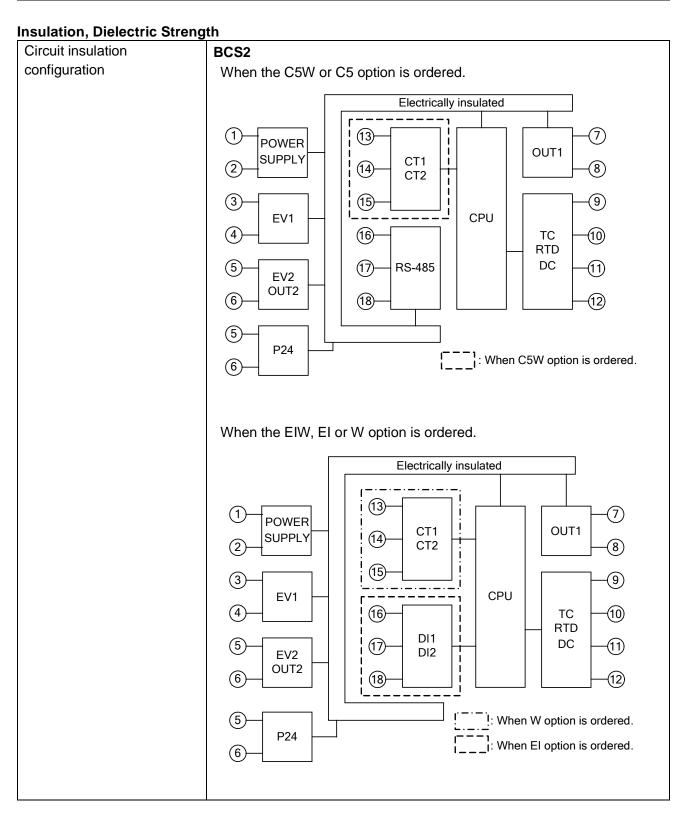
	Manual reset	±Proportional band value
	OUT1 ON/OFF	Thermocouple, RTD inputs: 0.1 to 1000.0°C (°F)
	hysteresis	Direct current, voltage inputs: 1 to 10000 (The placement of the decimal
		point follows the selection.)
	OUT1 high limit, OUT1 low limit	0 to 100% (Direct current output type: -5 to 105%)
Control	Relay contact	Control capacity: 3 A 250 V AC (resistive load)
output	1a	1 A 250 V AC (inductive load cos ≠=0.4)
		Electrical life: 100,000 cycles
		Minimum applicable load: 10 mA 5 V DC
	Non-contact	12 V DC±15%
	voltage (For SSR drive)	Max 40 mA (short circuit protected)
	Direct current	4 to 20 mA DC
		Resolution: 12000
		Load resistance: Max. 550 Ω

Standard Function

Standard F	arrotion	T		
EV1 outpu	t	The output is turned ON or OFF depending on the conditions selected in		
		[Event output EV1 allocation].		
		Relay contact 1a Control capacity: 3 A 250 V AC (resistive load)		
		1 A 250 V AC (inductive load $\cos\phi$ =0.4)		
		Electrical life: 100,000 cycles		
		Minimum applicable load: 10 mA 5 V DC		
Alarm action	on	When an alarm type and Energized action are selected in [Event output		
		EV1 allocation] or [Event output EV2 allocation]: The alarm action point		
		is set by ±deviation from the SV (excluding Process alarm) and if PV		
		goes outside the range, alarm output is turned ON or OFF (High/Low		
		limit range alarm).		
		When De-energized action is selected, alarm is activated conversely.		
	Туре	High limit alarm, Low limit alarm, High/Low limits alarm, High/Low limits		
		independent alarm, High/Low limit range alarm, High/Low limit range		
		independent alarm, Process high alarm, Process low alarm, High limit		
		with standby alarm, Low limit with standby alarm, High/Low limits with		
		standby alarm, High/Low limits with standby independent alarm		
		Energized/De-energized action are applied to the above alarms, totaling		
		24 alarm types. No alarm action can also be selected.		
	Action	ON/OFF action		
	Hysteresis	Thermocouple, RTD inputs: 0.1 to 1000.0°C (°F)		
		Direct current, voltage inputs: 1 to 10000 (The placement of the decimal point follows the selection.)		
	Output	EV1 output or EV2 output for which Alarm output (001 to 012) is		
		selected in [Event output EV1/EV2 allocation].		
	Alarm value 0	If 'Enabled' is selected in [Alarm value 0 Enabled/Disabled], the		
	Enabled/	following alarm type activates even if alarm value is set to 0 (zero):		
	Disabled	High limit alarm, Low limit alarm, High/Low limits alarm, High/Low limits		
		independent alarm, High/Low limit range alarm, High/Low limit range		
		independent alarm, High limit with standby alarm, Low limit with standby		
		alarm, High/Low limits with standby alarm, High/Low limits with standby		
		independent alarm.		
Loop break	k alarm	Detects heater burnout, sensor burnout and actuator trouble.		
		Event output EV1 or Event output EV2 for which Loop break alarm (014)		
		is selected in [Event output EV1/EV2 allocation].		

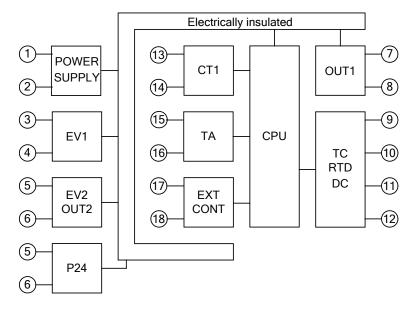
Simplified converter	If 'Converter' is selected in [Controller/Converter], this instrument can		
function	be used as a converter. The follo	pwing items are automatically set.	
	Setting Item	Values or Selection	
	SV1	Scaling low limit value	
	SV2	Scaling low limit value	
	(BCS2: EIW, EIT, EI options,		
	BCR2/BCD2: C5W, EIW, EIT, EI options)		
	SV3	Scaling low limit value	
	(BCS2: EIW, EI options,		
	BCR2/BCD2: C5W, EIW, EIT, EI options)		
	SV4	Scaling low limit value	
	(BCS2: EIW, EI options,		
	BCR2/BCD2: C5W, EIW, EIT, EI options)		
	AT/Auto-reset Perform/Cancel	AT/AT on startup/Auto-reset Cancel	
	OUT1 proportional band	Scaling span	
	Integral time	0	
	Derivative time	0	
	Reset	(Initialized) (Reset value calculated by Auto-reset function)	
	OUT1 high limit	100	
	OUT1 low limit	0	
	OUT1 rate-of-change	0	
	OUT2 proportional band	Scaling span	
	Direct/Reverse action	Direct action	
	EV1/EV2 alarm value 0	Disabled	
	Enabled/Disabled		
	EV1/EV2 alarm value	0 or Input range low limit value (Scaling	
		low limit value)	
	EV1/EV2 high limit alarm value	0 or Input range low limit value (Scaling	
		low limit value)	
	EV1/EV2 alarm hysteresis	1.0 (DC voltage, current inputs: The	
		placement of the decimal point follows	
		the selection.)	
	EV1/EV2 alarm delay time	0	
	EV1/EV2 alarm Energized/	Energized	
	De-energized		
	Loop break alarm time	0	
	Loop break alarm span	0	
	Event input DI1 allocation	000: No event	
	(BCS2: EIW, EIT, EI options,		
	BCR2/BCD2: C5W, EIW, EIT, EI options)		
	Event input DI2 allocation	000: No event	
	(BCS2: EIW, EI option,		
	BCR2/BCD2: C5W, EIW, EIT, EI options)		
	Event output EV1 allocation	000: No event	
	Event output EV2 allocation	000: No event	
	(EV2, EV2+D options)		
	Remote/Local (EIT option)	Local	
	[(L11 OP(IOII)		

Transmission output type (EIT option)	PV transmission
Transmission output high limit (EIT option)	Input range high limit
Transmission output low limit (EIT option)	Input range low limit
SV rise rate	0
SV fall rate	0
OUT/OFF key function	Control output OFF
4 to 20 mA DC Load resistance: Max 550 Ω	



Circuit insulation configuration

When the EIT option is ordered.

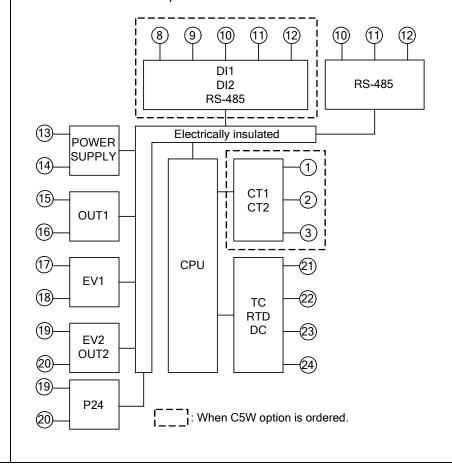


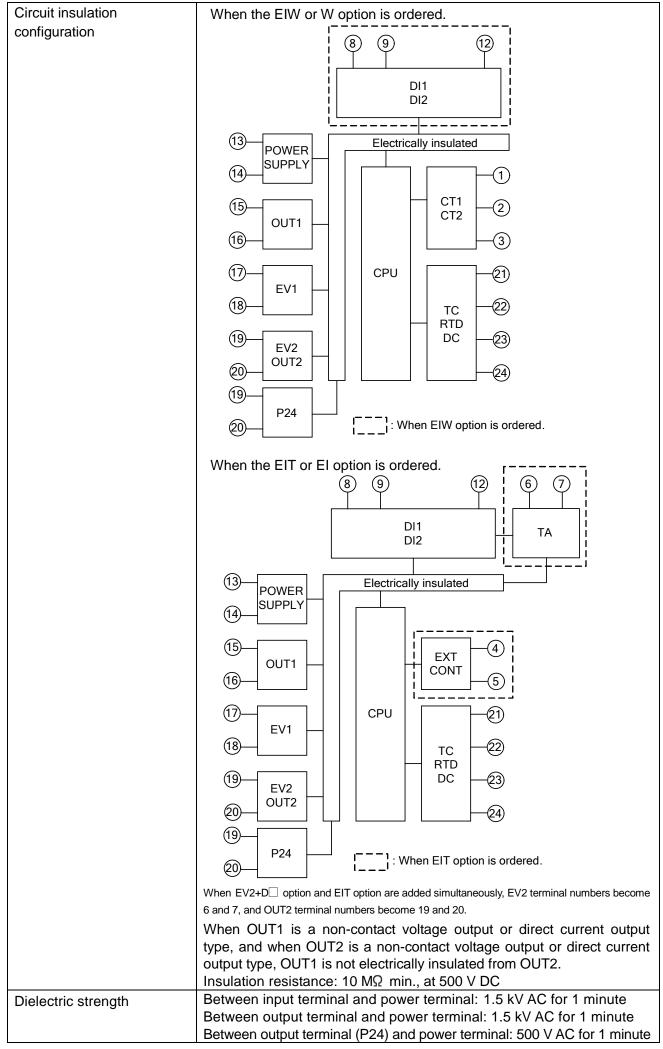
When OUT1 is a non-contact voltage output or direct current output type, and when OUT2 is a non-contact voltage output or direct current output type, OUT1 is not electrically insulated from OUT2.

Insulation resistance: 10 M Ω min., at 500 V DC

BCR2, BCD2

When the C5W or C5 option is ordered.





Power consumption		100 to 240 V AC	Approx. 8 VA max. (When the maximum number of	
			options are added: Approx. 11 VA max.)	
		24 V AC	Approx. 5 VA max. (When the maximum number of	
			options are added: Approx. 8 VA max.)	
		24 V DC	Approx. 5 W max. (When the maximum number of	
			options are added: Approx. 8 W max.)	
Rush current		100 to 240 V AC	Max. 14 to 34 A	
		24 V AC	Max. 34 A	
		24 V DC	Max. 34 A	
Ambient tempo	erature	-10 to 55℃ (Non-condensing, No icing)		
Ambient humi	dity	35 to 85 %RH (Non-condensing)		
Weight	BCS2	Approx. 110 g		
	BCR2	Approx. 160 g		
	BCD2	Approx. 220 g		
Accessories in	ncluded	Mounting frame: 1 piece (BCS2)		
		Screw type mounting bracket: 1 set (BCR2, BCD2)		
		Instruction manual (excerpt): 1 copy		
Accessories s	old	Terminal cover		
separately		CT (Current transformer):		
		CTL-6S (For Heater burnout alarm 20 A)		
		CTL-12-S36-10L1U (For Heater burnout alarm 100 A)		
		Tool cable CMD-001		
Environmental specification		RoHS directive compliant		

Attached Functions

Sensor correction coefficient		Sets slope of input value from a sensor.	
Sensor cor	rection	Corrects the input value from a sensor.	
Set value lo	ock	Locks the set values to prevent setting errors.	
Auto/Manu	al control	Switches Auto/Manual control.	
switching		In Manual control, sets MV with the	
SV ramp fu	ınction	When the SV is adjusted, it approaches the new SV by the preset	
		rate-of-change. Set SV rise rate and SV fall rate respectively.	
SV Rise/Fa	all rate start type	When control output is turned from OFF to ON, or switched from Manual	
		to Automatic control, SV start or PV start can be selected for SV rise rate	
		or SV fall rate action.	
Program co	ontrol	1 pattern; 9 steps	
Power failu counterme	-	The setting data is backed up in the non-volatile IC memory.	
Self-diagno	osis	The CPU is monitored by a watchdog timer, and if an abnormal status	
		occurs, the controller is switched to warm-up status, turning all outputs OFF.	
Automatic	cold junction	This detects the temperature at the connecting terminal between the	
temperatur	e compensation	thermocouple and the instrument, and always maintains it at the same	
		status as if the reference junction location temperature was at 0°C (32°F).	
Indication	Thermocouple	[Input range low limit value – 50°C (100°F)] to	
range,		[Input range high limit value + 50°C (100°F)]	
Control RTD [Input range low limit value – (Input span x 1%)] to		[Input range low limit value – (Input span x 1%)] to	
range		[Input range high limit value + 50° (100°F)]	
	DC voltage,	[Scaling low limit value – (Scaling span x 1%)] to	
	Direct current	[Scaling high limit value + (Scaling span x 10%)]	

If input errors (overscale, underscale) occur, the following will be Input error (Overscale, Underscale) performed depending on the selection in [Error indication Enabled/ Disabled]. If Disabled is selected in [Error indication Enabled/Disabled]: Overscale occurs if PV has exceeded Input range high limit value (Scaling high limit value for DC voltage, current inputs). The PV Display indicates PV. Underscale occurs if PV has dropped below Input range low limit value (Scaling low limit value for DC voltage, current inputs). The PV Display indicates PV. For manual control, the preset MV is output. If Enabled is selected in [Error indication Enabled/Disabled]: Overscale occurs if PV has exceeded Input range high limit value (Scaling high limit value for DC voltage, current inputs). The PV Display indicates the PV and error code $\mathcal{E} \cap \mathcal{G} \mathcal{G}$ alternately. Underscale occurs if PV has dropped below Input range low limit value

(Scaling low limit value for DC voltage, current inputs). The PV Display

indicates the PV and error code $\mathcal{E} \cap \mathcal{G} \mathcal{E}$ alternately.

For manual control, the preset MV is output.

Burnout

If burnout occurs, the following will be performed depending on the selection in [Error indication Enabled/Disabled].

If Disabled is selected in [Error indication Enabled/Disabled]:

1.

If PV has exceeded Indication range and Control range, the PV Display flashes []. If PV has dropped below Indication range and Control range, the PV Display flashes [____]. If thermocouple or RTD input is burnt out, or if DC voltage (0 to 1 V DC) input is disconnected, the PV Display flashes [

If DC voltage or current input is disconnected:

For 4 to 20 mA DC, 1 to 5 V DC inputs, the PV Display flashes [_ _ _ _].

For 0 to 20 mA DC, 0 to 5 V DC and 0 to 10 V DC inputs, the PV Display indicates the value corresponding with 0 mA DC or 0 V DC input.

OUT1 and OUT2 are turned OFF (OUT1 low limit value for direct current output, OUT2 low limit value for DA, EV2+DA). For manual control, the preset MV is output.

If Alarm, Heater burnout alarm or Loop break alarm is selected in [Event output EV1/EV2 allocation], Event output will be turned ON under the alarm active conditions.

Burnout is enabled even in standby (program control waiting) mode in Program control.

[Output status when input errors occur] can be used only for controllers using direct current and voltage inputs, and direct current output.

Output status differs depending on selection in [Output status when input errors occur].

Output status	·	Output Status			
when input	Contents,	OUT1		OUT2	
errors occur	Indication	Direct (Cooling)	Reverse (Heating)	Direct (Cooling)	Reverse (Heating)
Onoro occar		action	action	action	action
		ON (20mA) or			ON or
on III		OUT1 high limit	OFF (4mA) or	OFF or OUT2 low limit value	OUT2 high limit
	is flashing.	value (*)	OUT1 low limit		value (*)
oFF		OFF (4mA) or	value		OFF or
		OUT1 low limit			OUT2 low limit
		value			value
			ON (20mA) or	ON or	
on	l	OFF (4mA) or OUT1 low limit value	OUT1 high	OUT2 high	OFF or
			limit value (*)	limit value (*)	OUT2 low limit
			OFF (4mA) or	OFF or	value
oFF			OUT1 low limit	OUT2 low limit	value
			value	value	

^(*) Outputs a value between OFF (4mA) and ON (20mA) or between OUT1 (or OUT2) low limit value and OUT1 (or OUT2) high limit value, depending on deviation.

If Enabled is selected in [Error indication Enabled/Disabled]:

If PV has exceeded Indication range, Control range, the PV Display indicates $[\ \ \ \]$ and $[\ \ \ \ \ \ \]$ alternately.

If PV has dropped below Indication range, Control range, the PV Display indicates [---] and $[E \cap G]$ alternately.

If thermocouple, RTD or DC voltage (0 to 1 V DC) input is burnt out or disconnected, the PV Display indicates [\Box] and [$E \cap \Box$] alternately.

If DC voltage or current input is disconnected:

For 4 to 20 mA DC, 1 to 5 V DC inputs, the PV Display indicates [$____$] and [\not E r $\vec{\Box}$ $\vec{\Box}$] alternately. For 0 to 20 mA DC, 0 to 5 V DC and 0 to 10 V DC inputs, the PV Display indicates the value corresponding with 0 mA DC or 0 V DC input.

OUT1 and OUT2 are turned OFF (OUT1 low limit value for direct current output type, OUT2 low limit value for DA, EV2+DA).

For Manual control, the preset MV is output.

If Alarm, Heater burnout alarm or Loop break alarm is selected in [Event output EV1/EV2 allocation], Event output will be turned ON under the alarm active conditions.

In Program control, burnout is enabled even in standby (program control waiting) mode.

[Output status when input errors occur] can be used only for controllers using direct current and voltage inputs, and direct current output.

Output status differs depending on selection in [Output status when input errors occur].

Output status		Output Status			
when input	Contents,	OUT1		OUT2	
errors occur	Indication	Direct (Cooling)	Reverse (Heating)	Direct (Cooling)	Reverse (Heating)
Citors occur		action	action	action	action
on	Indicates [] and	ON (20mA) or OUT1 high limit value (*)	OFF (4mA) or	OFF or	ON or OUT2 high limit value (*)
oFF.	[E - [] 7] alternately.	OFF (4mA) or OUT1 low limit value	OUT1 low limit value	OUT2 low limit value	OFF or OUT2 low limit value
on	Indicates [] and	OFF (4mA) or OUT1 low limit	ON (20mA) or OUT1 high limit value (*)	ON or OUT2 high limit value (*)	OFF or OUT2 low limit
oFF	[E - [] 7] alternately.	value	OFF (4mA) or OUT1 low limit value	OFF or OUT2 low limit value	value

^(*) Outputs a value between OFF (4mA) and ON (20mA) or between OUT1 (or OUT2) low limit value and OUT1 (or OUT2) high limit value, depending on deviation.

Warm-up indication	After the power supply to the instrument is turned on, the PV Display indicates the input type, and SV Display indicates input range high limit value (for thermocouple, RTD inputs) or scaling high limit value (for direct current and voltage inputs) for approximately 3 seconds.
Console	By connecting to the tool cable (CMD-001, sold separately) to the
communication	console connector, the following operations can be conducted from an external computer, using the Console software SWC-BCx01M. Console communication and Serial communication (C5W option) cannot be used together. (1) Reading and setting of SV, PID and various set values (2) Reading of PV and action status (3) Function change Communication line: TTL level

11.2 Optional Specifications

1.2 Optional Specifications	
Event input	2 points of Event input (BCS2: 1 point for EIT option) can be applied.
BCS2: EIW, EIT, EI options	Any Event selected in [Event input DI1/DI2 allocation] will be performed
BCR2/BCD2: C5W, EIW,	depending on the DI1/DI2 input ON (Closed) or OFF (Open) status.
EIT, EI options	Circuit current when Closed: Approx. 16 mA
Event output	Output will be turned ON or OFF depending on the Event conditions
(EV2, EV2+D□ options)	selected in [Event output EV2 allocation].
	Relay contact, 1a
	Control capacity: 3 A 250 V AC (resistive load)
	1 A 250 V AC (inductive load, $\cos\phi$ =0.4)
	Electrical life: 100,000 cycles
	Minimum applicable load: 10 mA 5 V DC
Heater burnout alarm	Monitors heater current with CT (current transformer), and detects burnout.
(C5W, EIW, W options)	EV1/EV2 output, for which Heater burnout alarm is selected in [Event output
	EV1/EV2 allocation], will be turned ON or OFF.
	This alarm is also activated when the input is burnt out.
	Rated current: 20 A, 100 A (Must be specified when ordering.)
	Single-phase: Detects burnout with CT1 input.
	3-phase: Detects burnout with CT1 and CT2 inputs.
	Setting accuracy: Within ±5% of the rated value
Heating/Cooling control	Performs Heating/Cooling control.
(DS, DA, EV2, EV2+D□	(Heating side specifications are the same as those of OUT1.)
options)	OUT2 proportional band:
	Thermocouple, RTD inputs without decimal point: 0 to Input span
	Thermocouple, RTD inputs with decimal point: 0.0 to Input span
	DC voltage, current inputs: 0.0 to 1000.0%
	OUT2 integral time: Same as OUT1 integral time
	OUT2 derivative time: Same as OUT1 derivative time
	OUT2 proportional cycle: 0.5, or 1 or 120 seconds
	Overlap/Dead band setting range:
	Thermocouple, RTD inputs: -200.0 to 200.0°C (°F)
	DC voltage, current inputs: -2000 to 2000 (The placement of the decimal
	point follows the selection.)
	OUT2 ON/OFF hysteresis:
	Thermocouple, RTD inputs: 0.1 to 1000.0°C (°F)
	DC voltage, current inputs: 1 to 10000 (The placement of the decimal point
	follows the selection.)
	OUT2 high limit: 0 to 100% (Direct current output: -5 to 105%)
	OUT2 low limit: 0 to 100% (Direct current output: -5 to 105%)
	OUT2 cooling method:
	One cooling method can be selected from Air cooling (linear
	characteristics), Oil cooling (1.5th power of the linear characteristics)
	and Water cooling (2nd power of the linear characteristics) by keypad
	operation.
	Cooling output (OUT2):
	Relay contact 1a (EV2, EV2+DR)
	Control capacity: 3 A 250 V AC (resistive load)
	1 A 250 V AC (inductive load, $\cos\phi$ =0.4)
	Electrical life: 100,000 cycles
	Non-contact voltage (for SSR drive) (DS, EV2+DS): 12 V DC±15%,
	Max. 40 mA (short circuit protected)
	Direct current (DA, EV2+DA): 4 to 20 mA DC
	Resolution: 12000
	Load resistance: Max. 550 Ω
	LOAG TESISTATICE: IVIAX. DOU 1/2

Serial communication			be carried out from an e		
(C5W, C5 options)	Serial communication and Console communication cannot be used together.		innoi de usea		
		otting of the	SV DID values and varie	oue est values	
	(1) Reading and s	•	e SV, PID values and vario	ous set values	
	, , <u> </u>		on status		
	(3) Function chang		abla rasistanas, Within E	O O (Tarminatara ara	
	1		able resistance: Within 5	,	
	not side	•	but if used, use 120 Ω c	or more on both	
	Communication li	,	-485		
			f-duplex communication		
			rt-stop synchronization		
	1 -		, 19200, 38400 bps (Sele	ectable by keypad)	
	Data bit/Parity:		,, - (
	Data bit: 7 bits,	8 bits.			
			(Selectable by keypad)		
	Stop bit: 1 bit, 2 b		` ' ' '		
	· ·	•	nko protocol/Modbus AS	CII/Modbus RTU	
			electable by keypad)		
	Data format:	(,		
	Communication	Shinko	M - II - A00II	M. II . DTII	
	protocol	protocol	Modbus ASCII	Modbus RTU	
	Start bit	1	1	1	
	Data bit	7	7 (8) Selectable	8	
	Parity	Even	Even (No parity, Odd) Selectable	No parity (Even, Odd) Selectable	
	Stop bit	1	1 (2)	1 (2)	
	Selectable Selectable Substituting Selectable Sel				
				•	
	Communication error detection: Parity, checksum (Shinko protocol), LRC (Modbus ASCII), CRC-16 (Modbus RTU)				
	Digital external setting:				
	Receives digital SV from Shinko programmable controllers (PC-900,				
	PCD-33A with S	SVTC option	n).		
External setting input	SV adds external	analog sign	al to remote bias value.		
(EIT option)	Not available for F	Program cor	ntrol.		
	Setting signal: 4 to	20 mA DC	;		
	Allowable input: 5	0 mA DC m	ax.		
	Input impedance:	50 Ω max.			
	Input sampling pe	riod: 125 m	S		
Transmission output	Converting the value (PV, SV, MV or DV transmission) to analog signal				
(EIT option)	every 125 ms, ou	tputs the va	llue in current or voltage).	
	Outputs Transmis	sion output	low limit value if Transn	nission output high	
	limit and low limit	value are tl	he same.		
	Resolution: 12000)			
	Output: 4 to 20 m	A DC (Load	d resistance: Maximum 5	550 Ω)	
	Output accuracy:	Within ±0.	3% of Transmission out	put span	
Insulated power output	Output voltage: 24	1±3 V DC (when load current is 30 r	mA DC)	
(P24 option)	Ripple voltage: Within 200 mV DC (when load current is 30 mA DC)			is 30 mA DC)	
	Max. load current:	30 mA DC			

12. Troubleshooting

If any malfunctions occur, refer to the following items after checking that power is being supplied to the controller.

12.1 Indication

Problem	Possible Cause	Solution
The PV Display indicates [<i>E r 🏻 l</i>].	Internal non-volatile IC memory is defective.	Cancel the error code by pressing the key, and perform data clearing. (p.108) If the problem is not still solved, contact our agency or us.
The PV Display indicates [E - 02].	Data writing (in non-volatile IC memory) error when power failure occurs.	Cancel the error code by pressing the © key, and perform data clearing. (p.108)
The PV Display indicates PV and [£ - 05] (*) alternately.	Overscale. PV has exceeded Input range high limit value (scaling high limit value for DC voltage, current inputs).	Check the input signal source.
The PV Display indicates PV and [£ - 05] (*) alternately.	Underscale. PV has dropped below Input range low limit value (scaling low limit value for DC voltage, current inputs).	Check the input signal source and wiring of input terminals.
The PV Display indicates [].	PV has exceeded the Indication range and Control range.	Check the input signal source.
The PV Display indicates [] and [$\mathcal{E} \cap \mathcal{G} \cap \mathcal{G}$] (*) alternately.	Burnout of thermocouple, RTD or disconnection of DC voltage (0 to 1 V DC)	Replace each sensor. How to check whether the sensor is burnt out [Thermocouple] If the input terminals of the instrument are shorted, and if a value around room temperature is indicated, the instrument is likely to be operating normally, however, the sensor may be burnt out. [RTD] If approx. 100 Ω of resistance is connected to the input terminals between A-B of the instrument and between B-B is shorted, and if a value around 0°C (32°F) is indicated, the instrument is likely to be operating normally, however, the sensor may be burnt out. [DC voltage (0 to 1 V DC)] If the input terminals of the instrument are shorted, and if a scaling low limit value is indicated, the instrument is likely to be operating normally, however, the signal wire may be disconnected.
	Check whether the input terminals of thermocouple, RTD or DC voltage (0 to 1 V DC) are securely mounted to the instrument input terminals.	Connect the sensor terminals to the instrument input terminals securely.

^(*) Indicates when Enabled is selected in [Error indication Enabled/Disabled].

Problem	Possible Cause	Solution
The PV Display	PV has dropped below the	Check the input signal source and wiring of input
indicates [].	Indication range and Control	terminals.
	range.	
The PV Display	Check whether input signal	How to check whether the input signal wire is
indicates []	wire for DC voltage (1 to 5 V	disconnected [DC voltage (1 to 5 V DC)]
and [<i>E - □</i> 7] (*)	DC) or direct current (4 to 20	If the input to the input terminals of the instrument
alternately.	mA DC) is disconnected.	is 1 V DC and if a scaling low limit value is
		indicated, the instrument is likely to be operating
		normally, however, the signal wire may be disconnected.
		[Direct current (4 to 20 mA DC)]
		If the input to the input terminals of the instrument
		is 4 mA DC and if a scaling low limit value is
		indicated, the instrument is likely to be operating
		normally, however, the signal wire may be
		disconnected.
	Check whether input signal	Connect the input signal wire to the terminals of this instrument securely.
	wire for DC voltage (1 to 5 V DC) or current (4 to 20 mA	tills illistrament securely.
	DC) is securely connected to	
	the instrument input terminals.	
	Check if polarity of thermo-	Wire them correctly.
	couple or compensating lead	
	wire is correct.	
	Check whether codes (A, B,	
	B) of RTD agree with the	
	instrument terminals. Hardware malfunction	Contact our agoney or us
The PV Display	Haidware mailunction	Contact our agency or us.
indicates [<i>E r I□</i>].	0	Describe a least for a reserve 4 and a second to a second
The PV Display	Control output OFF function is enabled.	Press the key for approx. 1 second to cancel the function.
indicates [aFF],	is eriabled.	the fallotton.
nothing or PV.	Charle whather a page input	Colort the concer input and tomporature unit (°C
The indication of PV Display is irregular	Check whether sensor input	Select the sensor input and temperature unit ($^{\circ}$ C or $^{\circ}$ F) correctly.
or unstable.	or temperature unit (°C or °F) is correct.	or 1 / concoury.
	Sensor correction coefficient	Set them to suitable values.
	or Sensor correction value is	
	unsuitable.	
	Check whether the sensor	Use a sensor with appropriate specifications.
	specification is correct.	
	AC leaks into the sensor	Use an ungrounded type sensor.
	circuit.	
	There may be equipment that	Keep the instrument clear of any potentially
	interferes with or makes noise	disruptive equipment.
	near the instrument.	

^(*) Indicates when Enabled is selected in [Error indication Enabled/Disabled].

Problem	Possible Cause	Solution
The PV Display keeps indicating the value set in [Scaling low limit].	Check whether the input signal wire for DC voltage (0 to 5 V DC, 0 to 10 V DC) and direct current (0 to 20 mA DC) is disconnected.	Check the input signal wires of DC voltage (0 to 5 V DC, 0 to 10 V DC) and direct current (0 to 20 mA DC). How to check whether the input signal wire is disconnected [DC voltage (0 to 5 V DC, 0 to 10 V DC)] If the input to the input terminal of this controller is 1 V DC, and if a value (converted value from scaling high, low limit setting) corresponding to 1 V DC is indicated, the controller is likely to be operating normally, however, the input signal wire may be disconnected. [Direct current (0 to 20 mA DC)] If the input to the input terminal of this controller is 4 mA DC, and if a value (converted value from scaling high, low limit setting) corresponding to 4 mA DC is indicated, the controller is likely to be operating normally, however, the input signal wire may be disconnected.
	Check whether the input terminals for DC voltage (0 to 5 V DC, 0 to 10 V DC) or direct current (0 to 20 mA DC) are securely connected to the instrument input terminals.	Connect the input terminals of DC voltage and current to the input terminals of this instrument securely.

12.2 Key Operation

Problem	Possible Cause	Solution
None of the set	Set value lock (Lock 1 or	Release the lock in [Set value lock].
values can be set.	Lock 4) is selected.	
	AT, 'AT on startup' or	If AT or 'AT on startup' is performing, cancel AT or
	Auto-reset is performing.	'AT on startup'.
		Please wait until Auto-reset is finished.
		(It takes approximately 4 minutes until Auto-reset
		is finished.)
Only SV and Alarm	Set value lock (Lock 2 or	Release the lock in [Set value lock].
value can be set.	Lock 5) is selected.	
Other settings are		
impossible.		
The setting	Scaling high or low limit value	Set it to a suitable value.
indication does not	may be set at the point where	
change in the input	the value does not change.	
range, and new		
values are unable to		
be set.		

12.3 Control

Problem	Possible Cause	Solution
Temperature does	Sensor is out of order.	Replace the sensor.
not rise.	Check whether the sensor or control output terminals are securely mounted to the instrument input terminals.	Ensure that the sensor or control output terminals are mounted to the instrument input terminals securely.
	Check whether the wiring of sensor or control output terminals is correct.	Wire them correctly.
The control output remains in an ON status.	OUT1 (or OUT2) low limit value is set to 100% or higher.	Set it to a suitable value.
The control output remains in an OFF status.	OUT1 (or OUT2) high limit value is set to 0% or less.	Set it to a suitable value.
The PV display indicates [E r 20].	AT or 'AT on startup' has not been completed even if approx. 4 hours have elapsed since AT or 'AT on startup' started. For 'AT on startup', PV slope and delay time cannot be measured normally for P, I, D calculation.	Set P, I, D and ARW values manually

For all other malfunctions, please contact our main office or dealers.

13. Character Table

13.1 Error Code

Error codes are indicated on the PV Display.

Error Code	Error Contents	Occurrence
E-0 !	Internal non-volatile IC memory is defective.	When power
		is turned ON.
E-02	Data writing (in non-volatile IC memory) error when power failure	When power
	occurs.	is turned ON.
E-05 (*)	PV has exceeded Input range high limit value (Scaling high limit	When
	value for DC voltage, current inputs).	operating
E-05 (*)	PV has dropped below Input range low limit value (Scaling low limit	When
	value for DC voltage, current inputs).	operating
E-07 (*)	Input burnout or disconnection.	When
	Input value is outside of the Indication range and control range.	operating
Er 10	Hardware malfunction	When
EF 10		operating
E-20	AT or 'AT on startup' has not been completed even if approx. 4 hours	When AT or
	have elapsed since AT or 'AT on startup' started.	'AT on startup'
	For 'AT on startup', PV slope and delay time cannot be measured	
	normally for P, I, D calculation.	

^(*) Indicates when Enabled is selected in [Error indication Enabled/Disabled].

13.2 Run Mode

Character	Indicated Item Name
oFF	Control output OFF
25	Manual control
□ /Q5	(MV flashes.)

13.3 Monitor Mode

The PV Display indicates PV, and the SV Display indicates setting item value.

Character	Indicated Item Name
25	MV
[MV]	(Decimal point flashes.)
25	Remaining time (When Program control is performing)
[Remaining time]	
25	Current step number (When Program control is performing) (BCS2)
[Step number]	ト/- / to ト/- 日
25	SV number (BCS2)
[Memory number]	<i>〜& 1</i> □ to <i>〜&Ч</i> □

13.4 Initial Setting Mode

The PV Display (upper row) indicates setting characters, and the SV Display (lower row) indicates

factory default value.

Characters,								
Factory Default	Setting Item, Setting Range							
5E05	Input type							
EΠΕ	E	K -200 to 1370°C	EF	K -328 to 2498°F				
	E□ .C	K -200.0 to 400.0℃	E□ .F	K -328.0 to 752.0°F				
	ع الله	J -200 to 1000℃	J	J -328 to 1832°F				
	- III [R 0 to 1760°C	r F	R 32 to 3200°F				
	<u> </u>	S 0 to 1760°C	5 F	S 32 to 3200°F				
	ЬШС	B 0 to 1820℃	Ь∭Е	B 32 to 3308°F				
	ΕΙΙΙΕ	E -200 to 800°C	EIIF	E -328 to 1472°F				
	Γ□ .Ε	T -200.0 to 400.0℃	Γ□ .F	T -328.0 to 752.0°F				
	$ ag{1} $	N -200 to 1300°C	n F	N -328 to 2372°F				
	PL20							
	□□□□□□□□□□□□□□□□□□□□□□□□□□□□□□□□□□□□□							
	<i>Pl</i> .							
	JPT.E							
	PTE	Pt100 -200 to 850°C	Pt100 -328 to 1562°F					
	JPFE	JPt100 -200 to 500°C	JPFF	JPt100 -328 to 932°F				
	420R	4 to 20 mA DC -2000 to 10000						
	020R	0 to 20 mA DC -2000 to 10000						
	0 IB	G 58 0 to 5 V DC -2000 to 10000						
	05 <i>8</i>							
	/□58	1 to 5 V DC -2000 to 10000						
	0 108	0 to 10 V DC -2000 to 10000						
4FLH	Scaling high							
1370	Setting ra	ange: Scaling low limit value to in	. •	•				
. ~		DC voltage, current inputs	: -2000 to	10000 (*1)				
45LL	Scaling lov							
-200	Setting range: Input range low limit value to scaling high limit value							
17::	.	DC voltage, current inputs:	: -2000 to	10000 (*1)				
dP	Decimal po	•						
		No decimal point						
	0.00	1 digit after decimal point						
		2 digits after decimal point						
	QQQQ 3 digits after decimal point							

^(*1) The placement of the decimal point follows the selection.

Event output EV1 allocation [Event Output Allocation Table]
[Event Output Allocation Table] ODD No event ODD Alarm output, High limit alarm ODD Alarm output, Low limit alarm ODD Alarm output, High/Low limits alarm ODD Alarm output, High/Low limits independent alarm ODD Alarm output, High/Low limit range alarm ODD Alarm output, High/Low limit range independent alarm ODD Alarm output, Process high alarm ODD Alarm output, Process low alarm ODD Alarm output, High limit with standby alarm ODD Alarm output, Low limit with standby alarm ODD Alarm output, High/Low limits with standby alarm ODD Alarm output, High/Low limits with standby independent alarm ODD Alarm output, High/Low limits with standby independent alarm ODD Alarm output, High/Low limits with standby independent alarm ODD Alarm output, High/Low limits with standby independent alarm ODD Alarm output, High/Low limits with standby independent alarm
No event OO I Alarm output, High limit alarm OOO Alarm output, Low limit alarm OOO Alarm output, High/Low limits alarm OOO Alarm output, High/Low limits independent alarm OOO Alarm output, High/Low limit range alarm OOO Alarm output, High/Low limit range independent alarm OOO Alarm output, Process high alarm OOO Alarm output, Process low alarm OOO Alarm output, High limit with standby alarm OOO IO Alarm output, Low limit with standby alarm OOI Alarm output, High/Low limits with standby alarm OOI Alarm output, High/Low limits with standby independent alarm OOI Heater burnout alarm output OOI Heater burnout alarm output
Alarm output, High limit alarm Alarm output, Low limit alarm Alarm output, High/Low limits alarm Alarm output, High/Low limits independent alarm Alarm output, High/Low limit range alarm Alarm output, High/Low limit range independent alarm Alarm output, Process high alarm Alarm output, Process low alarm Alarm output, High limit with standby alarm Alarm output, Low limit with standby alarm Alarm output, High/Low limits with standby alarm Alarm output, High/Low limits with standby alarm Alarm output, High/Low limits with standby independent alarm Alarm output, High/Low limits with standby independent alarm Alarm output alarm output C 13 Heater burnout alarm output
Alarm output, Low limit alarm OO3 Alarm output, High/Low limits alarm OO5 Alarm output, High/Low limit range alarm OO5 Alarm output, High/Low limit range independent alarm Alarm output, High/Low limit range independent alarm OO7 Alarm output, Process high alarm OO8 Alarm output, Process low alarm OO9 Alarm output, High limit with standby alarm OO1 Alarm output, Low limit with standby alarm OO1 Alarm output, High/Low limits with standby alarm OO1 Alarm output, High/Low limits with standby independent alarm OO1 Heater burnout alarm output OO1 Loop break alarm output
Alarm output, High/Low limits alarm COS Alarm output, High/Low limit independent alarm Alarm output, High/Low limit range alarm Alarm output, High/Low limit range independent alarm Alarm output, Process high alarm Alarm output, Process low alarm Alarm output, High limit with standby alarm Alarm output, Low limit with standby alarm Alarm output, High/Low limits with standby alarm Alarm output, High/Low limits with standby independent alarm Alarm output, High/Low limits with standby independent alarm Alarm output alarm output Alarm output alarm output Alarm output Alarm output Alarm output Alarm output Alarm output
Alarm output, High/Low limits independent alarm Alarm output, High/Low limit range alarm Alarm output, High/Low limit range independent alarm Alarm output, Process high alarm Alarm output, Process low alarm Alarm output, High limit with standby alarm Alarm output, Low limit with standby alarm Alarm output, High/Low limits with standby alarm Alarm output, High/Low limits with standby independent alarm Blarm Blarm output, High/Low limits with standby independent alarm Blarm output alarm output Coll Heater burnout alarm output
Alarm output, High/Low limit range alarm Alarm output, High/Low limit range independent alarm Alarm output, Process high alarm Alarm output, Process low alarm Alarm output, High limit with standby alarm Alarm output, Low limit with standby alarm Alarm output, High/Low limits with standby alarm Alarm output, High/Low limits with standby independent alarm Alarm output, High/Low limits with standby independent alarm Alarm output alarm output Alarm output alarm output DIS IS Heater burnout alarm output
Alarm output, High/Low limit range independent alarm Alarm output, Process high alarm BBB Alarm output, Process low alarm BBB Alarm output, High limit with standby alarm BBB Alarm output, Low limit with standby alarm BBB Alarm output, High/Low limits with standby alarm BBB Alarm output, High/Low limits with standby alarm BBB Alarm output, High/Low limits with standby independent alarm BBB Alarm output, High/Low limits with standby independent alarm BBB Alarm output, High/Low limits with standby independent alarm BBB Alarm output, High/Low limits with standby independent alarm BBB Alarm output, High/Low limits with standby independent alarm
Alarm output, Process high alarm BBB Alarm output, Process low alarm BBB Alarm output, High limit with standby alarm BBB Alarm output, Low limit with standby alarm BBB Alarm output, High/Low limits with standby alarm BBB Alarm output, High/Low limits with standby independent alarm BBB Alarm output, High/Low limits with standby independent alarm BBB Alarm output, High/Low limits with standby independent alarm BBB Alarm output, High/Low limits with standby independent alarm
Alarm output, Process low alarm BBB Alarm output, High limit with standby alarm BBB Alarm output, Low limit with standby alarm BBB IB Alarm output, Low limits with standby alarm BBB IB Alarm output, High/Low limits with standby alarm BBB IB Alarm output, High/Low limits with standby independent alarm BBB IB Heater burnout alarm output BBB IB Loop break alarm output
Alarm output, High limit with standby alarm Alarm output, Low limit with standby alarm Alarm output, High/Low limits with standby alarm Alarm output, High/Low limits with standby independent alarm BIS 13 Heater burnout alarm output BIS 14 Loop break alarm output
Alarm output, Low limit with standby alarm Alarm output, High/Low limits with standby alarm Alarm output, High/Low limits with standby independent alarm BIS 13 Heater burnout alarm output BIS 14 Loop break alarm output
Alarm output, High/Low limits with standby alarm Alarm output, High/Low limits with standby independent alarm Bild Heater burnout alarm output Bild Loop break alarm output
Alarm output, High/Low limits with standby independent alarm I I Heater burnout alarm output I Loop break alarm output
alarm □□ I∃ Heater burnout alarm output □□ IH Loop break alarm output
☐☐ / ☐ Heater burnout alarm output ☐☐ / ☐ Loop break alarm output
☐☐ 1'H Loop break alarm output
☐☐ 15 Time signal output
□□ 15 Output during AT
□□ 17 Pattern end output
□□ 18 Output by communication command
8 158 EV1 alarm value 0 Enabled/Disabled
no Disabled
サビ Enabled
R I EV1 alarm value
High limit alarm -(Input span) to Input span °C (°F) (*1) (*2)
Low limit alarm -(Input span) to Input span °C (°F) (*1) (*2)
High/Low limits alarm 0 to Input span °C (°F) (*1) (*2)
High/Low limits independent 0 to Input span °C (°F) (*1) (*2)
alarm
High/Low limit range alarm 0 to Input span °C (°F) (*1) (*2)
High/Low limit range 0 to Input span °C (°F) (*1) (*2)
independent alarm
Process high alarm Input range low limit to Input range high limit (*1) (
Process low alarm Input range low limit to Input range high limit (*1) (
High limit with standby alarm
Low limit with standby alarm -(Input span) to Input span °C (°F) (*1) (*2)
High/Low limits with standby 0 to Input span °C (°F) (*1) (*2)
alarm
High/Low limits with standby 0 to Input span °C (°F) (*1) (*2)
independent alarm
EV1 high limit alarm value Setting range: Same as those of EV1 alarm value

^(*1) The placement of the decimal point follows the selection.

 $^{(\}ensuremath{^{\star}}\xspace2)$ For DC voltage, current inputs, the input span is the same as the scaling span.

^(*3) For DC voltage, current inputs, input range low (or high) limit value is the same as scaling low (or high) limit value.

Characters, Factory Default	Setting Item, Setting Range				
A IHA	EV1 alarm hysteresis				
□□ tØ	Setting range: 0.1 to 1000.0°C(°F),				
5	DC voltage, current inputs: 1 to 10000 (*1)				
8 197	EV1 alarm delay time				
	Setting range: 0 to 10000 seconds				
A ILĀ	EV1 alarm Energized/De-energized				
noñL	FUL De granding de				
5. u	¬E出っ De-energized				
[5 15	TS1 output step number				
<u> </u>	Setting range: 1 to 9				
Γ' 1F	TS1 OFF time				
0000	Setting range: 00:00 to 99:59 (*4)				
[TS1 ON time				
0000	Setting range: 00:00 to 99:59 (*4)				
28o2	Event output EV2 allocation				
□ <i>000</i>	[Event Output Allocation Table]				
	DDD No event				
	Alarm output, High limit alarm				
	Alarm output, Low limit alarm				
	Alarm output, High/Low limits alarm				
	Alarm output, High/Low limits independent alarm DD5 Alarm output, High/Low limit range alarm				
	Alarm output, High/Low limit range independent alarm DD7 Alarm output, Process high alarm				
	Alarm output, High/Low limits with standby alarm				
	alarm				
	☐☐ 1∃ Heater burnout alarm output				
	☐☐ 14 Loop break alarm output				
	☐Ø 15 Time signal output				
	□□ 15 Output during AT				
	□□□ 17 Pattern end output				
	☐☐ IB Output by communication command				
	☐☐ 19 Heating/Cooling control relay contact output				
8538	EV2 alarm value 0 Enabled/Disabled				
00	Disabled				
	<i>当</i> E 与□ Enabled				

^(*1) The placement of the decimal point follows the selection.

^(*4) Time unit follows the selection in [Step time unit].

Characters,	Sotting them Sotting Dange				
Factory Default	Setting Item, Setting Range				
R2[[[]	EV2 alarm value				
	High limit alarm	-(Input span) to Input span °C (°F) (*1) (*2)			
	Low limit alarm	-(Input span) to Input span °C (°F) (*1) (*2)			
	High/Low limits alarm	0 to Input span °C (°F) (*1) (*2)			
	High/Low limits independent	0 to Input span °C (°F) (*1) (*2)			
	alarm				
	High/Low limit range alarm	0 to Input span °C (°F) (*1) (*2)			
	High/Low limit range	0 to Input span °C (°F) (*1) (*2)			
	independent alarm				
	Process high alarm	Input range low limit to Input range high limit (*1) (*3)			
	Process low alarm	Input range low limit to Input range high limit (*1) (*3)			
	High limit with standby alarm	-(Input span) to Input span °C (°F) (*1) (*2)			
	Low limit with standby alarm	-(Input span) to Input span °C (°F) (*1) (*2)			
	High/Low limits with standby	0 to Input span °C (°F) (*1) (*2)			
	alarm				
	High/Low limits with standby	0 to Input span °C (°F) (*1) (*2)			
	independent alarm				
R2H	EV2 high limit alarm value				
	Setting range: Same as those of EV2 alarm value				
RSH3	EV2 alarm hysteresis				
UU ίŪ	Setting range: 0.1 to 1000.0℃ (°F),				
		current inputs: 1 to 10000 (*1)			
859A	EV2 alarm delay time				
	Setting range: 0 to 10000 s				
R2LA	EV2 alarm Energized/De-ene	rgized			
noñL	nonL Energized				
	ー E 出っ De-energized				
[42 h	TS2 output step number				
1	Setting range: 1 to 9				
F-12F	TS2 OFF time				
0000	Setting range: 00:00 to 99:	59 (*4)			
[520	TS2 ON time				
0000	Setting range: 00:00 to 99:				
H (Heater burnout alarm 1 valu	Ie			
	Setting range:				
H I and CT1 current	20 A: 0.0 to 20.0 A				
value are alternately indicated on the PV	100 A: 0.0 to 100.0 A				
Display.					
H2	Heater burnout alarm 2 valu	ie			
	Setting range:				
H₽ and CT2 current	20 A: 0.0 to 20.0 A				
value are alternately indicated on the PV	100 A: 0.0 to 100.0 A				
Display.	decimal point follows the coloction				

^(*1) The placement of the decimal point follows the selection.

^(*2) For DC voltage, current inputs, the input span is the same as the scaling span.

^(*3) For DC voltage, current inputs, input range low (or high) limit value is the same as scaling low (or high) limit value.

^(*4) Time unit follows the selection in [Step time unit].

Factory Default	Setting Item, Setting Range						
LP_F	Loon brea	Loop break alarm time					
	Setting range: 0 to 200 minutes						
LP_H	Loop break alarm span						
	Setting range: 0 to 150° C (°F), or 0.0 to 150.0° C (°F)						
	DC voltage, current inputs: 0 to 1500 (*1)						
EBI I	Event input DI1 allocation						
000	[Event Input Allocation Table]						
	-	Event input Input ON Input OFF					
		function	(Closed)	(Open)			
	000	No event					
	00 i	Set value memory					
	002	Control ON/OFF	Control OFF	Control ON			
	003	Direct/Reverse action	Direct action	Reverse action			
	□004	Preset output 1 ON/OFF	Preset output	Usual control			
	005	Preset output 2 ON/OFF	Preset output	Usual control			
	006	Auto/Manual control	Manual	Automatic			
		Remote/Local	control	control			
	008		Remote RUN	Local STOP			
		Program control RUN/STOP	RUN	510P			
	□009	Program control Holding/Not holding	Holding	Not holding			
	□0 10	Program control	Advance	Usual control			
		Advance function	function				
		Integral action	Integral action	Usual			
		Holding	Holding	integral action			
E81 2	-	it DI2 allocation					
		item: Same as those of	Event input DI1 a	allocation			
FFLH		etting input high limit					
1370		ange: External setting inp	out low limit to Inp	out range high limit (*1)			
-511		etting input low limit	74 . E 4	e			
-200		ange: Input range low lim	iit to External set	ting input high limit (*1)			
roh Dumm		ion output type					
PB	PB	PV transmission					
	58 <u></u>	SV transmission					
	⊼≝ MV transmission						
(+4) Ti	d8	DV transmission					
(*1) The placement of the	ne decimal point i	follows the selection.					

^(*1) The placement of the decimal point follows the selection.

Characters,

Characters, Factory Default	Setting Item, Setting Range					
Γ r LH	Transmission output high limit					
1370	PV, SV transmission	SV transmission Transmission output low limit to Input range high limit				
	DC voltage, currents: -2000 to 10000					
	MV transmission Transmission output low limit to 105.0%					
	DV transmission					
Γ – L L	Transmission output low limit					
-200	PV, SV transmission Input range low limit to Transmission output high limit					
	DC voltage, currents: -2000 to 10000					
	MV transmission -5.0% to Transmission output high limit value					
	DV transmission -Scaling span to Transmission output high limit value (*					
4	SV1					
	Setting range: Scaling	Setting range: Scaling low limit to Scaling high limit (*1)				
5 <u>2</u>	SV2					
$\square \square \mathcal{G}$	Setting range: Scaling low limit to Scaling high limit (*1)					
5∃ <u></u>	SV3					
$\Box\Box\Box$	Setting range: Scaling low limit to Scaling high limit (*1)					
54	SV4					
	Setting range: Scaling low limit to Scaling high limit (*1)					

^(*1) The placement of the decimal point follows the selection.

13.5 Main Setting Mode

Characters,			
Factory Default	Setting Item, Setting Range		
4	SV1		
$\square\square\square G$	Setting range: Scaling low limit to Scaling high limit (*1)		
Γ 1	Step 1 time		
0000	Setting range: [=]=[=], or 00:00 to 99:59		
ŭL !	Step 1 wait value		
	Setting range: 0 to 20% of input span		
	DC voltage, current inputs: 0 to 20% of scaling span (*1)		
5 <u>2</u>	SV2		
	Setting range: Scaling low limit to Scaling high limit (*1)		
<i>「</i> □_ <i>?</i>	Step 2 time		
0000	Setting range: Elelele, or 00:00 to 99:59		
<i>5</i> □_ <i>2</i>	Step 2 wait value		
	Setting range: 0 to 20% of input span		
	DC voltage, current inputs: 0 to 20% of scaling span (*1)		
<i>5∃</i> □□	SV3		
	Setting range: Scaling low limit to Scaling high limit (*1)		
Γ□_ ∃	Step 3 time		
0000	Setting range: [=]=]=, or 00:00 to 99:59		
J□_ 3	Step 3 wait value		
	Setting range: 0 to 20% of input span		
	DC voltage, current inputs: 0 to 20% of scaling span (*1)		
44	SV4		
	Setting range: Scaling low limit to Scaling high limit (*1)		
Γ <u></u> _4	Step 4 time		
0000	Setting range: Settin		
<u> </u>	Step 4 wait value		
	Setting range: 0 to 20% of input span		
	DC voltage, current inputs: 0 to 20% of scaling span (*1)		
45 T	Step 5 SV		
	Setting range: Scaling low limit to Scaling high limit (*1)		
Γ <u></u> 5	Step 5 time		
0000	Setting range: [][][], or 00:00 to 99:59		
<u> </u>	Step 5 wait value		
	Setting range: 0 to 20% of input span		
, /=mm	DC voltage, current inputs: 0 to 20% of scaling span (*1)		
\ <u> \6</u>	Step 6 SV		
	Setting range: Scaling low limit to Scaling high limit (*1)		
Γ□_5 0000	Step 6 time		
0000	Setting range: First, or 00:00 to 99:59		
J□_	Step 6 wait value		
iiii /	Setting range: 0 to 20% of input span		
	DC voltage, current inputs: 0 to 20% of scaling span (*1)		

^(*1) The placement of the decimal point follows the selection.

Characters, Factory Default	Setting Item, Setting Range				
5 7 T	Step 7 SV				
$\Box \Box \Box \Box$	Setting range: Scaling low limit to Scaling high limit (*1)				
Γ. 7	Step 7 time				
00.00	Setting range:, or 00:00 to 99:59				
<u>J</u> □_ 7	Step 7 wait value				
	Setting range: 0 to 20% of input span				
	DC voltage, current inputs: 0 to 20% of scaling span (*1)				
<i>∖8</i> □□	Step 8 SV				
	Setting range: Scaling low limit to Scaling high limit (*1)				
Γ□_8	Step 8 time				
00.00	Setting range: [=i=i=i], or 00:00 to 99:59				
J□_8	Step 8 wait value				
	Setting range: 0 to 20% of input span				
	DC voltage, current inputs: 0 to 20% of scaling span (*1)				
<i>59</i> □□	Step 9 SV				
	Setting range: Scaling low limit to Scaling high limit (*1)				
r□_s	Step 9 time				
00.00	Setting range: [
J□_9	Step 9 wait value				
	Setting range: 0 to 20% of input span				
	DC voltage, current inputs: 0 to 20% of scaling span (*1)				

 $^{(\}ensuremath{^{\star}}\xspace1)$ The placement of the decimal point follows the selection.

13.6 Sub Setting Mode

factory default value	e			
Characters, Factory Default	Setting Item, Setting Range			
RI Delault	AT/Auto-reset Perform/Cancel			
	AT/Auto-reset Perform/Cancer AT/AT on startup/Auto-reset Cancel			
1	85 AT Perform			
	用により AT on startup Perform			
	- SET Auto-reset Perform			
PITTI	OUT1 proportional band			
10	Thermocouple, RTD input without decimal point: 0 to Input span °C(°F)			
	Thermocouple, RTD input with decimal point: 0.0 to Input span °C(°F) ⊂			
, ,	DC voltage, current inputs: 0.0 to 1000.0%			
/	Integral time			
	Setting range: 0 to 3600 seconds			
d	Derivative time			
50	Setting range: 0 to 1800 seconds			
Arū□ □□=n	ARW			
<u> </u>	Setting range: 0 to 100%			
- 48F	Manual reset			
ε I I I	Setting range: ±Proportional band value			
30	OUT1 proportional cycle			
ii2U	Setting range: 0.5, or 1 to 120 seconds Factory default value:			
	Relay contact output: 30 sec			
	Non-contact voltage output: 3 sec			
HY5	OUT1 ON/OFF hysteresis			
ι ι σ	Setting range: 0.1 to 1000.0°C (°F) DC voltage, current inputs: 1 to 10000 (*1)			
oL H	OUT1 high limit			
00,,00	Setting range: OUT1 low limit value to 100%			
	(Direct current output type: OUT1 low limit value to 105%)			
oLL	OUT1 low limit			
	Setting range: 0% to OUT1 high limit value			
	(Direct current output type: -5% to OUT1 high limit value)			
or Af	OUT1 rate-of-change			
	Setting range: 0 to 100 %/second			
cRcF	OUT2 cooling method			
A: r□	Air cooling (linear characteristics)			
	Oil cooling (1.5th power of the linear characteristics)			
	₩ater cooling (2nd power of the linear characteristics)			
P_6[]	OUT2 proportional band			
□□ <i>IB</i>	Thermocouple, RTD input without decimal point: 0 to Input span°C (°F)			
	Thermocouple, RTD input with decimal point: 0.0 to Input span°C (°F) DC voltage, current inputs: 0.0 to 1000.0%			
c_b	OUT2 proportional cycle			
30	Setting range: 0.5, or 1 to 120 seconds			
	Factory default value:			
	• EV2(*2), EV2+DR: 30 sec			
HYS5	• DS, EV2+DS: 3 sec OUT2 ON/OFF hysteresis			
	Setting range: 0.1 to 1000.0° C (°F),			
	DC voltage, current inputs: 1 to 10000 (*1)			
(±4) =1				

^(*1) The placement of the decimal point follows the selection.
(*2) When EV2 is selected { (Heating/Cooling control relay contact output) is selected in [Event output EV2 allocation]}.

Characters, Factory Default	Setting Item, Setting Range				
oL Hb	OUT2 high limit				
□ 100	Setting range: OUT2 low limit value to 100% (Direct current output type: OUT2 low limit value to 105%)				
oLLb	OUT2 low limit				
ii	Setting range: 0% to OUT2 high limit value (Direct current output type: -5% to OUT2 high limit value)				
db	Overlap/Dead band				
	Setting range: -200.0 to 200.	0℃ (°F),			
	DC voltage, current inputs: -	· /·			
conf	Direct/Reverse action				
HERF	HERF Reverse (Heatin	g) action			
	cook Direct (Cooling)	action			
<i>R (</i>	EV1 alarm value				
\square \square \square \square	High limit alarm	-(Input span) to Input span °C (°F) (*1) (*2)			
	Low limit alarm	-(Input span) to Input span °C (°F) (*1) (*2)			
	High/Low limits alarm	0 to Input span [°] C (°F) (*1) (*2)			
	High/Low limits independent	0 to Input span [°] C (°F) (*1) (*2)			
	High/Low limit range alarm	0 to Input span [°] C (°F) (*1) (*2)			
	High/Low limit range	0 to Input span [°] C (°F) (*1) (*2)			
	independent alarm				
	Process high alarm Process low alarm	Input range low limit to Input range high limit (*1) (*3)			
		Input range low limit to Input range high limit (*1) (*3)			
	High limit with standby alarm	-(Input span) to Input span °C (°F) (*1) (*2) -(Input span) to Input span °C (°F) (*1) (*2)			
	Low limit with standby alarm High/Low limits with standby	0 to Input span °C (°F) (*1) (*2)			
	High/Low limits with standby	0 to Input span °C (°F) (*1) (*2)			
	independent alarm				
A IH	EV1 high limit alarm value				
	Setting range: Same as those of EV1 alarm value				
<i>R2</i>	EV2 alarm value				
	Setting range: Same as those of EV1 alarm value				
<i>R2H</i> □ □ □ □ 0	EV2 high limit alarm value Setting range: Same as those of EV1 alarm value				
H I	Heater burnout alarm 1 valu				
		e			
	Setting range: 20.0 A: 0.0 to 20.0 A				
H I and CT1 current value are alternately indicated on the PV Display.	100.0 A: 0.0 to 100.0 A				
H2	Heater burnout alarm 2 valu	e			
	Setting range:				
H₽ and CT2 current	20.0 A: 0.0 to 20.0 A				
value are alternately indicated on the PV Display.	100.0 A: 0.0 to 100.0 A				
LP_F	Loop break alarm time				
	Setting range: 0 to 200 minu	utes			
LP_H	Loop break alarm span	the south de since I as since O to 450°C (°C)			
		thout decimal point: 0 to 150° C (°F) the decimal point: 0.0 to 150.0° C (°F)			
	DC voltage, current inputs: (
	decimal point follows the selection				

^(*1) The placement of the decimal point follows the selection.
(*2) For DC voltage, current inputs, the input span is the same as the scaling span.
(*3) For DC voltage, current inputs, input range low (or high) limit value is the same as scaling low (or high) limit value.

13.7 Engineering Mode 1

Characters,	Setting Item, Setting Range						
Factory Default	Set value lock						
	Set valu	ie lock	Change via Keypad			Change via Software Communication	
	[-]-]-]	Unlock	All set values can be changed.			All set values can be	
	Loci	Lock 1	None of the set values can be		changed.		
			changed.	changed.			
	Loc2	Lock 2	In Fixed value control, only SV				
				llue can be chang	ged.		
				ontrol, Step SV,			
			·	d Alarm value car	า		
	, –,		be changed.				
	Loc3	Lock 3		can be changed		1	ns – except Input
	Loc4	Lock 4		set values can be		type, Controller/Converter – can be changed temporarily	
	Locs	Lock 5	changed.	e control, only S\	,		communication.
		LUCK 3		llue can be chang			power is turned
				ontrol, Step SV,	jcu.	ON again, the set values revert to the values before	
				d Alarm value car	า		
			be changed.			Lock 3, 4 or 5 was selected	
EBI I	Event input DI1 allocation						
□000	[Event Input Allocation Table]						
		E	ent input	Input ON	ı	nput OFF	
			function	(Closed)		(Open)	
			alue memory	0			
			ol ON/OFF	Control OFF		ontrol ON	
			t/Reverse	Direct		everse	
	actio		et output 1	action Preset output	1	tion sual control	
		ON/C	•	Freset output	US	dai controi	
	009	Prese	et output 2	Preset output	Us	sual control	
	008		Manual	Manual	Au	tomatic	
		contro	ol	control	со	ntrol	
	00	Remo	ote/Local	Remote	Lo	cal	
	□ <i>008</i>		ram control	RUN ST		OP	
	009		ram control ng/Not ng	Holding	No	ot holding	
	□ <i>0 10</i>	Progr	am control	Advance	Us	ual control	
			nce function	function			
			ral action	Integral action		sual	
		holdir	ng	holding	integral action		

Characters, Factory Default		Set	ting Item, Setting Range	
EBI 2	Event input DI2 allocation			
000	Selection item: Same as Event input DI1 allocation			
E80 !	Event output EV1 allocation			
000	-	[Event Output Allocation Table]		
	000	No event		
	00 I	Alarm output, Hig	th limit alarm	
	002	Alarm output, Lov		
	003	•	h/Low limits alarm	
	004	·	h/Low limits independent alarm	
	005	Alarm output, Hig	h/Low limit range alarm	
	008		h/Low limit range independent alarm	
	007	Alarm output, Pro		
	008	Alarm output, Pro	ocess low alarm	
	009	Alarm output, Hig	gh limit with standby alarm	
	0 10	Alarm output, Low limit with standby alarm		
		Alarm output, High/Low limits with standby alarm		
	□ <i>0 12</i>	Alarm output, High/Low limits with standby independent alarm		
	O 13	Heater burnout alarm output		
	□ <i>0 1</i> 4	Loop break alarm output		
	O 15	Time signal outpu	ut	
	□ <i>0 1</i> 6	Output during AT		
	□ <i>0</i> 17	Pattern end outpo	ut	
	O 18	Output by communication command		
RIER	EV1 alarm value 0 Enabled/D		Disabled	
no	00	Disabled		
	4E 4	Enabled		
R I	EV1 alarm value			
	High limit alarm		-(Input span) to Input span [°] C (°F) (*1) (*	2)
	Low limit al	arm	-(Input span) to Input span °C (°F) (*1) (*	2)
	High/Low li		0 to Input span °C (°F) (*1) (*2)	
	High/Low li alarm	mits independent	0 to Input span °C (°F) (*1) (*2)	
	High/Low li	mit range alarm	0 to Input span °C (°F) (*1) (*2)	
	High/Low li	mit range	0 to Input span [°] C (°F) (*1) (*2)	
	independent alarm Process high alarm Process low alarm High limit with standby alarm Low limit with standby alarm High/Low limits with standby alarm			
			Input range low limit to Input range hig	h limit (*1) (*3)
			Input range low limit to Input range hig	h limit (*1) (*3)
			-(Input span) to Input span $^{\circ}\mathbb{C}$ ($^{\circ}\mathbb{F}$) (*1) (*	2)
			-(Input span) to Input span °C (°F) (*1) (*	2)
			0 to Input span °C (°F) (*1) (*2)	
			0 to Input span °C (°F) (*1) (*2)	
	independer			
A IH□		imit alarm value	<u> </u>	
	_		se of EV1 alarm value	
t	_ Journal 10	21.90. Juino ao ino	SS S. E.V. I GIGITII VAIGO	

^(*1) The placement of the decimal point follows the selection.

^(*2) For DC voltage, current inputs, the input span is the same as the scaling span.
(*3) For DC voltage, current inputs, input range low (or high) limit value is the same as scaling low (or high) limit value.

Characters, Factory Default	Setting Item, Setting Range			
ล เหร	EV1 alarm hysteresis			
□□ <i>ŧ□</i>	Setting range: 0.1 to 1000.0°C (°F),			
	DC voltage, current inputs: 1 to 10000 (*1)			
8 192	EV1 alarm delay time			
	Setting ra	ange: 0 to 10000 seconds		
RILĀ		Energized/De-energized		
noñL	noñL	Energized		
	rE85	De-energized		
[5]5		step number		
1	_	ange: 1 to 9		
rs if	TS1 OFF ti			
0000		ange: 00:00 to 99:59 (*2)		
54 lo	TS1 ON tin			
0000	_	ange: 00:00 to 99:59 (*2)		
E805	_	ut EV2 allocation		
		utput Allocation Table]	-	
	000	No event		
		Alarm output, High limit alarm		
		Alarm output, Low limit alarm		
	003	Alarm output, High/Low limits alarm		
	<u> </u>	Alarm output, High/Low limits independent alarm		
	005	Alarm output, High/Low limit range alarm		
	006	Alarm output, High/Low limit range independent alarm		
	007	Alarm output, Process high alarm		
	008	Alarm output, Process low alarm		
	009	Alarm output, High limit with standby alarm		
	□ <i>0 10</i>	Alarm output, Low limit with standby alarm		
		Alarm output, High/Low limits with standby alarm		
	□0 12	Alarm output, High/Low limits with standby independent alarm		
	□ <i>0 13</i>	Heater burnout alarm output		
	□0 1Y	Loop break alarm output		
	0 15	Time signal output		
	□ <i>0 1</i> 6	Output during AT		
	□ <i>0</i> /7	Pattern end output		
	□0 <i>18</i>	Output by communication command		
	O 19	Heating/Cooling control relay contact output		
R2ER	EV2 alarm	value 0 Enabled/Disabled		
no	no	Disabled		
	4E 5	Enabled		

^(*1) The placement of the decimal point follows the selection. (*2) Time unit follows the selection in [Step time unit].

Characters, Factory Default	Setting Item, Setting Range		
82	EV2 alarm value		
	High limit alarm	-(Input span) to Input span °C (°F) (*1) (*2)	
	Low limit alarm	-(Input span) to Input span °C (°F) (*1) (*2)	
	High/Low limits alarm	0 to Input span °C (°F) (*1) (*2)	
	High/Low limits independent alarm	0 to Input span °C (°F) (*1) (*2)	
	High/Low limit range alarm	0 to Input span °C (°F) (*1) (*2)	
	High/Low limit range independent alarm	0 to Input span °C (°F) (*1) (*2)	
	Process high alarm	Input range low limit to Input range high limit (*1) (*3)	
	Process low alarm	Input range low limit to Input range high limit (*1) (*3)	
	High limit with standby alarm	-(Input span) to Input span [°] C (°F) (*1) (*2)	
	Low limit with standby alarm	-(Input span) to Input span ℃ (˚F) (*1) (*2)	
	High/Low limits with standby alarm	0 to Input span °C (°F) (*1) (*2)	
	High/Low limits with standby independent alarm	0 to Input span °C (°F) (*1) (*2)	
82H_	EV2 high limit alarm value		
	Setting range: Same as those	se of EV2 alarm value	
BSHA	EV2 alarm hysteresis	0.00	
□□□ tØ	Setting range: 0.1 to 1000.0°C (°F), DC voltage, current inputs: 1 to 10000 (*1)		
8593	EV2 alarm delay time		
	Setting range: 0 to 10000 se	econds	
ASLA	EV2 alarm Energized/De-energized		
noñL	nañt Energized		
	ァモ岩ト De-energized		
[424	TS2 output step number		
<u> </u>	Setting range: 1 to 9		
[42F	TS2 OFF time		
00.00	Setting range: 00:00 to 99:59 (*4)		
	TS2 ON time		
5060 5060	Setting range: 00:00 to 99:59 (*4) Sensor correction coefficient		
1000	Setting range: -10.000 to 10.000		
50 II	Sensor correction		
	Setting range: -1000.0 to 10	000.0℃ (°F)	
	DC voltage, current inputs: -10000 to 10000 (*1)		
FILC □□ΩO	PV filter time constant Setting range: 0.0 to 10.0 seconds		
cñhL	Communication protocol		
noñL	Shinko protocol		
	ក់១៨ក Modbus ASCII		
	กัดฝ่า Modbus RTU		
		JC command allocated)	
	` ` ` ` ` ` ` ` ` ` ` ` ` ` ` `	C command allocated)	
	` _ `	command allocated)	
		January and Grand Grand	

^(*1) The placement of the decimal point follows the selection.

^(*2) For DC voltage, current inputs, the input span is the same as the scaling span.

(*3) For DC voltage, current inputs, input range low (or high) limit value is the same as scaling low (or high) limit value.

^(*4) Time unit follows the selection in [Step time unit].

Characters, Factory Default	Setting Item, Setting Range		
cñno	Instrument number		
	0 to 95		
cāhP	Communication speed		
35	1198	9600 bps	
	□ <i>192</i>	19200 bp	S
	384	38400 bp	S
cāff	Data bit/Pa	rity	
7885	8000	8 bits/No	parity
	7000	7 bits/No	parity
	8E8n	8 bits/Eve	en
	7885	7 bits/Eve	en
	8000	8 bits/Ode	d
	Todd	7 bits/Ode	d
cกัปโ	Stop bit		
1	1111111	1 bit	
		2 bits	
cñdy	Response delay time		
□□ <i>IB</i>	Setting ra	ange: 0 to 1	1000 ms
58 ₋ 6	SVTC bias		
	Setting range: ±20% of the input span DC voltage, current inputs: ±20% of scaling span (*1)		
rear	Remote/Local		
Lock	Lock	Local	
<i></i>	- 555	Remote	
-CLH 1370	External setting input high limit		
- FLL	Setting range: External setting input low limit to Input range high limit		
	External setting input low limit		
-200 -5-b	Setting range: Input range low limit to External setting input high limit		
	Remote bias Setting range: ±20% of input span DC voltage, current inputs: ±20% of scaling span (*1)		0/ of input anan
1i!!!			• •
500			
PB	Transmission output type PB PV transmission		
, <u>Q</u>	7.8	SV transr	
	⊼8	MV transi	
	48 III		
r-LH	db		
וֹם בּוֹם			ı
	PV, SV transmission		Transmission output low limit to 105.0%
	DV transmi		Transmission output low limit to Scaling span (*1)
r-LL	Transmiss		
-200	PV, SV tran	_	Input range low limit to Transmission output high limit value
	MV transmi		-5.0% to Transmission output high limit value
	DV transmi		-Scaling span to Transmission output high limit value (*1)
	עם וומווטוווו	331UH	-ocaming spair to Transmission output high limit value (*1)

^(*1) The placement of the decimal point follows the selection.

Characters, Factory Default	Setting Item, Setting Range			
ñ_50	Step time unit			
āl o	ก็ไ ก Hours:Minutes			
	与とこ Minutes:Seconds			
PrEF	Power restore action			
450P	与にゅう Stops after power is restored			
	Continues (resumes) after power is restored.			
	Hala Suspends (on hold) after power is restored.			
5_58	Program start temperature			
	Setting range: Scaling low limit value to Scaling high limit value (*1)			
5_51	Program control start type			
P8	PB PV start			
	P₩r□ PVR start			
	58 SV start			
-695	Number of repetitions			
	Setting range: 0 to 10000 times			
-855	SV Rise/Fall rate start type			
585F	ト 占っ 「 SV start			
	PB与「 PV start			
-REU	SV rise rate			
	Setting range: 0 to10000 °C/min (°F/min)			
	Thermocouple, RTD inputs with a decimal point: 0.0 to 1000.0 °C/min (°F/min)			
5.5	DC voltage, current inputs: 0 to 10000/min			
-ACd	SV fall rate Setting range: 0 to10000 °C/min (°F/min)			
	Thermocouple, RTD inputs with a decimal point: 0.0 to 1000.0 °C/min (°F/min)			
	DC voltage, current inputs: 0 to 10000/min			
P58	Indication when control output OFF			
off	□ FF OFF indication			
	RoFF No indication			
	PB PV indication			
	PBRL PV indication + Any Alarm active			
Ar_b	AT bias			
20	Setting range: 0 to 50℃ (0 to 100°F), or 0.0 to 50.0℃ (0.0 to 100.0°F)			
AC_E	AT gain			
UU UU	Setting range: 0.1 to 10.0 times			
EaUF	Output status when input errors occur			
off[□ FF Output OFF			
	Output ON			
ARAU	OUT/OFF key function			
off.	□ FF Control output OFF function			
	ลีลเปิ Auto/Manual control			
	Program control			
ñ8r5	Auto/Manual after power ON			
RUF ₀	Automatic control			
	_ คือเป_ Manual control			

^(*1) The placement of the decimal point follows the selection.

Characters, Factory Default		Setting Item, Setting Range			
ri ae	Indication time				
00.00	Setting range: 00:00 to 60:00 (Minutes:Seconds)				
	When se	When set to 00:00, Displays remain ON.			
P55 !	OUT1 MV preset value				
	Setting range: OUT1 low limit to OUT1 high limit				
	For Direct	t current output type, and when OUT1 is in ON/OFF control: OUT1 low			
	limit or OUT1 high limit				
	For Relay contact output or Non-contact voltage output type, and when OUT1 is				
	in ON/OFF control: 0.0% or 100.0%				
P552	OUT2 MV preset value				
$\Box\Box$ 00	Setting range: OUT2 low limit to OUT2 high limit				
	For DA, EV2+DA options, and when OUT2 is in ON/OFF control: OUT2 low limit or OUT2 high limit				
	For DR, DS, EV2+DR, EV2+DS options, and when OUT2 is in ON/OFF control:				
	0.0% or 100.0%				
FUnc	Controller/Converter function				
cn/r	colr	Controller			
	cn8f	Converter			
Ed! F	Error indication Enabled/Disabled				
no	no	Disabled			
	4E 4	Enabled			

13.8 Engineering Mode 2

taretery are raint rains			
Characters, Factory Default	Setting Item, Setting Range		
co5L	Control method		
noñL	noñL	PID control	
	26oF	2DOF PID control	
FPRH	Proportional gain 2DOF coefficient (α)		
<u> </u>	0.00 to 1.00		
F1 6F	Integral 2DOF coefficient (β)		
□ ₹35	0.00 to 1	0.00	

Inquiries *****

For any inquiries about this unit, please contact our agency or the vendor where you purchased the unit after checking the following.

	[Example]
• Model	BCS2R00-12
• Option	EV2, C5W (100A)
Serial number	No. 145F05000

In addition to the above, please let us know the details of the malfunction, or discrepancy, and the operating conditions.

